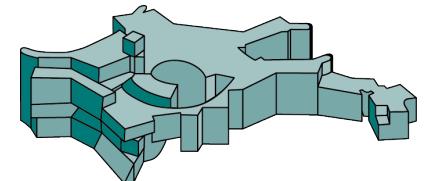


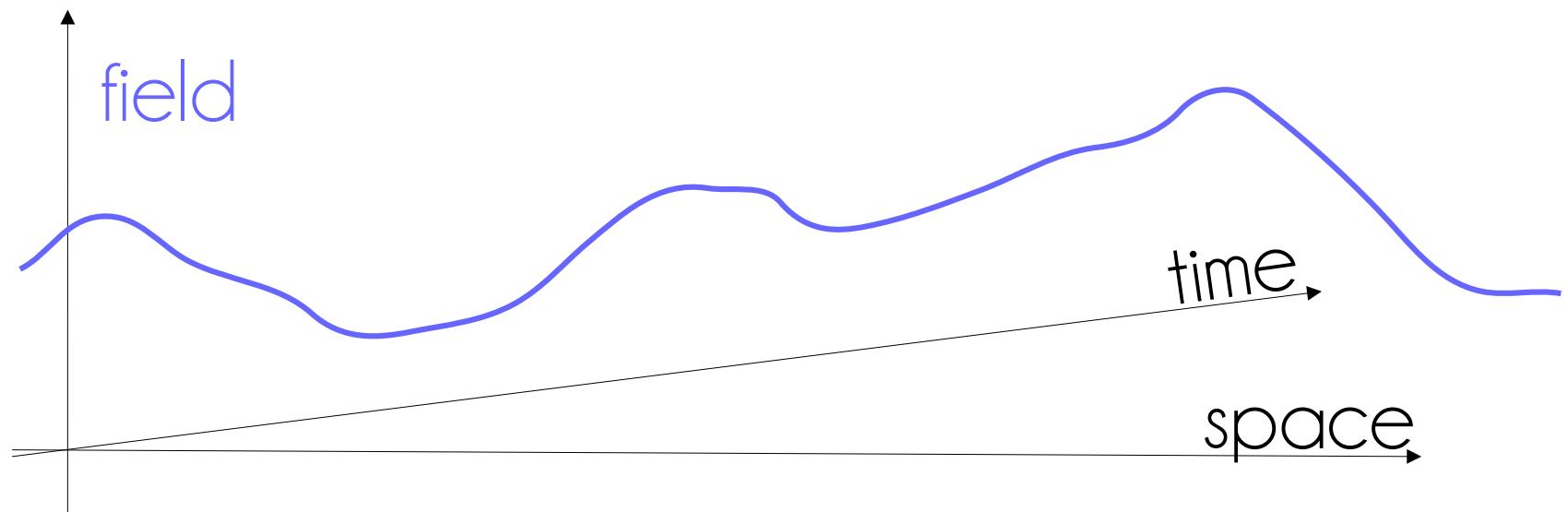
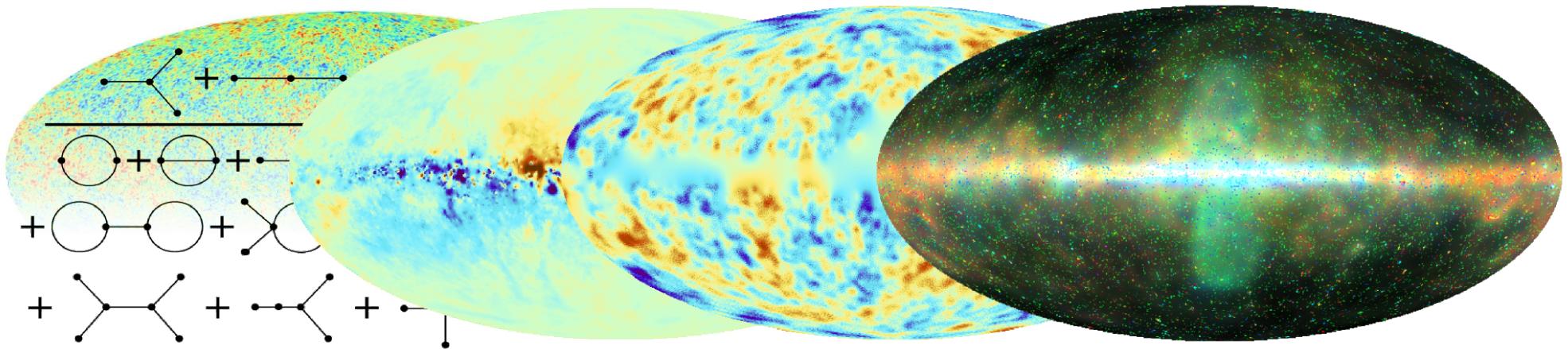
Information field theory

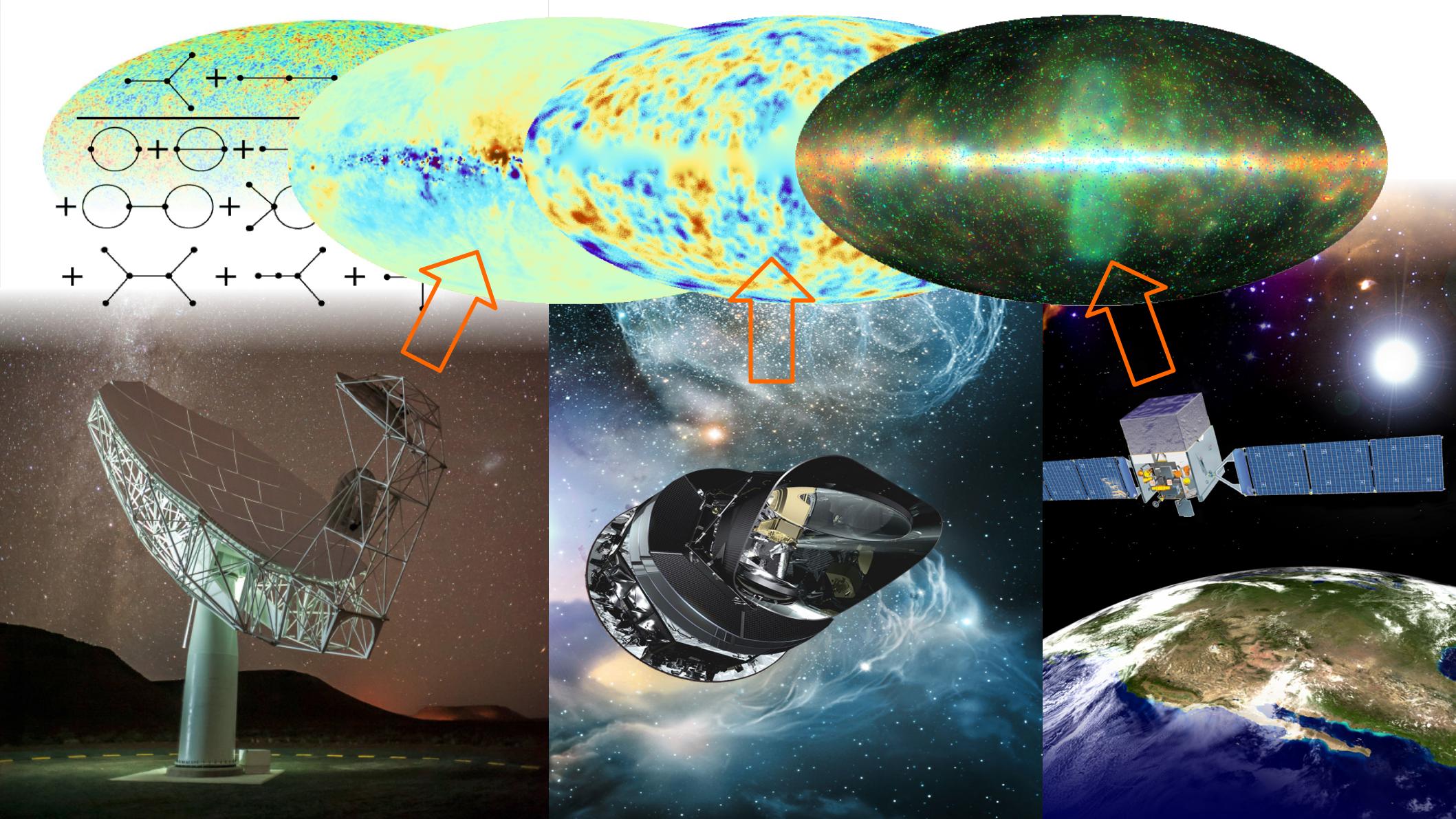


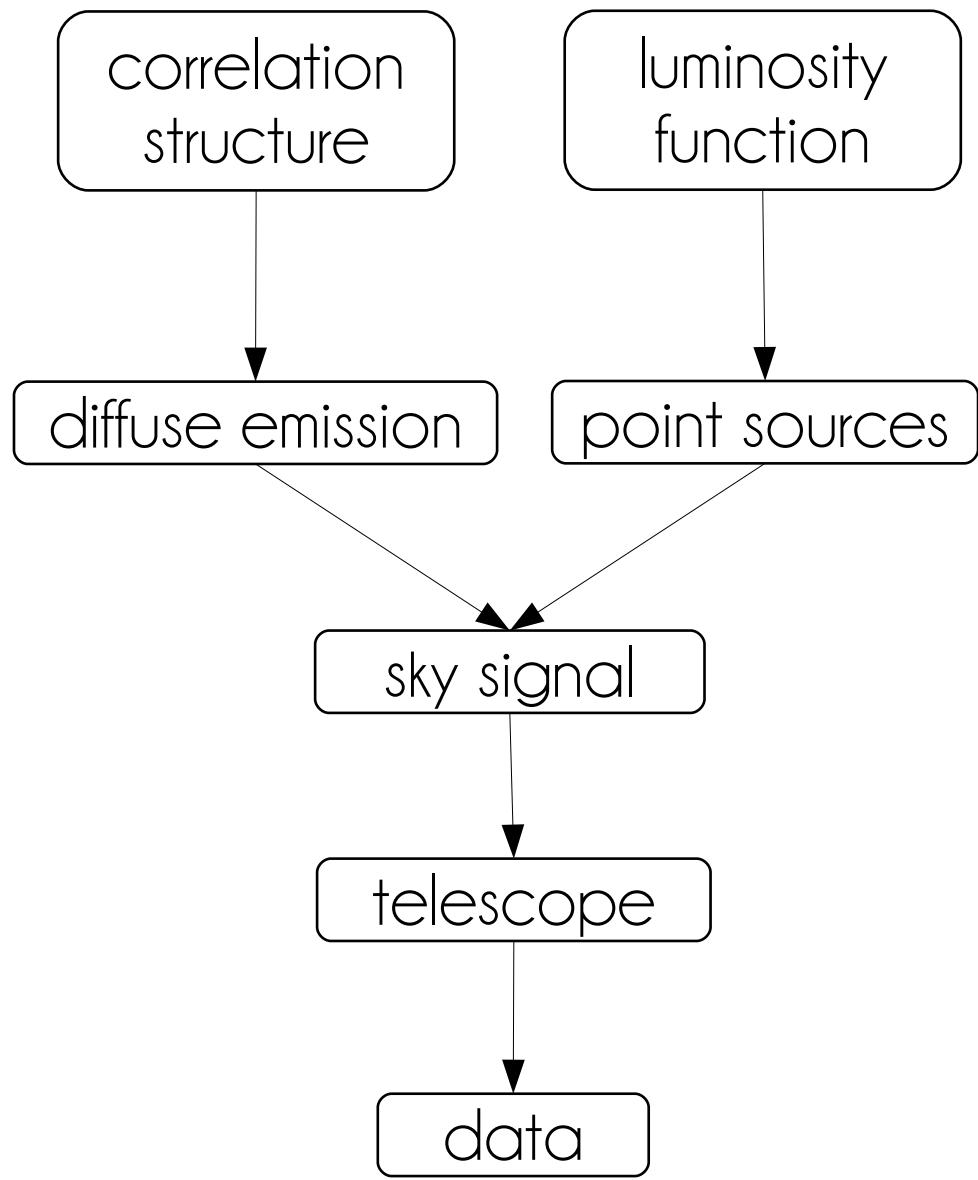
Torsten Enßlin
MPI for Astrophysics
Ludwig Maximilian University Munich



