

The CRIRES Data Reduction Challenges

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> in utili · crires util combine:

· crires util extract:

Science observations images combination (nodding and jitter are handled)

• crires_util_vication: • crires_util_wicalib: Wavelength Calibration using a lamp, emission

lines or a gas cell and the proper catalogue

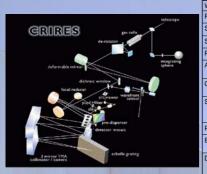
Science Observations

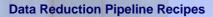
crires_util_combine

COMBINED_IMA CONTRIBUTION_IMA

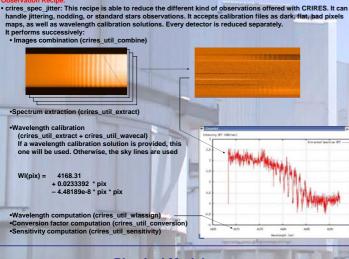
CRIRES Instrument Specificities

- CRIRES is CRyogenic high-resolution InfraRed Echelle Spectrogram
- CRIRES is located at the Nasmyth focus A of UT1 (Antu)
- CRIRES can boost all scientific applications aiming at fainter objects, higher spatial (extended sources), spectral and temporal resolution.
- Mosaic of four Aladdin III InSb arrays providing an effective 4096 x 512 focal plane detector array
- Adaptive Optics with MACAO

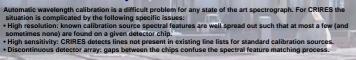




- Calibration Recipes: crires_spec_dark: Produces the dark calibration file crires_spec_flat: Produces the flat-field and the bad pixels map crires_spec_detectrans: Compute photometric transfer function for each detector crires_spec_wavecal: Compute the wavelength calibration with gas cells, lamps, or sky emission frames



Physical Model



These issues make the automatic elimination of false matches and obtaining a well defined fit for some CRIRES wavelength settings almost impossible using an empirical approach.

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As an alternative we have developed a physical model based	Section of simplified CRIRES ray trace
approach to CRIRES wavelength calibration:	showing possible tip
A simplified ray trace model describes the CRIRES	and tilts of the
dispersive optics.	pre-disperser prism
Spectral features are identified in a series of wavelength	
calibration exposures.	
The model parameters (tips and tilts of the critical	Statement of the local division of the local
components) are optimized so that the model reproduces	
the measured spectral feature locations (in 2D).	and e
· Science exposures are calibrated by setting the model	
prism and grating angles (which define the wavelength	
range) to match the header values and using the calibrated	
model to compute the 2D dispersion relation.	
Possible to optimize the prism and grating values using	R
contemporaneous calibration exposures (removing the	A
reliance upon header values).	D

- Combines data from many calibration exposures to produce a solution that is valid for the entire wavelength range. • Provides a 2D solution for the detector array • The model parameters have a physical basis, providing insight into the status of the instrument
- The modeling approach will be discussed in greater detail by Paul Bristow during the "Data Flow and Data Reduction Software" session.

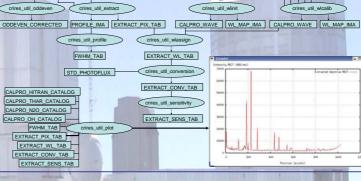


0.95 – 5.2 microns
100,000
0.2 – 1 arcsec
40 arcsec
0.086 arcsec
60 actuators curvature sensing system
Integrating sphere / line lamps
Aladdin array, J, H, K and 2 neutral density H filters, 0.045 arcsec/pixel
ZnSe prism
40x20 cm, 31.6 lines/mm, 63.5 deg. blaze
4096x512 pixels using 4 Aladdin arrays, with inter- detector gaps of 283 pixels

