



Fig. 2 and shows a mean residual less than 0.08 for the red surface brightness and 0.12 for the blue surface brightness. The final photometric system will be determined through a study of $m_{pg} - m_{pe}$ residuals of all B and R plates simultaneously. The dotted line in the flow chart in Fig. 1 represents this "loop" in our calibration. Providing a catalogue with standard galaxies and the list of coefficients of the characteristic curve can be considered as the first two products of our project.

The Automatic Parameter Extraction

Once the characteristic curve coefficients of a plate have been determined, the images of the galaxies are converted from density into intensity and are ready for further analysis. Using a sequence of software routines the following is obtained IAU Colloquium No. 79

Very Large Telescopes, their Instrumentation and Programs

ESO, Garching, 9-12 April, 1984

Scientific Organizing Committee:

R. Angel, R. Cayrel, O. Citterio, M. Longair, G. Münch, N. V. Steshenko, J.-P. Swings, M.-H. Ulrich (Chairman), S. van den Bergh, H. van der Laan.

The meeting will last four days. Two and one half days will be devoted to the questions of Telescope design and fabrication, Domes, Sites, Instruments and Components:

- Primary mirrors, structures, support systems
- Active optics, wind loading, dome seeing, properties of the atmosphere
- Radiometric properties of telescopes
- Instrument matching in spectroscopy and direct imaging
- Large format detectors in the optical and IR
- Interferometry and speckle methods

One day will be allotted to Reviews of the Astronomical Programs and one half day to a panel discussion and a summary.

Invited Speakers include:

R. Angel, J. Beckers, H. Butcher, V. Castellani, F. Forbes, P. Léna, F. Low, R. Lynds, B. Mack, J. Nelson, H. Richardson, F. Roddier, R. Tull, J. Wampler, G. Weigelt, N. Woolf.

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in one main programme. First a version of the programme INVENTORY is run which detects and classifies all objects present in a single frame of a target galaxy and whose surface brightness exceeds that of the sky by a factor two. On average about 20 such objects are found per frame and their positions, magnitude and classification are calculated using a reference point spread function. The data are stored in a separate disk file for later investigation. In the future this data bank will be used to search for peculiar objects, such as quasars and novae, in the neighbourhood of the target galaxies. For instance, an automatic survey of objects with a certain colour excess will be feasible. The INVENTORY programme finally creates an image with all neighbouring objects subtracted from the input image. Next, as a first step in a string of our own routines, which we have called AND, the sky brightness distribution is approximated by a plane using 8 surrounding subregions, four of them being close to the corners. After the subtraction of the sky we are finally set to extract the photometric and structural information from the images. Radial B, R and B-R profiles are stored in the disk catalogue together with overall elongations and position angles from an octants comparison. For elliptical and SO galaxies ellipses are fitted to the isophotes determining the