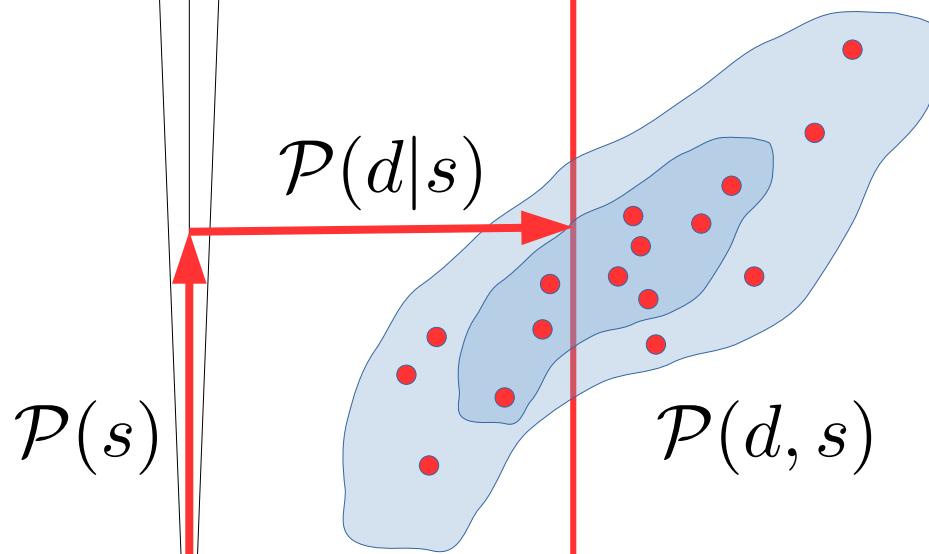
IFT Team: Philipp Arras, Michael Bell, Vanessa Böhm, Sebastian Dorn, Martin Dupont, Mona Frommert, Philipp Frank, Mahsa Chaempanah, Maksim Greiner, Philipp Haim, Sebastian Hutschenreuter, Henrik Junklewitz, Francisco-Shu Kitaura, Jakob Knollmüller, Christoph Lienhard, Reimar Leike, Anca Müller, Johannes Oberpriller, Niels Oppermann, Natalia Porquerese, Daniel Pumpe, Tiago Ramalho, Martin Reinecke, Julia Stadler, Marco Selig, Theo Steininger, Valentina Vacca, Cornelius Weig, Margret Westerkamp, & many more





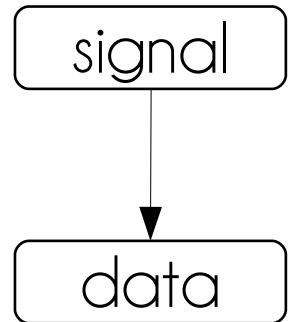


signal



$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d, s)}{\mathcal{P}(d)} = \frac{\mathcal{P}(d|s) \mathcal{P}(s)}{\mathcal{P}(d)}$$

Bayes' theorem



data

Information theory

$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d, s)}{\mathcal{P}(d)} = \frac{e^{-\mathcal{H}(d, s)}}{\mathcal{Z}(d)}$$

$$\mathcal{H}(d, s) = -\log \mathcal{P}(d, s)$$

$$\mathcal{Z}(d) = \mathcal{P}(d)$$

$$= \int \mathcal{D}s \mathcal{P}(d, s)$$

$$\mathcal{P}(d, s) = \mathcal{P}(d|s) \mathcal{P}(s)$$

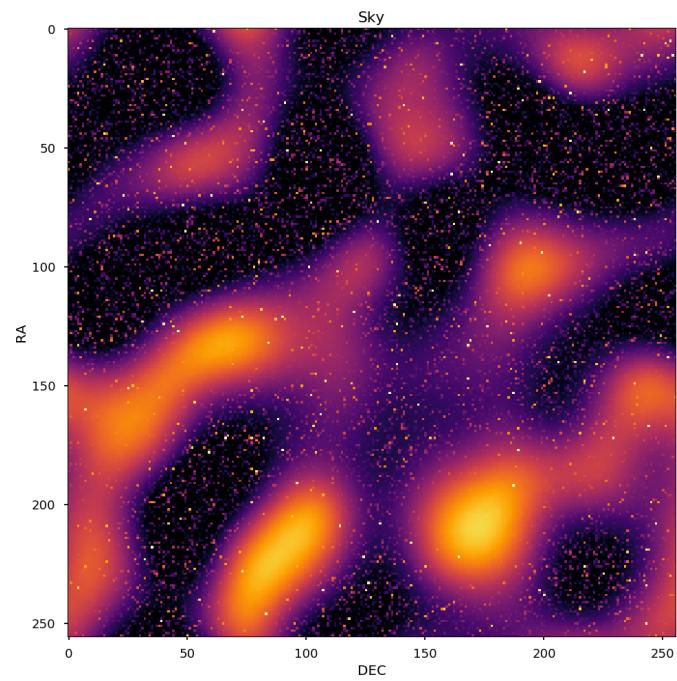
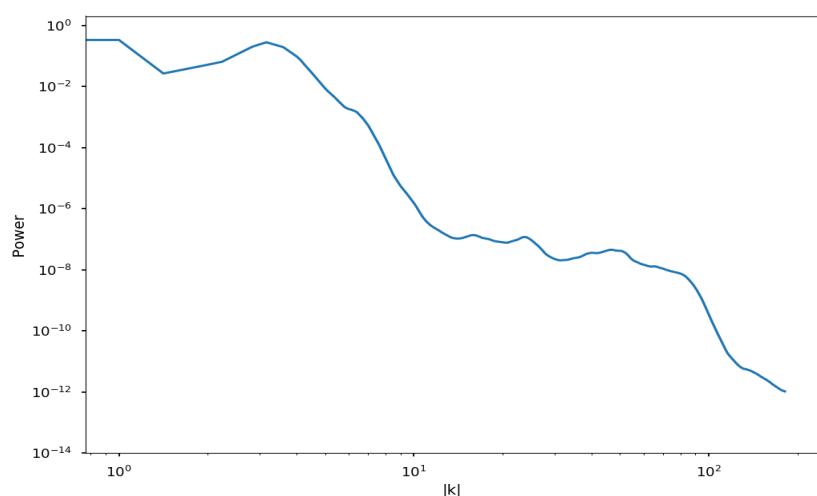
$$\mathcal{H}(d, s) = \mathcal{H}(d|s) + \mathcal{H}(s)$$

metric

regularization

Information

is additive



$$\mathcal{P}(s)$$

correlation
structure

luminosity
function

diffuse emission

point sources

sky signal

$$\text{telescope } \mathcal{P}(d|s)$$

data

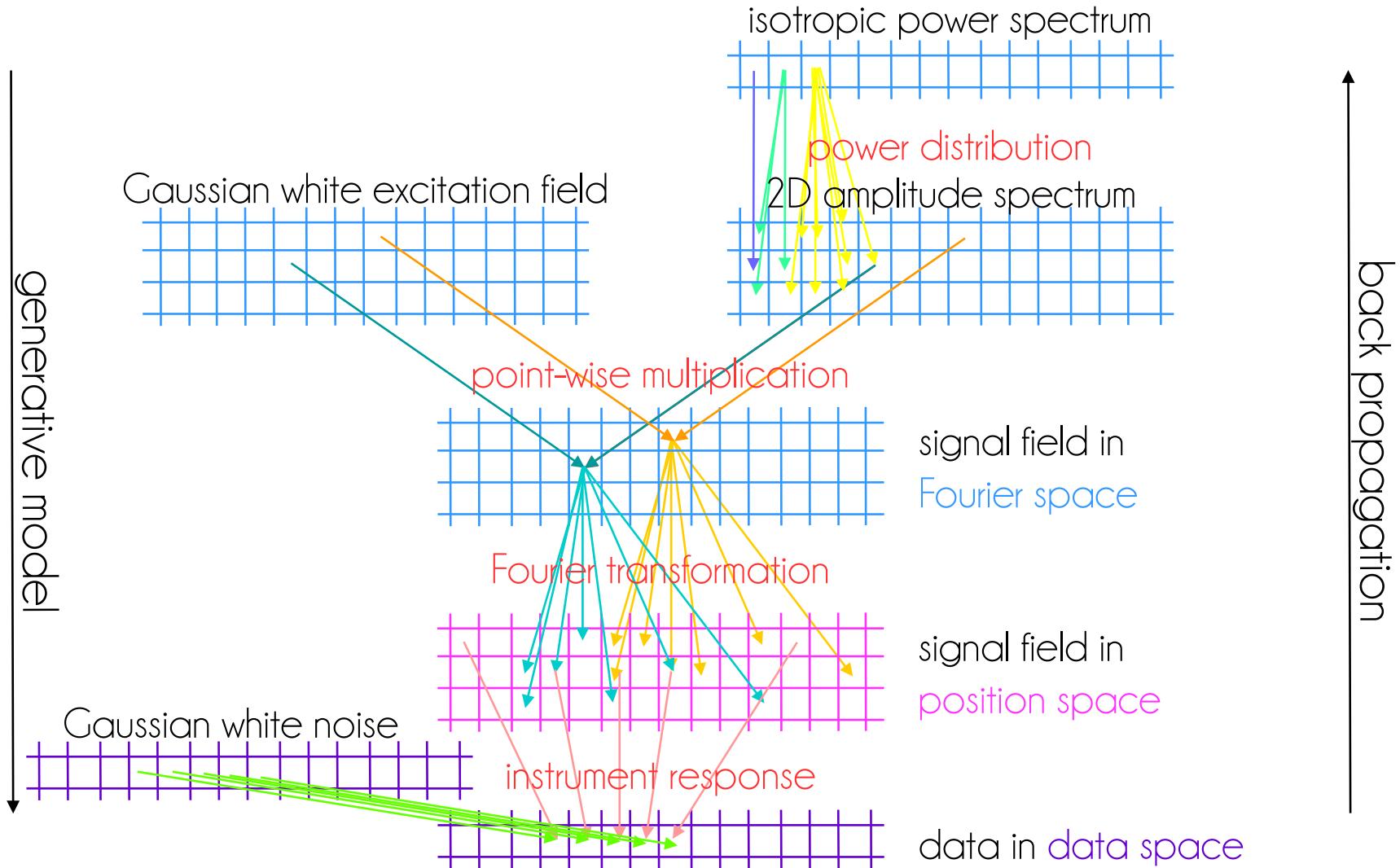
Photon counting instrument: Log-normal Poisson model



Information

$$\begin{aligned}\mathcal{H}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) &= -\log \mathcal{P}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) \\&= \boldsymbol{1}^\dagger [\log(d!) + \boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] - \boldsymbol{d}^\dagger \log [\boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] \\&\quad + \frac{1}{2} \boldsymbol{s}^\dagger \boldsymbol{S}^{-1} \boldsymbol{s} + \frac{1}{2} \log (\det [\boldsymbol{S}]) \\&\quad + (\boldsymbol{\alpha} - \mathbf{1})^\dagger \boldsymbol{\tau} + \boldsymbol{q}^\dagger \mathrm{e}^{-\boldsymbol{\tau}} + \frac{1}{2} \boldsymbol{\tau}^\dagger \boldsymbol{T} \boldsymbol{\tau} \\&\quad + (\boldsymbol{\beta} - \mathbf{1})^\dagger \boldsymbol{u} + \boldsymbol{\eta}^\dagger \mathrm{e}^{-\boldsymbol{u}} \\ \boldsymbol{S} &= \sum_k \mathrm{e}^{\tau_k} \boldsymbol{S}_k\end{aligned}$$

IFT as neural network





NIFTy – Numerical Information Field Theory

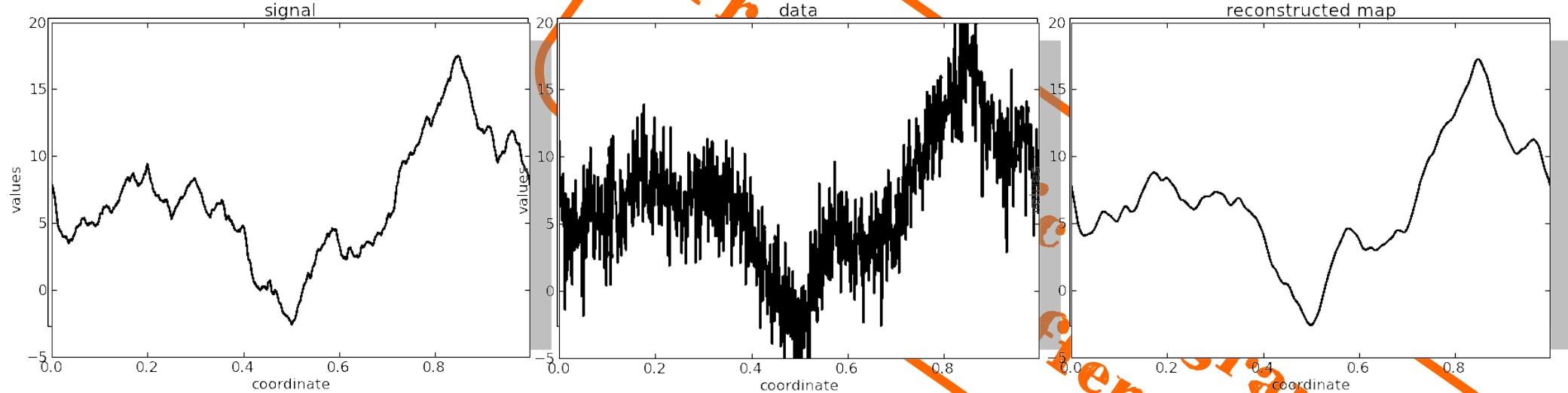
NIFTy [1], [2], "Numerical Information Field Theory is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python."

*Probabilistic programming
with auto-differentiation*



NIFTy – Numerical Information Field Theory

NIFTy [1], [2], "Numerical Information Field Theory is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python."



