NRAO An NSF Facility Pipelines!

National Radio Astronomy Observatory LORÁNT SJOUWERMAN

Associated Universities, Inc. Atacama Large Millimeter/submillimeter Array Karl G. Jansky Very Large Array Robert C. Byrd Green Bank Telescope

Very Long Baseline Array



<u>Aim</u>

- Radio interferometry data sets are becoming complex and huge, and increasingly cumbersome to deal with
- Pipelines are already being widely used to process (radio interferometry) data
- Pipelines save a lot of time, but each have their pro's and con's



Overview

- Pipelines (data reduction),
 - what and why?
 - principles!
 - what's out there?
- · CASA, AIPS, other pipelines
 - Example: ALMA pipeline by Liz Humphreys hereafter!
- · Design your own!
- · Cautionary notes



- Dictionary (noun)
 - 1] A long pipe, typically underground, for conveying oil, gas, etc. over long distances
 - 1.1] A channel or system supplying goods or information
 - 2] Computing: A linear sequence of specialized modules used for "processing"
 - 3] (In surfing) the hollow formed by the breaking of a very large wave



• Wikipedia.org (e.g.)

 Pipeline (computing), a chain of dataprocessing stages and/or processes

A pipeline is a set of data processing elements connected in series, where the output of one element is the input of the next one



- Observatories (support part):
 - Telescope data describing an observation, processed from its original state (...) to the form in which it is presented to the end user
 - Here: "raw"/archive data → observer



- Observatory directors:
 - Proposal →

 (observer/staff → telescope → staff)
 → "science ready images"
 - What are "science ready images"?
 - What about the resources?



 Pipelines are useful to process data in a consistent way, for procedures that are known or can be derived automatically

• Heuristics:



• Pipelines have a defined input or starting point, and a purpose or goal with a defined final data product or outcome

• Not always explicit ...



• A "pipeline" can be a simple few-line script, to a multi-purpose, flexible and complex data processing path with many different procedures, even a pipeline of pipelines, all depending on the goal



- Observatory perspective
- Observations → publications:
 - Telescopes are more and more complex
 - · Can collect a wealth of data
- Data reduction \rightarrow results, a bottle neck?
 - · Speed up or take away bumps
- Happy scientific community
 - Faster turn-around of effort
 - Ease of use → more/new observers



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- Also (observer perspective):
 - · Observatory generally best knows, e.g.,
 - What to flag as bad data
 - How to optimize calibration
 - · Observatory has the infrastructure
 - Pipeline can reduce data set size
 - · Allows for science instead of processing
- But note:
 - Science/result is domain of observer!



- Pipelines are good!
 - Provide consistent approach
 - Apply accumulated knowledge
 - Saves distraction from doing science
- However, every pipeline has its limitations
 - Make sure these are understood
 - Best effort approach



- Pipelines do what they are programmed to do and typically do it well and efficiently: take input, attempt goal, deliver product
- Ideally only use the information contained in the data, possibly with hooks for override Hooks should be for fine-tuning only, not for requiring human intervention to run



- Apply sequence of processes, each tuned with its own heuristics to achieve sub-goal
- Each sub-goal should be evaluated (QA) before attempting next step:
 → go/no-go
- Reporting is one of the key final products (e.g., log-file, progress plot, process timing)



- Main types of pipelines:
 - Observatory run pipelines
 - Push data to community
 - User run pipelines
 - (re)Process project
 - Private/personal pipelines ...
 - Any particular goal



- Observatory pipelines are run by staff, run on all eligible observations with a general goal and typically not well advertised or documented
- User pipelines are run by the user on a limited number of observations with a specific goal in a data reduction package and therefore usually better documented



- For example:
 - extract observation from archive
 - load into data reduction package
 - remove/flag bad data
 - calibrate instrument (dly, bp, pol, flx)
 - calibrate environment (d/dt)
 - apply total calibration
 - make images
 - deliver products to final destination each step/sub-goal has its heuristics/QA



- Quality of processing and QA more important than processing speed (24/7, future hardware upgrades)
- Partial run and/or (re)run with additional flagging, parameter override and other flexibility from a file or by hand should be built in from the start, not by many (hacked) versions of the code



- Pipelines can do all the nuisance and administration, be fine-tuned for the instrument and accumulated knowledge (heuristics), independent of science goal
 great for calibration
- Science goal for the imaging artwork (i.e., "science ready") typically needs some extra information not known to the pipeline
 limited to "reference images"



Pipelines in the field

- Many observatories have pipelines for a specialized observing mode and a specific deliverable for non-user projects
- Examples:
 - Sky surveys like NVSS
 - Sky monitors like LWA-TV
 - Piggy-back observations like VLITE
- · Code typically not publicly available