mary header	 Usual FITS mandatory keywords 	Basic
	•WCS keywords	•FI1
	 Observation related keywords 	•4 e
	 Template related keywords 	•32
	Data Classification keywords	•8.4
	•Various information about the carriage, the field selector, the filters, the de-rotator, the lamps, etc	•Ab
mary data unit	EMPTY	The data a
tension 1 header	 Usual FITS mandatory keywords 	Data Class
	HIERARCH ESO DET CHIP NO = 1	DPR.TECH
	HIERARCH ESO DET CHIP NX = 1024	
	HIERARCH ESO DET CHIP NY = 1024	These key
	HIERARCH ESO DET CHIP X = 1	CRIRES fi
	HIERARCH ESO DET CHIP Y = 1	observatio
	HIERARCH ESO DET WIN NX = 512	obtained v
	HIERARCH ESO DET WIN NY = 1024	obtained
tension 1 data unit		The system keywords
tension 2 header	HIERARCH ESO DET CHIP NO = 2	in order to
	HIERARCH ESO DET CHIP X = 2	
tension 2 data unit		Example:
tension 3 header	HIERARCH ESO DET CHIP NO = 3	HIERARCI
lension 5 header	HIERARCH ESO DET CHIP NO = 3	HIERARCI
tension 3 data unit	THERAKOT ESO DET CHIF X = 5	HIERARCI
tension 5 data unit		Define a C
		needs to b
tension 4 header	HIERARCH ESO DET CHIP NO = 4	crires_spe
	HIERARCH ESO DET CHIP X = 4	between t
tension 4 data unit		defined in

CRIRES Data

TS compliant ICB compliant extensions files (1 / detector) 2 bits single precision floating point 4 Mb each for 4*512*1024 pixels out 1 or 2 Gb per night are automatically classified with the sification keywords (DPR.CATG, H, DPR.TYPE). words uniquely define the kind of ile they are written into (Science on, calibration lamp for wavelength n, flat field observation, standard star with nodding. etc...). matically decides using those which pipeline recipe it will execute o reduce the data. H ESO DPR CATG = 'CALIB' H ESO DPR TECH = 'SPECTRUM' H ESO DPR TYPE = 'FLAT' CRIRES flat-field calibration file that be reduced by the system with the ec_flat recipe. The association the DPR keywords and the recipes is n the pipeline package. **Data Reduction Pipeline Utilities** The different utilities allow a flexible data reduction, and a better control of the intermediate products Main intermediate products: • COMBINED_IMA: The combined image • CALPRO_WAVE: The wavelength calibration solution • EXTRACT_WL_TAB: The extracted spectrum (in wavelength) • EXTRACT_SENS_TAB: The extracted spectrum (in wavelength), the sensitivity, the conversion factor, the throughput. Only for standard stars. Lamp or Gas Cell or Sky Observation CALPRO_HITRAN_CATALOG CALPRO_THAR_CATALOG crires_util_extract > CALPRO_OH_CATALOG PROFILE_IMA EXTRACT_PIX_TAB crires_util_wlinit es util wlcalib



Wavelength Calibration

P (1024

P (512) P (1)

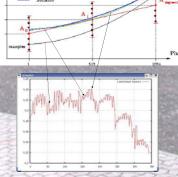
- Inputs:

 The Estimate Polynomial (coming from the physical model or a previous computation in an iterative process)
 The Wavelength Error of the estimate (WLerror)
 The degree of the searched polynomial (degree)
 The number of samples (nsamples)
 The lines catalogue (OH, Gas cell, Lamps, Hitran) depending on the signal to calibrate
 The signal to calibrate (in pixels)
 Wavelength

- Consider degree+1 positions Ai regularly spaced, and nsamples points spread within WLerror around these positions

- WLerror around these positions
 For each possible sequence of points (nsamples*(degree+1) possibilities), the interpolation polynomial is created and considered as candidate
 The candidate polynomial is used to convert the signal to calibrate from pixels to wavelengths. This signal is compared to the signal generated from the catalogue. A likelihood coefficient is computed
 The best likelihood parameter gives the best candidate, i.e. the polynomial that is the closest to the solution
- closest to the solution
- A second pass (or more) is used to refine the 5. solution with the first pass solution used as estimate, with a smaller WLerror and a higher

2.5



nial Pestimate (input)

Candidate polynomial Best polynomial (the closest to the soluti

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- Advantages: The method is very generic. It is used for CRIRES and SOFI, It will be used for ISAAC, NACO and VISIR. The best likelihood factor gives a good idea of the quality of the final calibration There is no line detection involved, it works also for noisy signals (interesting in infrared)
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