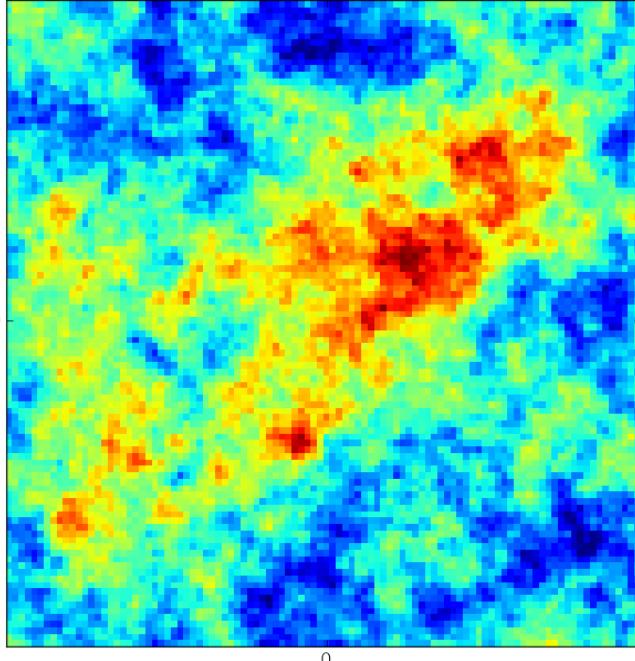
```
import nifty5 as ift  
s_space = ift.RGSpace([N])
```



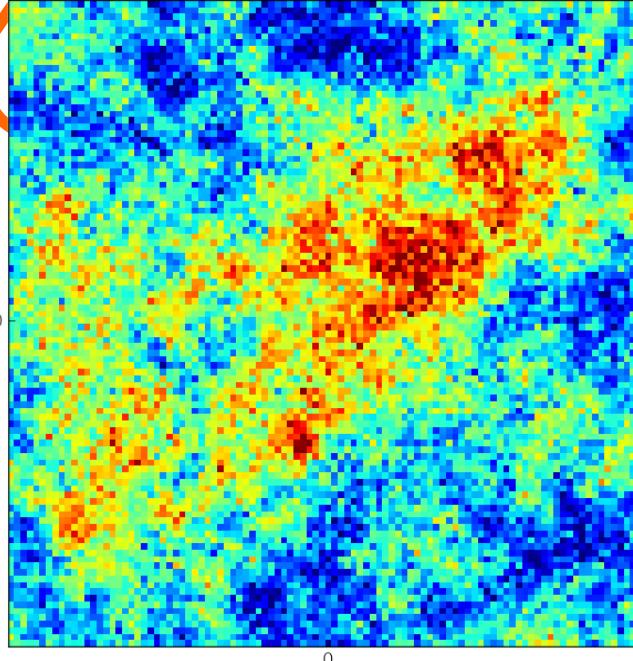
NIFTy – Numerical Information Field Theory

NIFTy [1], [2], "Numerical Information Field Theory is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python."

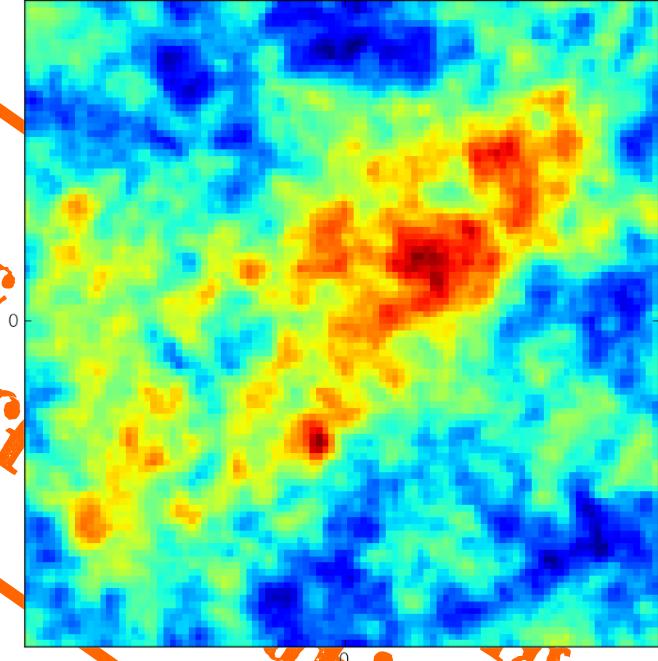
signal



data



reconstructed map

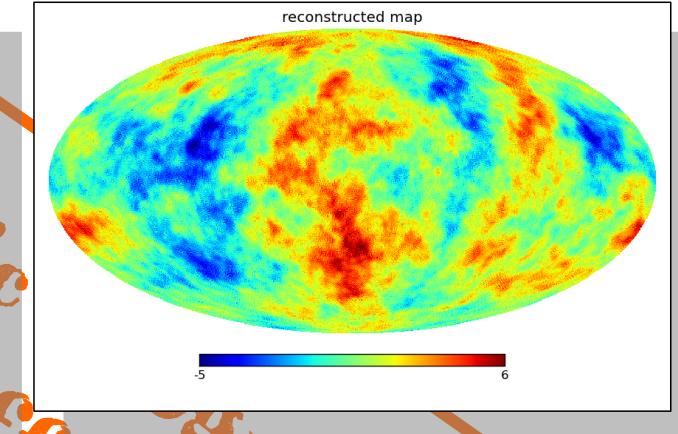
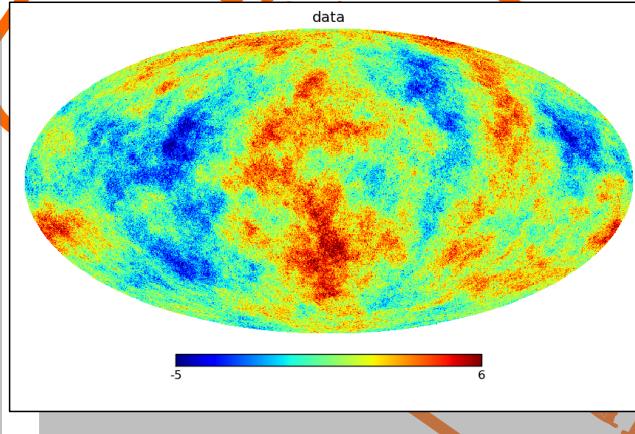
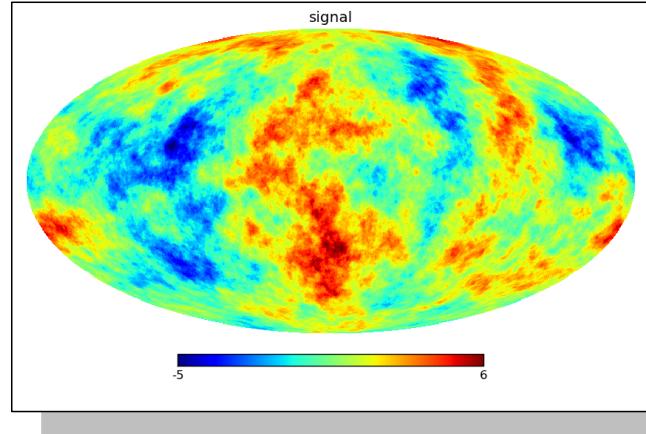


```
import nifty5 as ift  
s_space = ift.RGSpace([N,N])
```



NIFTy – Numerical Information Field Theory

NIFTy [1], [2], "Numerical Information Field Theory is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python."



```
import nifty5 as ift  
s_space = ift.HPSpace(NSide)
```

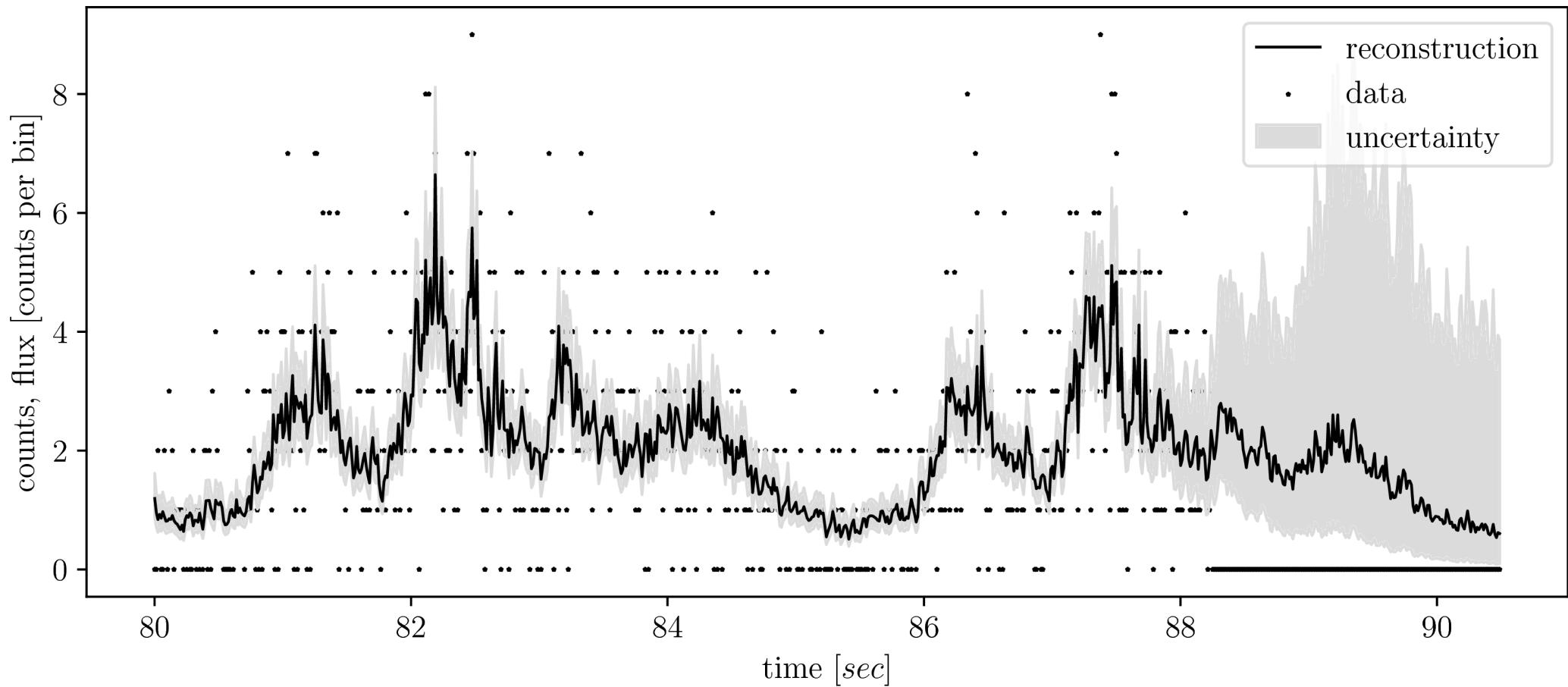
gramming.
differentia-

Information

$$\begin{aligned}\mathcal{H}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) &= -\log \mathcal{P}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) \\&= \boldsymbol{1}^\dagger [\log(d!) + \boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] - \boldsymbol{d}^\dagger \log [\boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] \\&\quad + \frac{1}{2} \boldsymbol{s}^\dagger \boldsymbol{S}^{-1} \boldsymbol{s} + \frac{1}{2} \log (\det [\boldsymbol{S}]) \\&\quad + (\boldsymbol{\alpha} - \mathbf{1})^\dagger \boldsymbol{\tau} + \boldsymbol{q}^\dagger \mathrm{e}^{-\boldsymbol{\tau}} + \frac{1}{2} \boldsymbol{\tau}^\dagger \boldsymbol{T} \boldsymbol{\tau} \\&\quad + (\boldsymbol{\beta} - \mathbf{1})^\dagger \boldsymbol{u} + \boldsymbol{\eta}^\dagger \mathrm{e}^{-\boldsymbol{u}} \\ \boldsymbol{S} &= \sum_k \mathrm{e}^{\tau_k} \boldsymbol{S}_k\end{aligned}$$

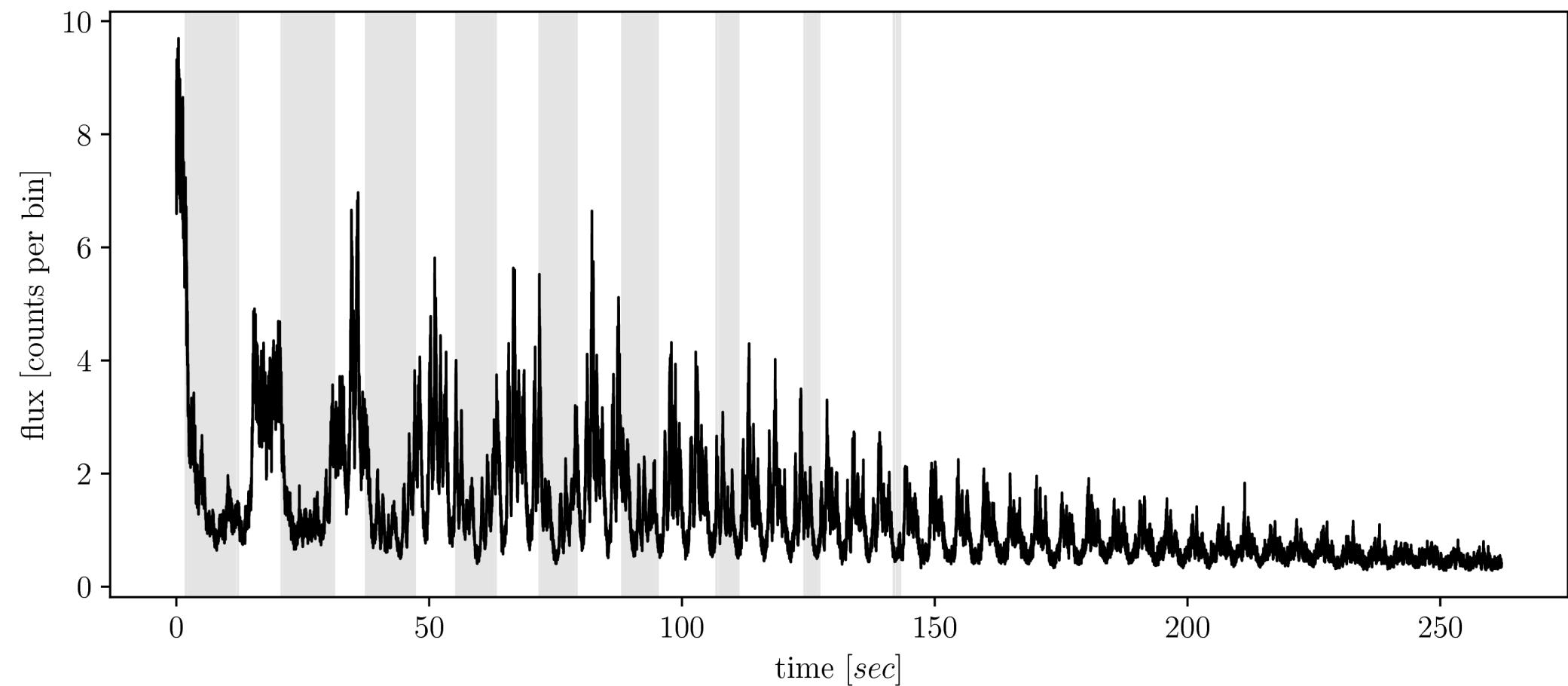
Magnetar flare SGR 1900+14

Pumpe et al. (2018)