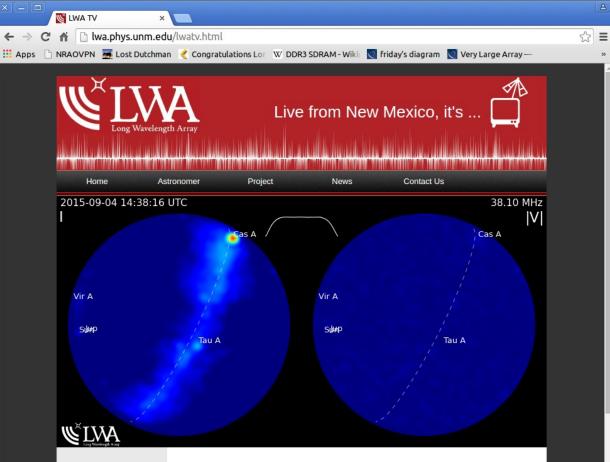


• Many obse specialized deliverable

• Examples:

- Sky - Sky - Pig • Code typi





LWA TV ... live!

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LWA TV

These images show the sky above the first LWA station. They update every few seconds, and they're typically about 30 seconds old. If the image isn't updating right now, it's probably because we are running beamformed observations, which we do for many hours every day. Check back again soon.

Each image shows the full sky, down to the horizon at the image's edge. Depending on the current operating mode of the LWA's Prototype All-Sky Imager experiment, there may be one or two images. If there is one, it shows the total intensity - the power coming from each point on the sky. If there are two, the left will show the total intensity, and the right will show the intensity of circularly polarized radio waves.

At the upper left you can see the average time of the data that went into the image (given in UTC, which is basically the same as Greenwich Mean Time). There is no time gap between the images: we are imaging sky in real time with a 100% duty cycle. At the upper right is the central frequency of the image. In the center is a 100 kHz bandwidth spectrum from a single antenna and polarization; the images are produced from the middle 75 kHz.

Finally, we've labeled the brightest objects in the sky: Cas A - a supernova remnant Vir A — a supergiant elliptical galaxy also known as M87 Tau A — the Crab Nebula, a supernova remnant Cyg A — a bright radio galaxy Jup - Jupiter, which only can be seen when it is bursting Sun - the Sun, which can become so bright that it wipes out everything else in the image! Dashed line - the plane of our galaxy

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- Observatory based pipelines for user data need to be more general due to the variety of observing projects, modes and strategies, and typically attempt flagging, calibration and "reference images"
- Examples:
 - EVN Calibration pipeline
 - VLA CASA scripted pipeline
 - ALMA pipeline
- Code, documentation "available" (support?)



The EVN Pipeline

Stephen Bourke, 27 Aug 2010

The EVN pipeline was originally developed by Cormac Reynolds, it is currently being developed by Stephen Bourke.

The main pipeline script is Sevn.py. It uses three Python modules:

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 calibra
- Examp

evn_aips_tasks.py: Shortcut functions for executing AIPS tasks with most parameters defaulted to sensible values for the EVN. Parameters which must be set are mentioned in the docstring at the beginning, e.g., try

>>> help(evn_aips_tasks.runlwpla)

- evn_funcs.py: Other functions used by evn.py. Mostly provide simplified interaction with functions in evn_aips_tasks.py.
- crfuncs.py: Generic functions used by evn.py. At the moment this is just a couple of filehandling classes to allow better logging of what the pipeline is doing.

The pipeline is driven by an input file. An example can be found here: 📄 template.txt

If you want to grab it all in one go, here's a gzipped tar: () pypeline-4.7.tar.gz

Usage

\$ ParselTongue EVN.py template.txt

• Code,

will run the pipeline using the given input file. A very brief guide to running the pipeline is available: pypeline_public.pdf. A description of the output of the pipeline is available at: http://www.evlbi.org/pipeline/pipe_desc.html. Any comments/questions on the pipeline should be directed to Stephen Bourke (Source@jive.nl) ← → C ⋒ 🗋 www.evlbi.org/pipeline/pipe_desc.html

EVN pipeline plots

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Site Navigation » Home Introduction **EVN User's Guide** Access to the EVN » EVN User Support » EVN Data Archive » Bologna Catalogue of EVN observations » e-VLBI » EVN Meetings » EVN TOG » EVN CBD > EVN PC » Contact » Publications » Newsletter » Image Gallery » Outreach » VLBI Links » Search

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• Examples:

strategies

calibration

Code

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Consortium for Very Long Baseline Interferometry in Europe



Description of the EVN Pipeline Feedback Pages

The following is a description of the plots and information that are available on the pipeline feedback page. The pipeline feedback for EVN user experiments can be obtained from the <u>EVN Data Archive</u> (choose experiment, select 'pipeline' and then select 'pipeline plots'). Further details are available from the <u>pipeline homepage</u>.