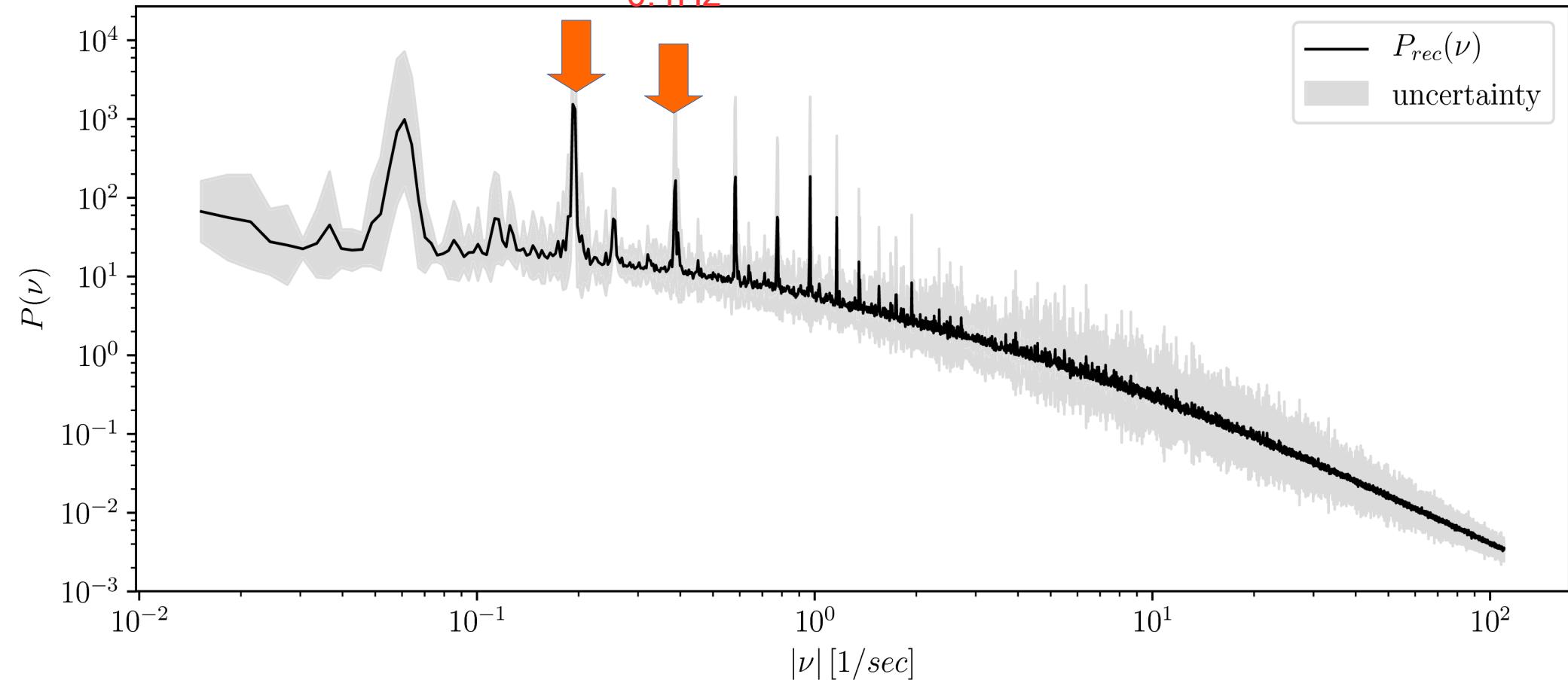
Magnetar flare SGR 1900+14

Pumpe et al. (2018)



Magnetar flare SGR 1900+14

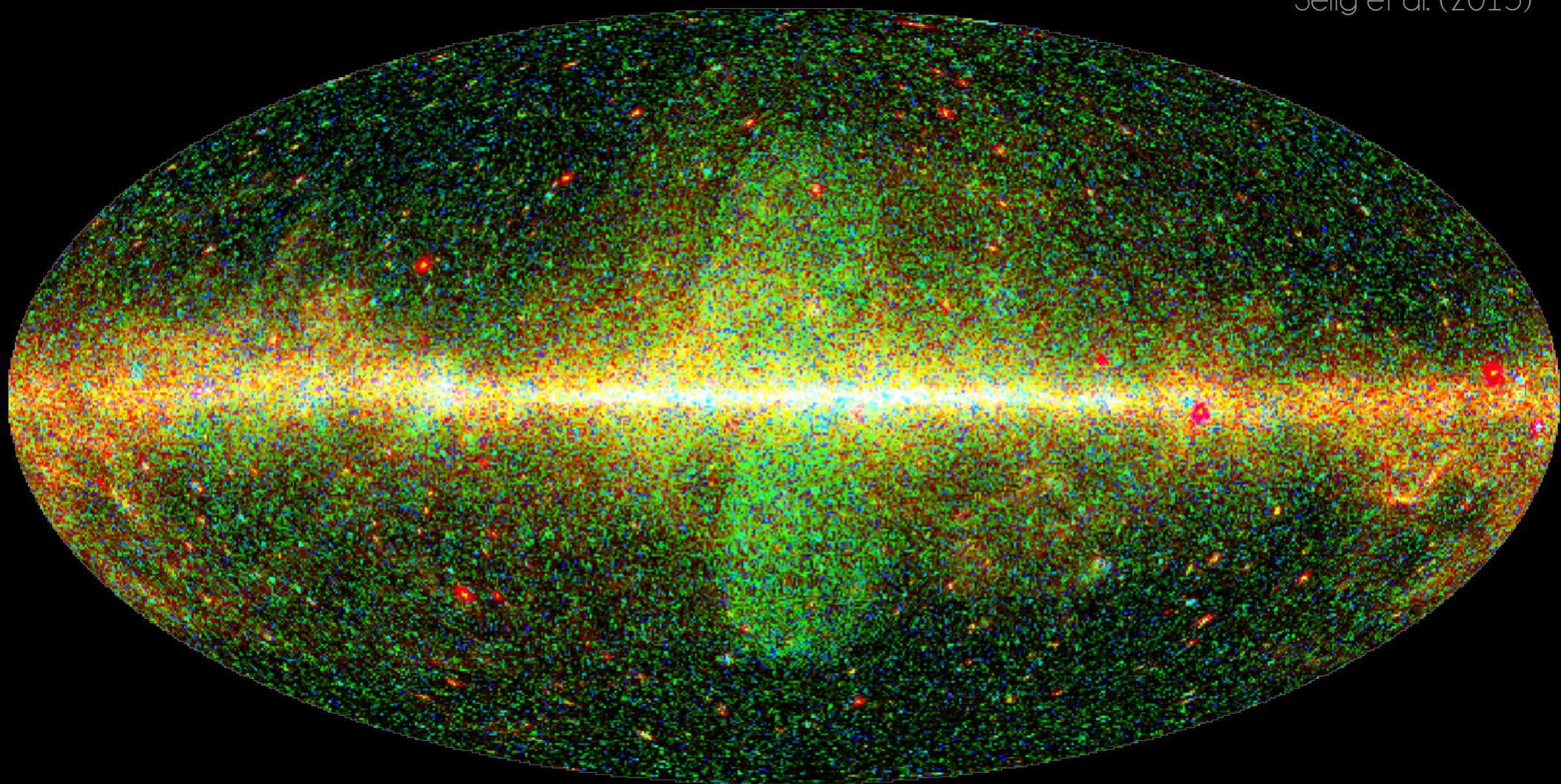
0.2Hz Pumpe et al. (2018)
0.4Hz

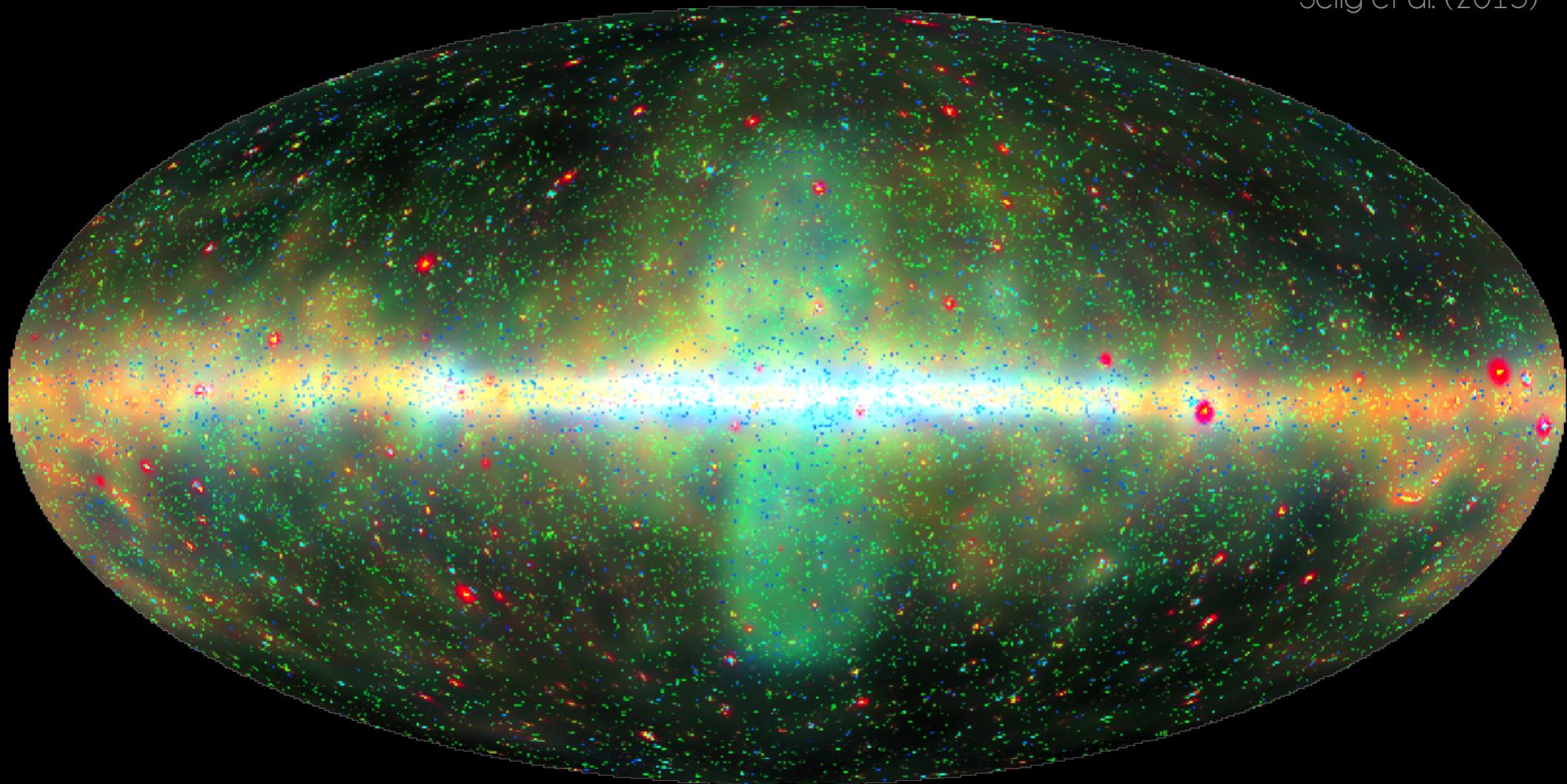


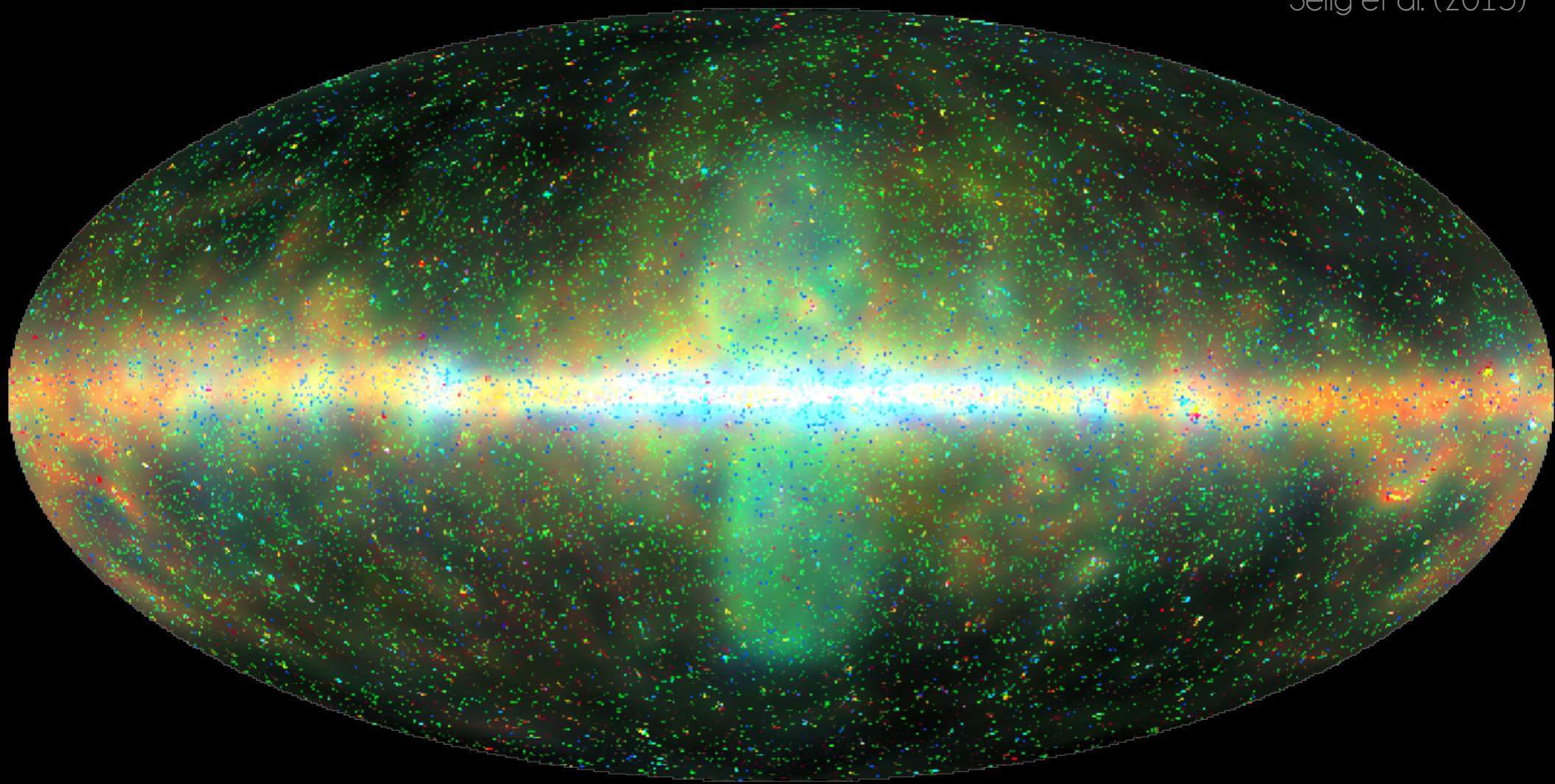
Information

$$\begin{aligned}\mathcal{H}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) &= -\log \mathcal{P}(\boldsymbol{d}, \boldsymbol{s}, \boldsymbol{\tau}) \\&= \boldsymbol{1}^\dagger [\log(d!) + \boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] - \boldsymbol{d}^\dagger \log [\boldsymbol{R} (\mathrm{e}^{\boldsymbol{s}} + \mathrm{e}^{\boldsymbol{u}})] \\&\quad + \frac{1}{2} \boldsymbol{s}^\dagger \boldsymbol{S}^{-1} \boldsymbol{s} + \frac{1}{2} \log (\det [\boldsymbol{S}]) \\&\quad + (\boldsymbol{\alpha} - \mathbf{1})^\dagger \boldsymbol{\tau} + \boldsymbol{q}^\dagger \mathrm{e}^{-\boldsymbol{\tau}} + \frac{1}{2} \boldsymbol{\tau}^\dagger \boldsymbol{T} \boldsymbol{\tau} \\&\quad + (\boldsymbol{\beta} - \mathbf{1})^\dagger \boldsymbol{u} + \boldsymbol{\eta}^\dagger \mathrm{e}^{-\boldsymbol{u}} \\ \boldsymbol{S} &= \sum_k \mathrm{e}^{\tau_k} \boldsymbol{S}_k\end{aligned}$$

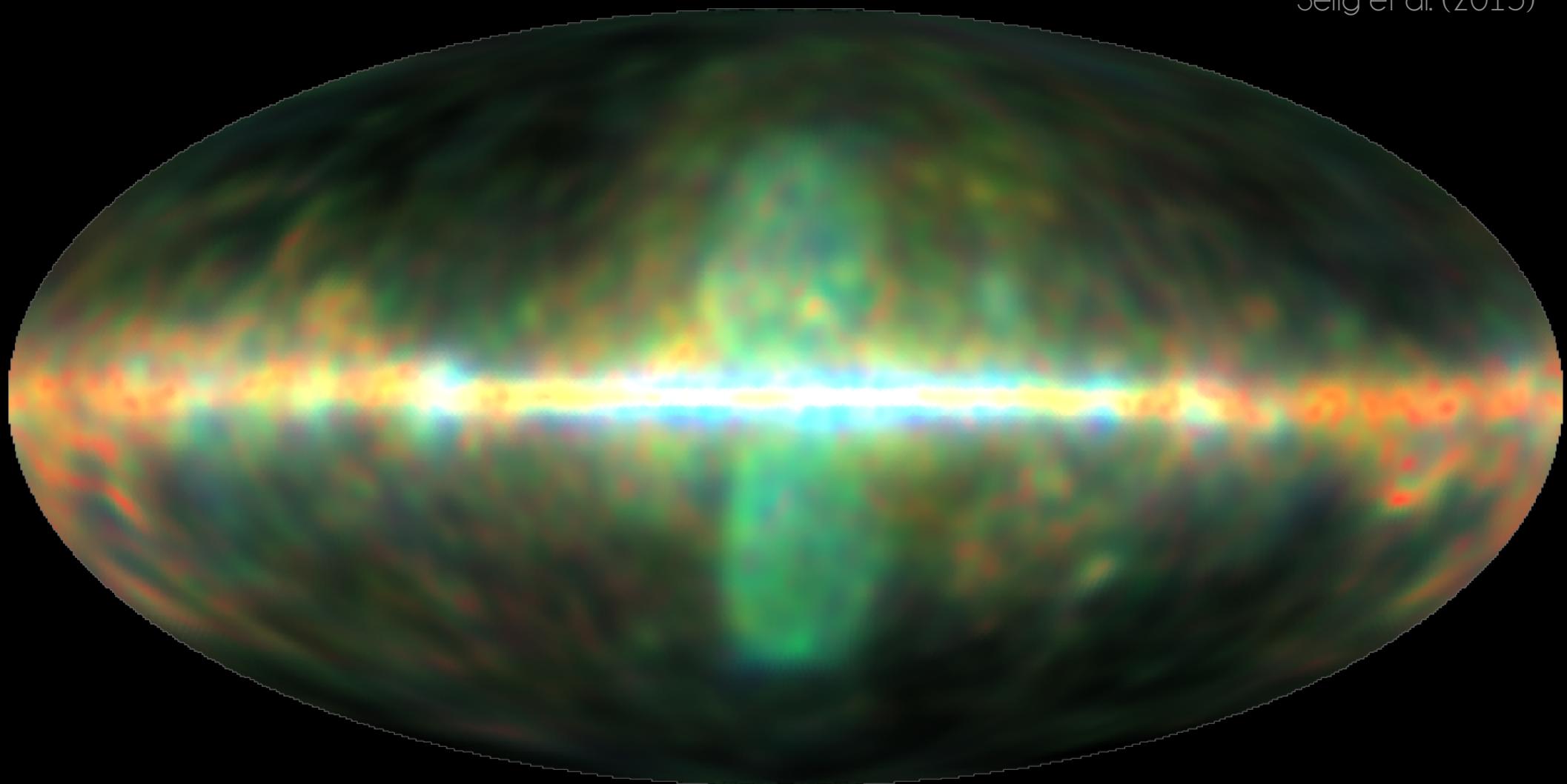
Selig et al. (2015)



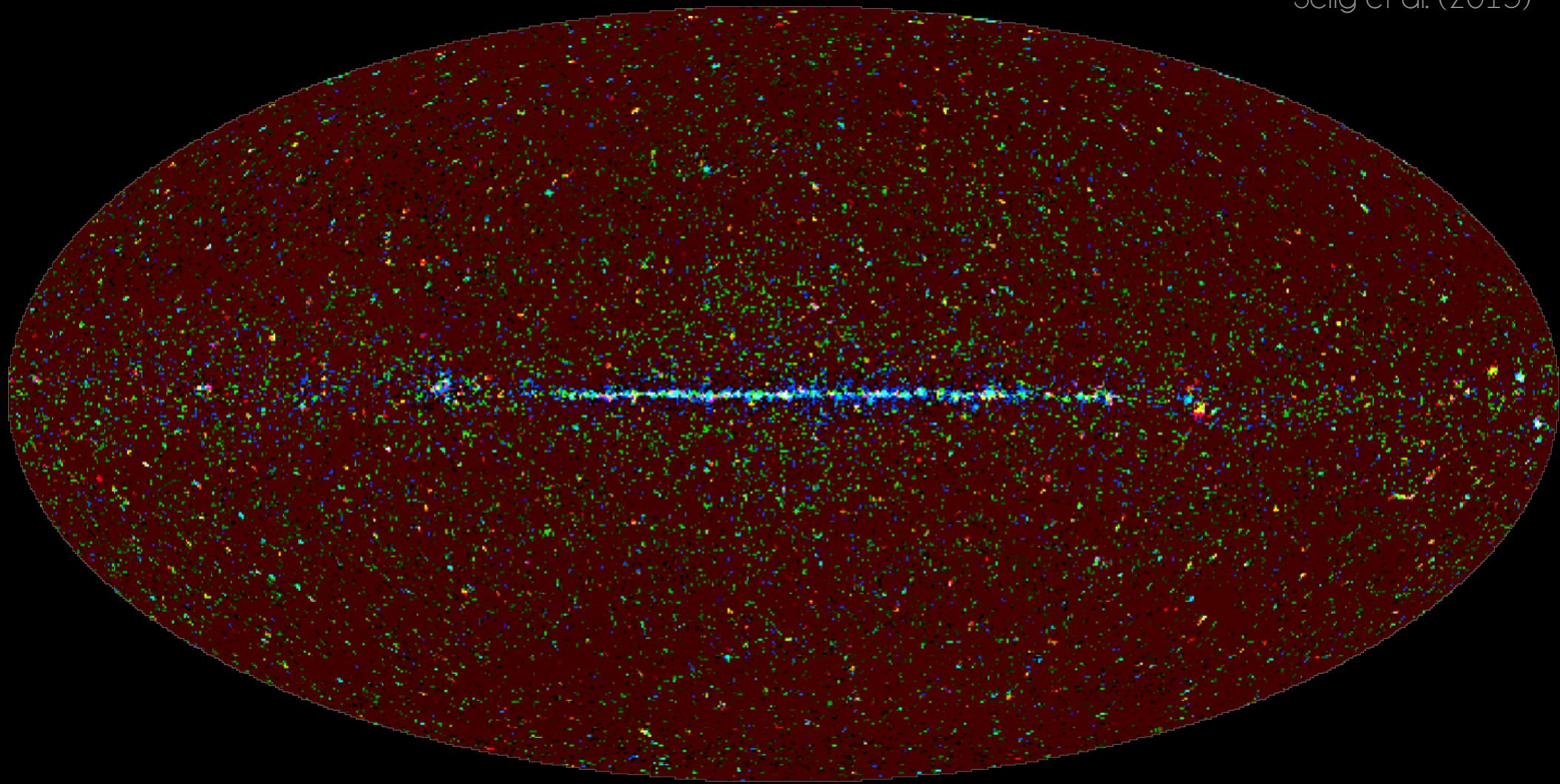




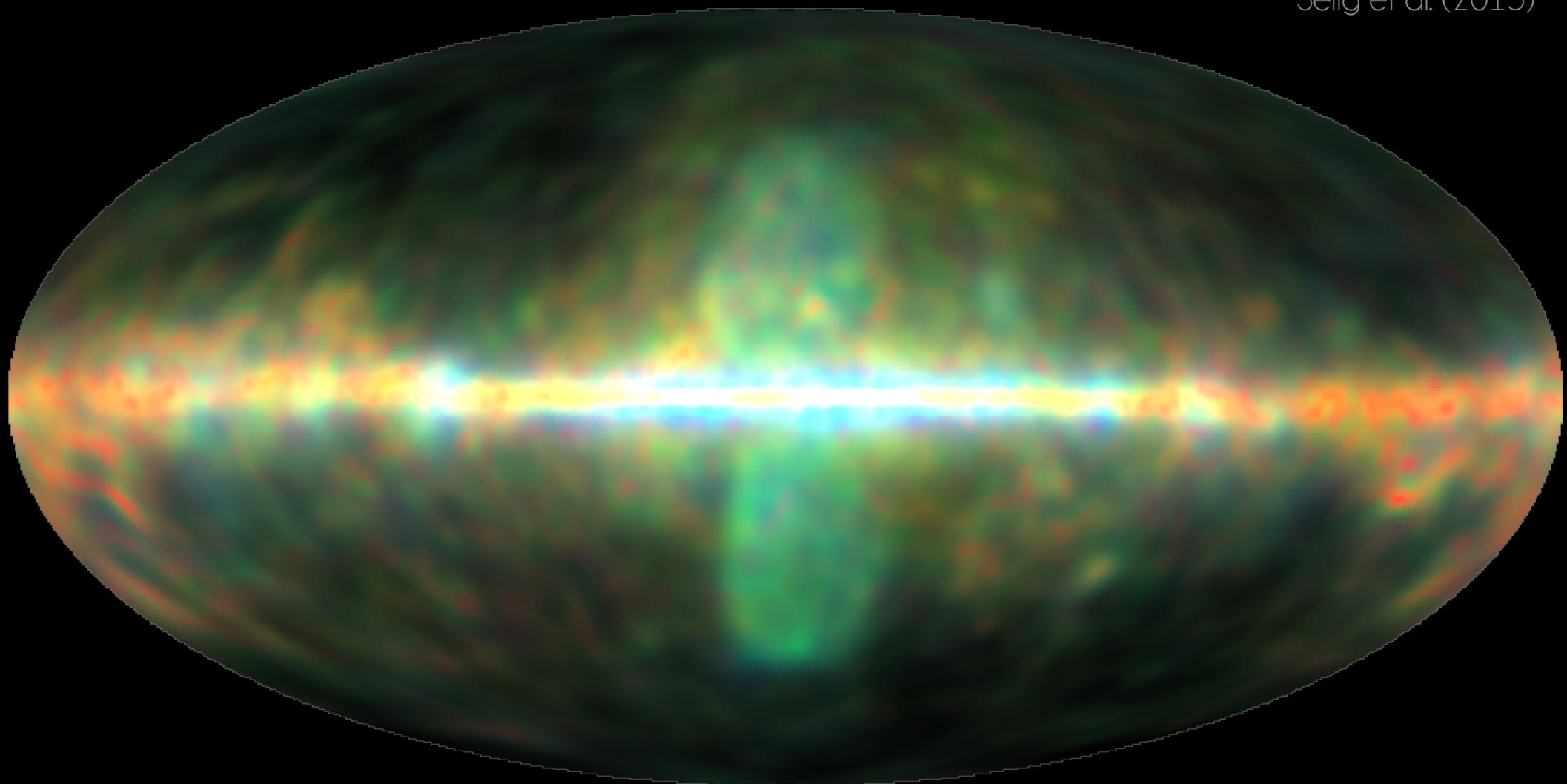
Selig et al. (2015)



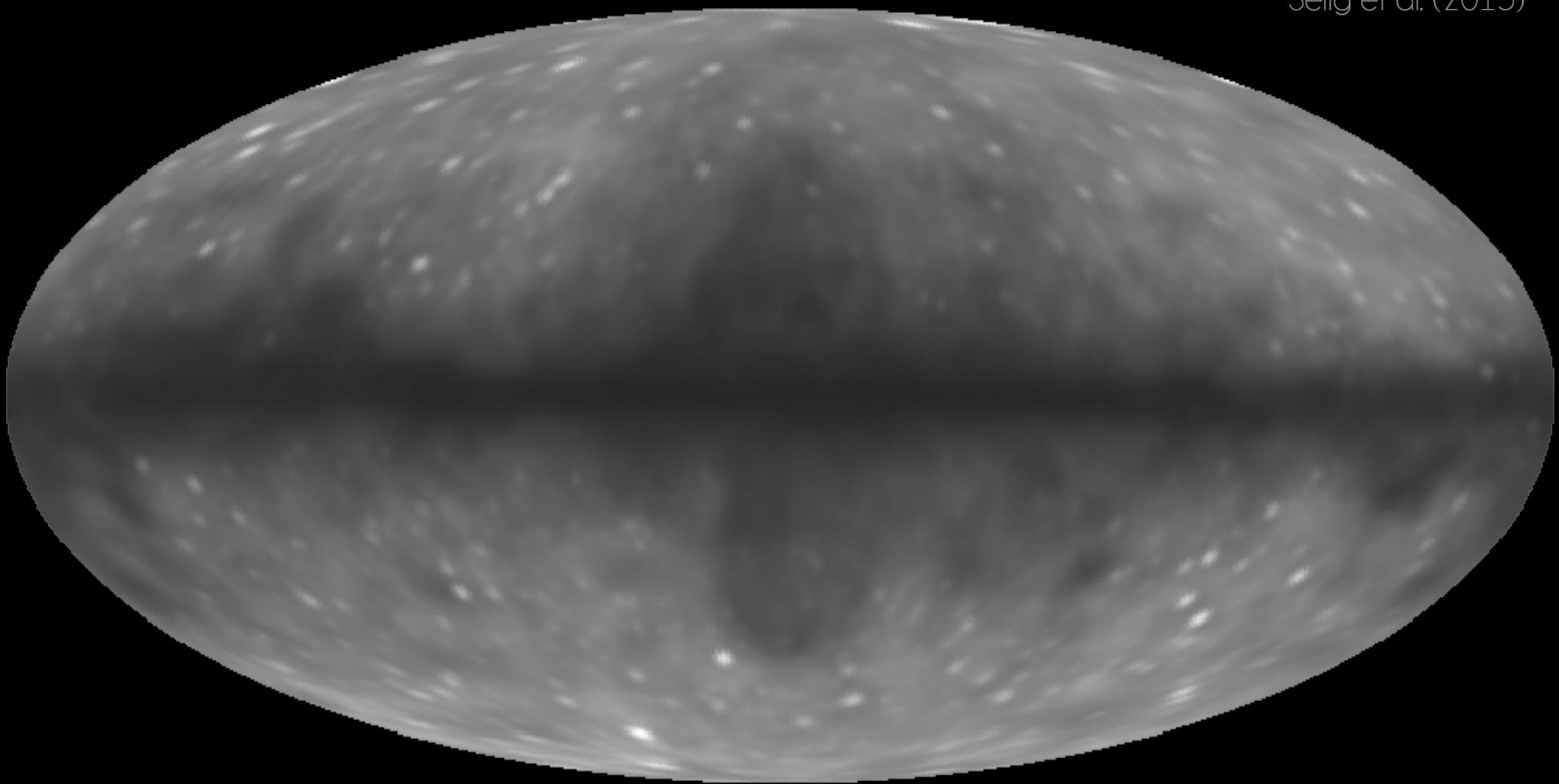
Selig et al. (2015)

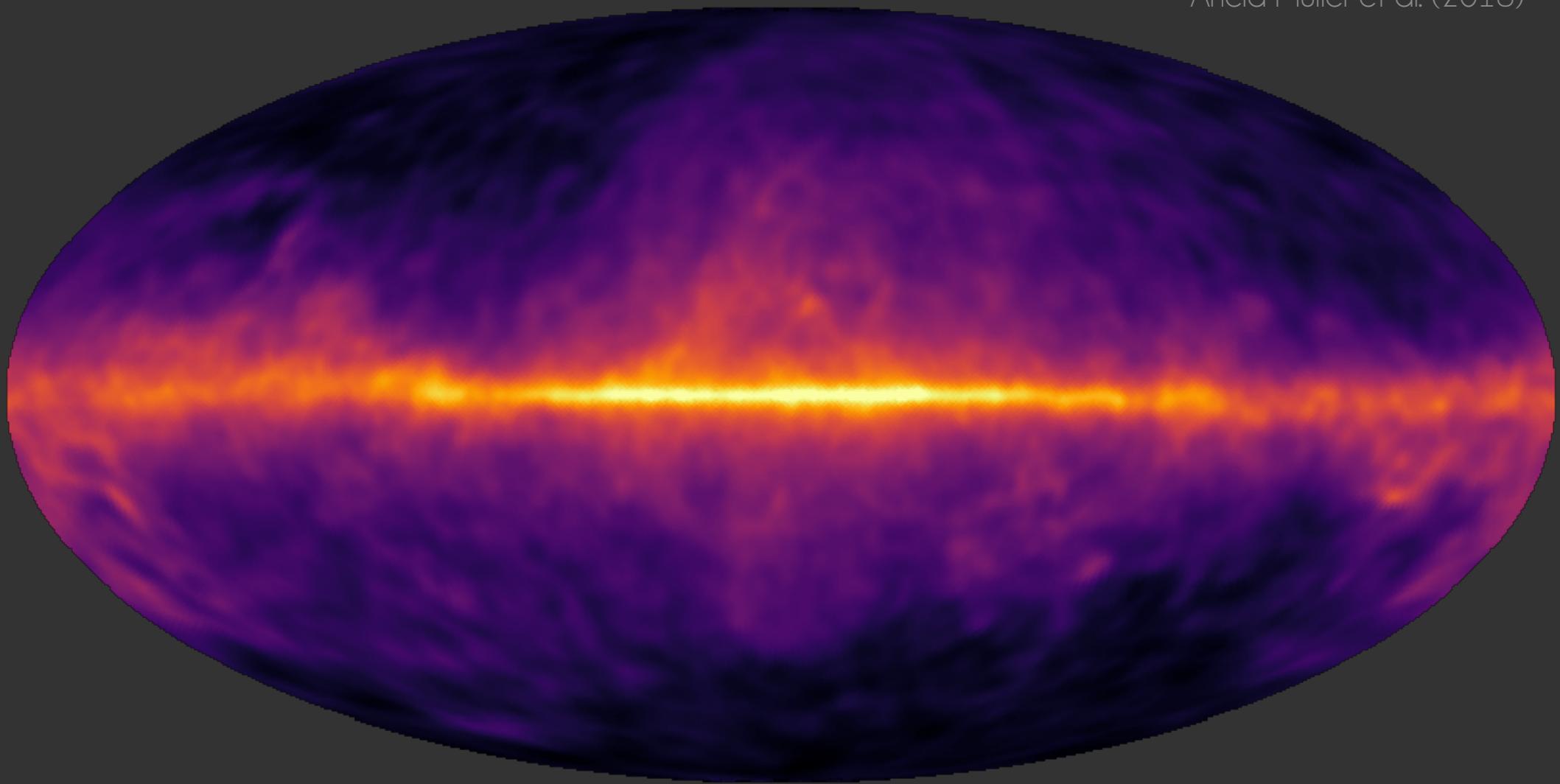


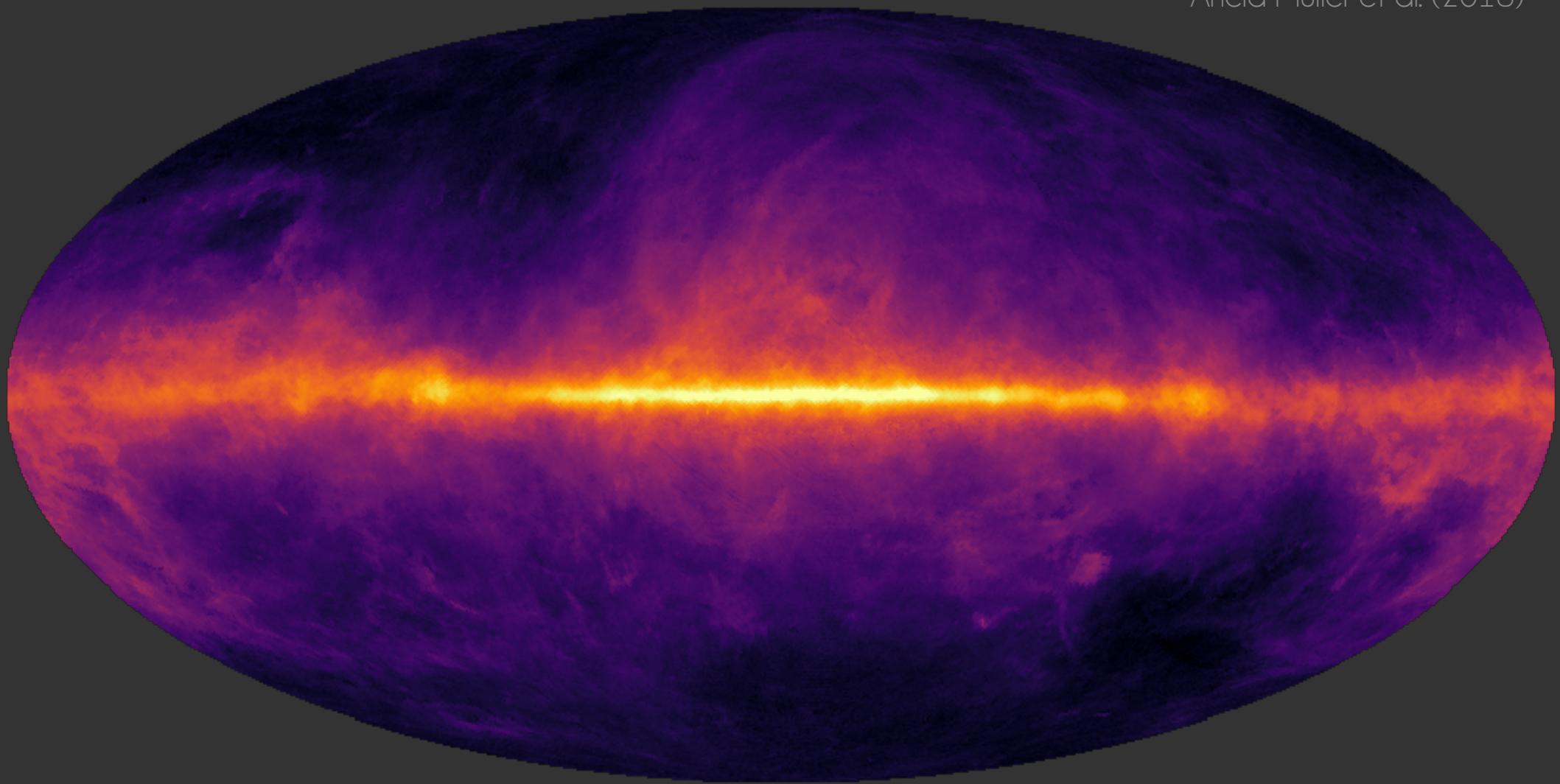
Selig et al. (2015)



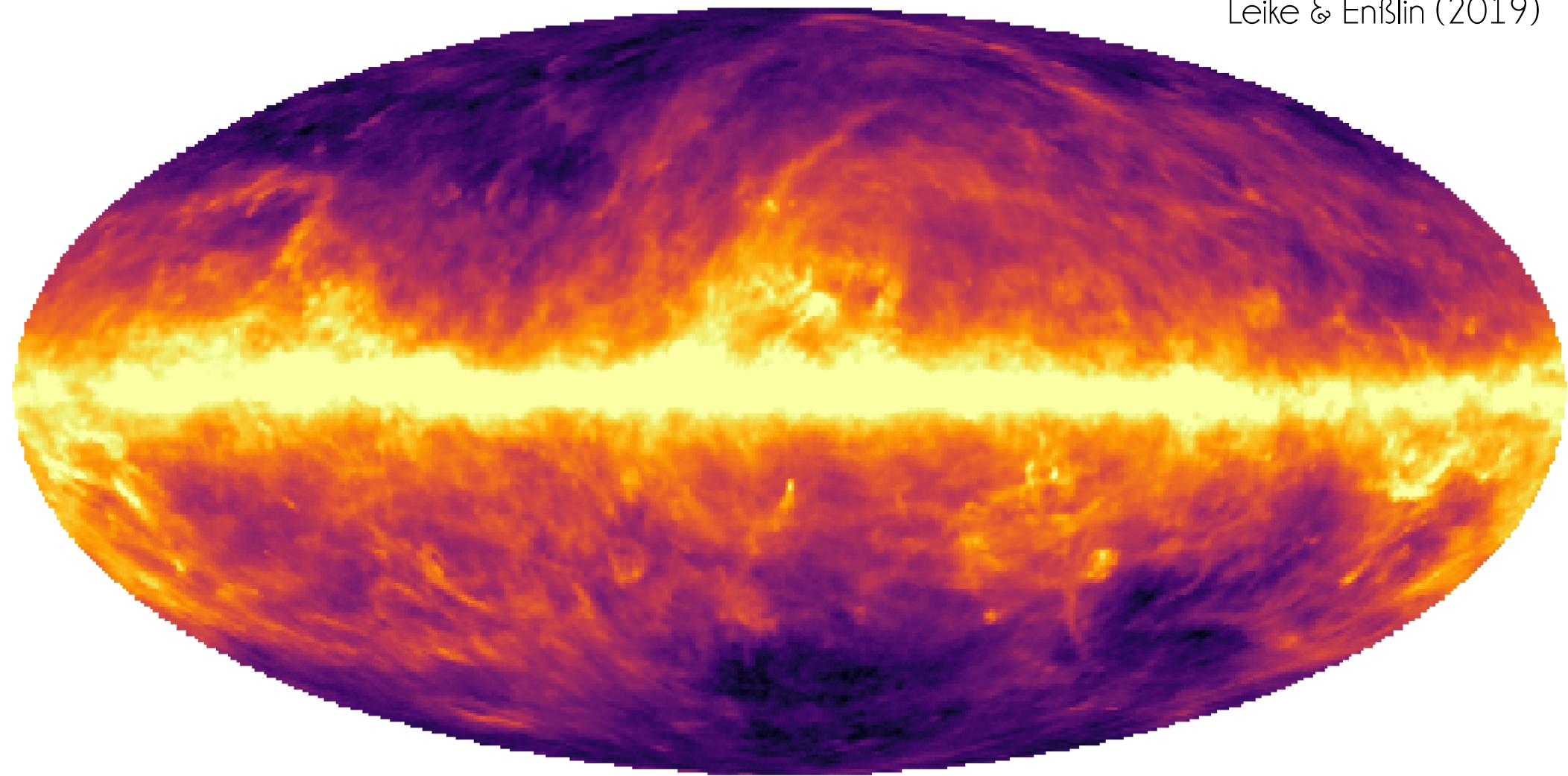
Selig et al. (2015)



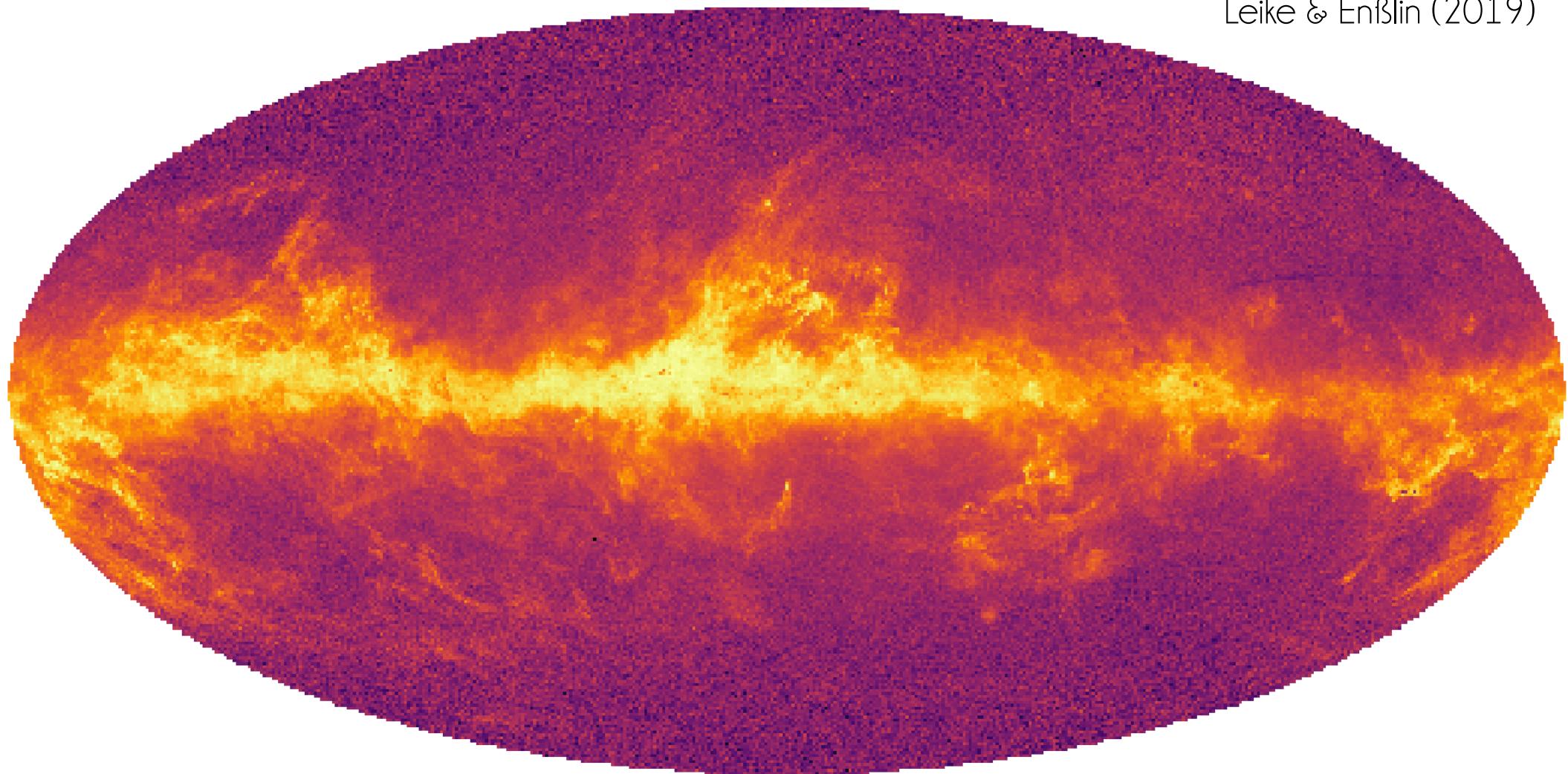




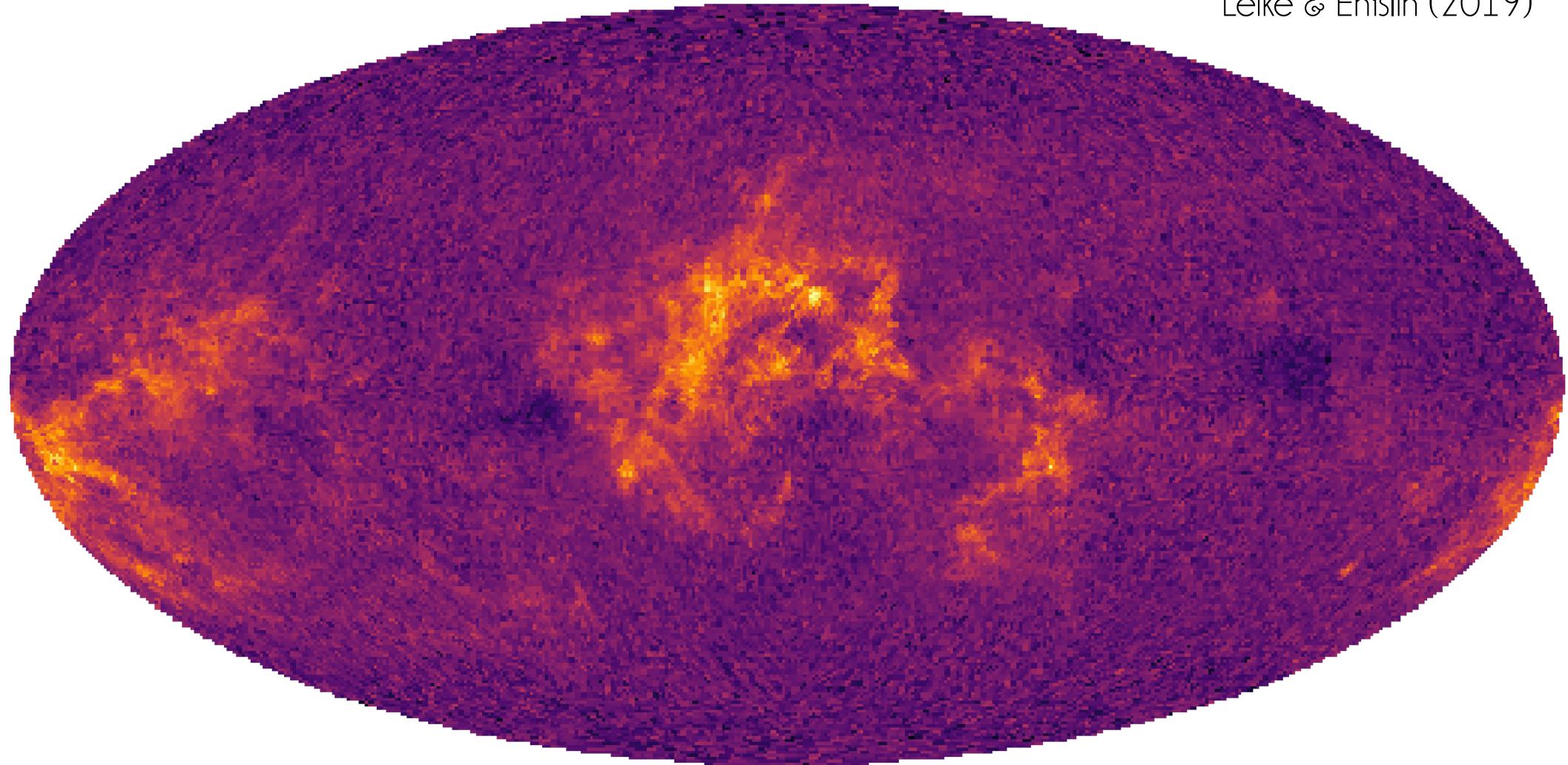
dust emission by Planck
Leike & Enßlin (2019)



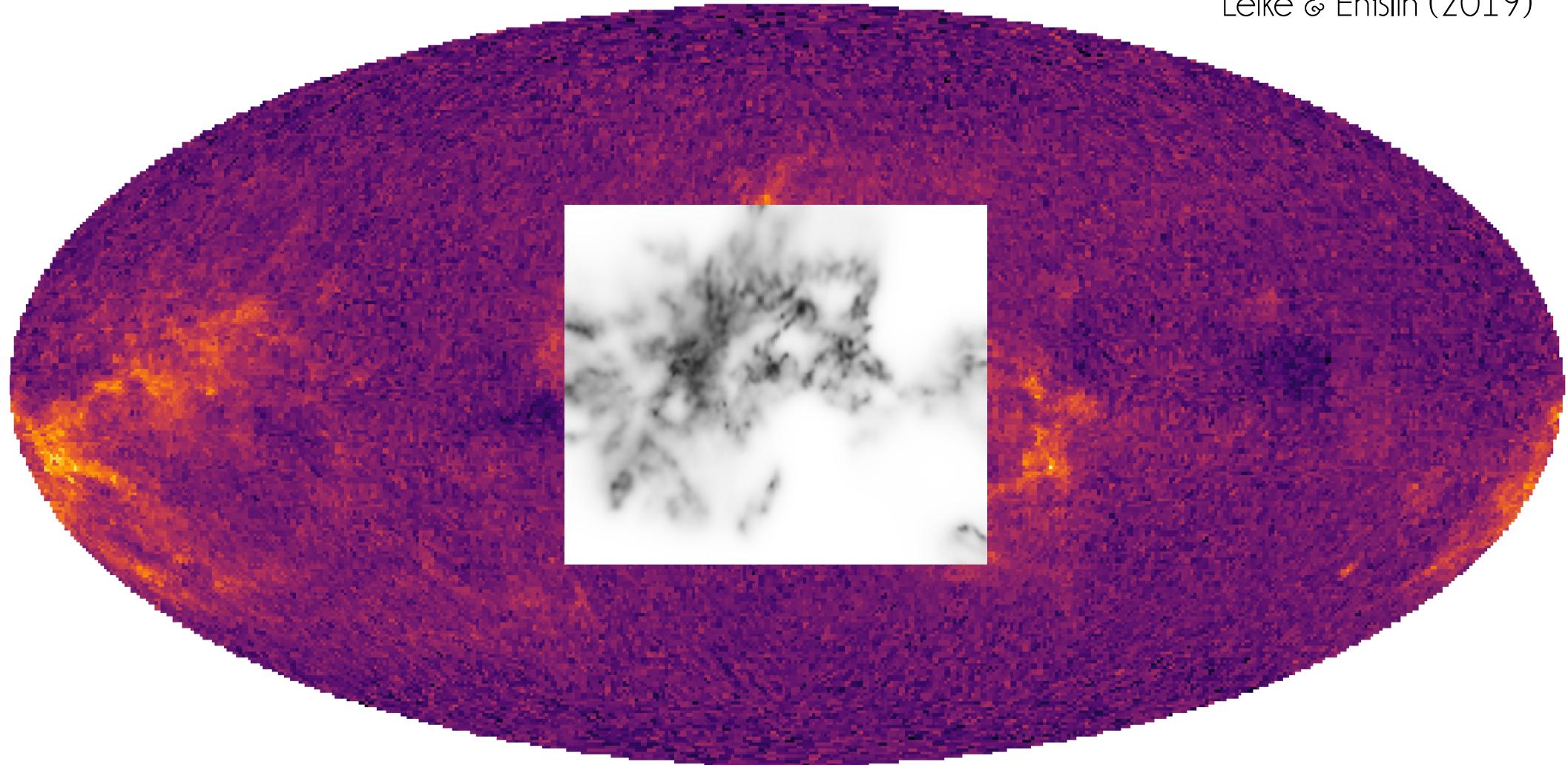
dust absorption by Gaia
Leike & Enßlin (2019)



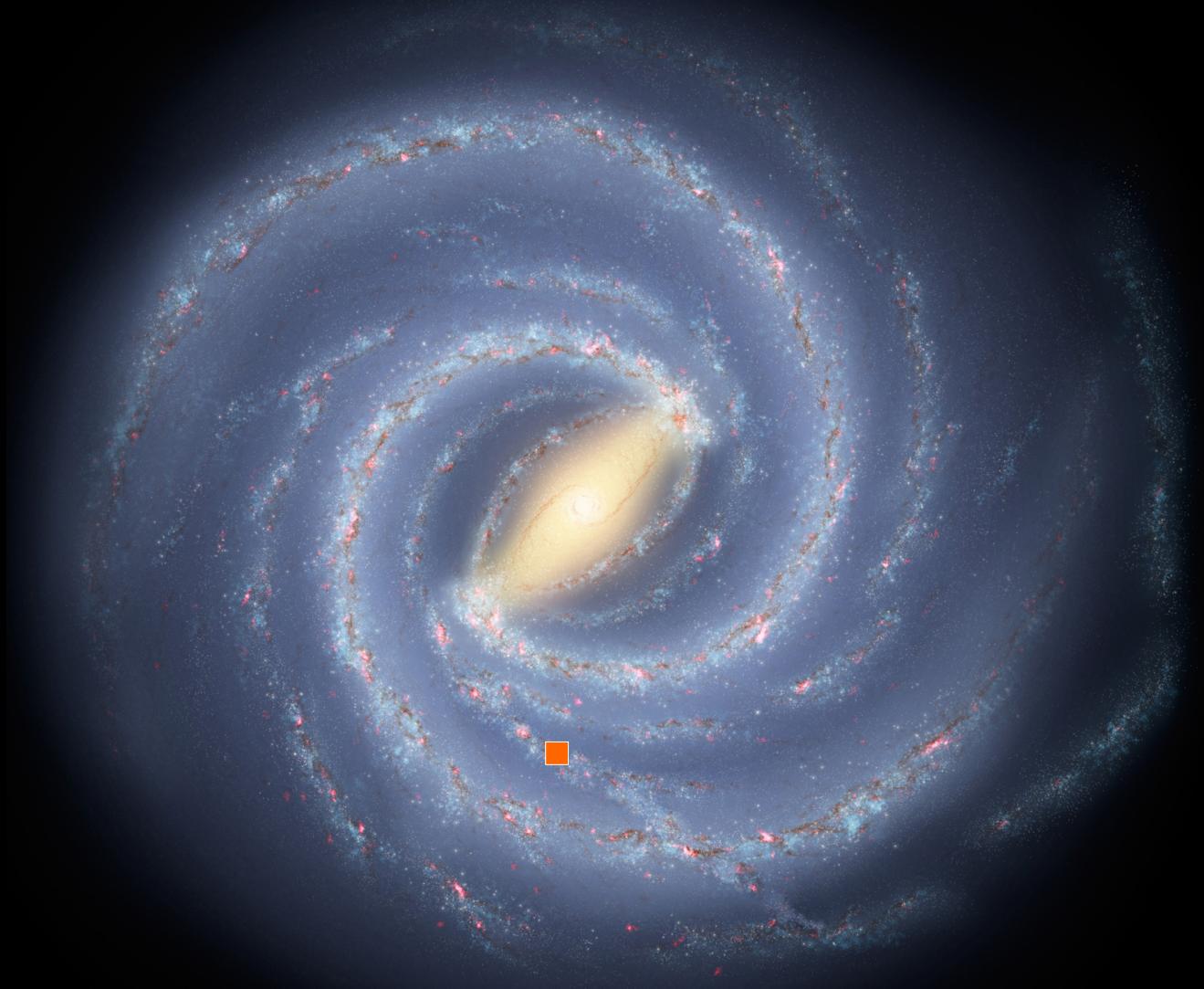
dust absorption by Gaia
Leike & Enßlin (2019)

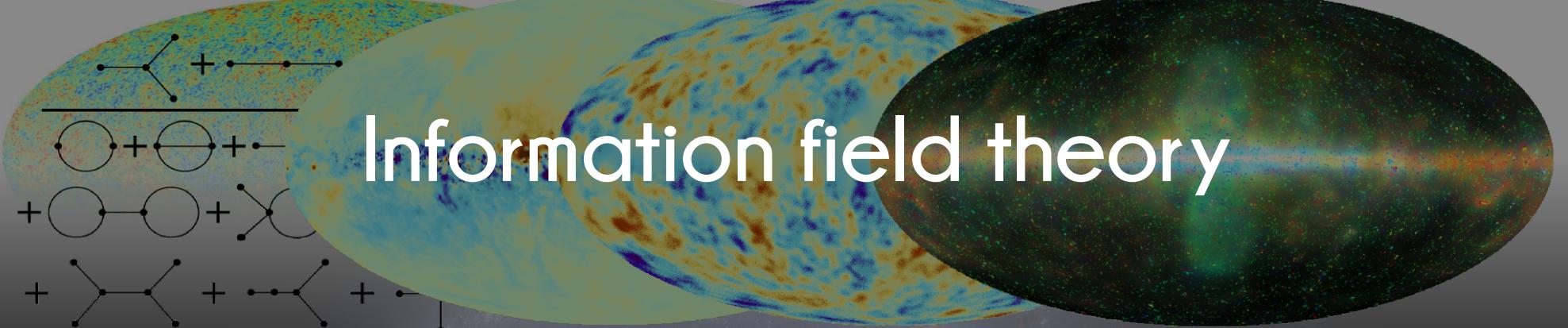


dust absorption by Gaia
Leike & Enßlin (2019)









Information field theory

Field inference

IFT = information theory for fields

IFT is fully Bayesian

IFT exploits & learns signal correlations & other properties

IFT fuses machine learning & human knowledge

NIFTy

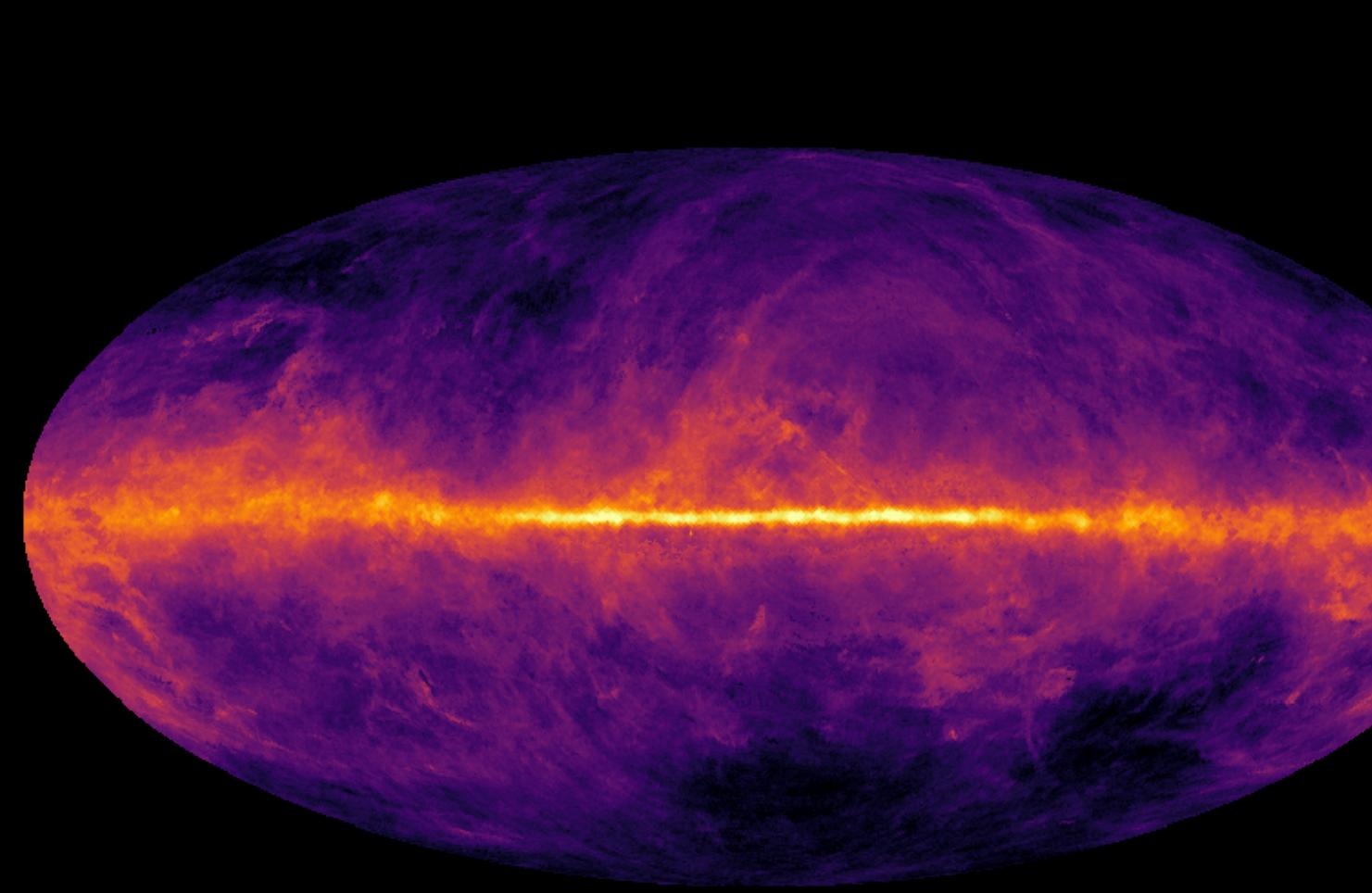
Numerical IFT

Reconstruction of signal fields over Cartesian and spherical spaces and products thereof

NIFTy algorithms are special purpose NN that do not require extra training

Unified imaging UBIK





Thank you!