Please note that some plots may not be available for all experiments. Also, some of the plots will not be available for particular sources (e.g. dirty maps are not useful for bright sources and so are not shown, weak sources are not self-calibrated, etc.). In general, the plots of (u,v) data show all baselines to a single station only, and each AIPS IF is plotted separately.

General Comments. (Brief data summary and scan listing)

The JIVE support scientist responsible for pipelining the experiment will note here general particulars of the experiment. Also given are a brief summary of the data (scan listing, list of participating telescopes with their AIPS antenna table numbers, the number of visibilities on each baseline, etc.). Also given is the EVN Reliability Indicator, which gives an estimate of the ratio of observed (good) visibilities to the number of visibilities expected at scheduling time. ERI* is also given, and is the ERI modified to account for data lost due to the weather (or other 'acts of God'). Thus ERI* >= ERI.

Plots of the autocorrelations.

The autocorrelation against frequency. These plots use 22 minute or scan averages (whichever is smaller) and cover the whole experiment. They are useful for identifying RFI.

Plots of the uncalibrated amplitude and phase against time.

This shows the raw data averaged across each AIPS IF and plotted as a function of time for the whole experiment. Each AIPS IF is plotted separately. This can be used, for example, to determine times when stations were not producing data or to identify IFs with problems. Note that flags from telescope monitoring data (that flag data taken when antennas are off source) will have been applied. As the data have not yet been fringe-fitted some decorrelation is likely due to averaging across the IFs.

Plots of the uncalibrated amplitude and phase against frequency channel

Each plot shows a scan average. All scans are plotted (but only baselines to the reference antenna). Each channel is plotted so bandpass shapes and the sensitivity of different telescopes and IFs can be compared.

The uncalibrated amplitude and phase of the crosshand correlations against frequency channel.

If the cross polarizations (RL and LR) were correlated these are plotted here for information (no polarization calibration is done by the pipeline).

TSYS against time

A priori Tsys values as a function of time for all AIPS IFs.

Telescope sensitivities from the a priori TSYS and Gain curves

This is the result of combining the Tsys with the station gain curves. The units are square root of the SEFD (nominal values of the SEFD of EVN telescopes can be found on the <u>EVN status table</u>).

Fringe-fit phase solutions

The phase solutions produced by fringe-fitting the data for all telescopes and all AIPS IFs.

Fringe-fit delay solutions

Fringe-fit rate solutions

Telescope bandpasses

Note of the handhace (amplitude and phace) determined for each telecoope using the AIDS tack

European VLBI Network × ← → C f | archive.jive.nl/exp/GP051A_140612/pipe/gp051a.html

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EVN User Experiment Pipeline Feedback

Pipeline feedback for experiment GP051A. If you have any comments on this experiment please email the address below. A detailed description of the pipeline output is available.

Last updated: Wed Apr 8 11:51:31 CEST 2015 campbell@jive.nl

General Comments. (Brief data summary and scan listing)

GP051A had 18 good stations, 1 16MHz IFs, 2 polarizations, 8192 frequency points per IF/pol, and 0.35s integrations. Considerably more information is included in the experiment's cover letter on the standard-plots portion of the EVN Archive. The target scans were not included, either as a fringe-fit source nor as a phase-reference target. At the beginning of pipelining, the data were UVAVG ed down to 2s, and were AVSPC ed (for FRING only) down to 256 frequency points. The SOLINT was set to 1.0 minutes. Ef, then Yy, were used as the reference stations.

The EVN reliability indicator (ERI) for this experiment was ERI = 1.00 . ERI* = 1.00 . The ERI values pertain to only the EVN stations in the experiment, for which there were no losses.

Plots of the autocorrelations

Comments.

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• Examples:

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Each scan plotted separately, all stations. This plot seems not have been made (see instead the auto plots in the standard plots for representative passbands).

plots of the uncalibrated amplitude and phase against time

Full-experiment for Ef-* baselines, no calibration applied. A 1.0-minute plot-averaging was used.

Plots of the uncalibrated amplitude and phase against frequency channel

Comments.

Scalar averaged Ef-* baselines, each scan plotted separately. No calibration applied yet.

The uncalibrated amplitude and phase of the crosshand correlations against frequency channel (not available) Comments.

Scalar averaged Ef-* baselines showing LR, each scan plotted separately. No calibration applied yet.

TSYS against time Comments.

TY1 table, each IF/pol on a separate plot.

Telescope sensitivities from the a priori TSYS and Gain curves (the square of this number gives the antenna noise (SEFD) in Jy - the smaller the better). Comments.

Gain amplitude from CL2 table.

Fringe-fit phase solutions (including Parallactic Angle correction).

Pipelines in the field

- Observatory based pipelines for user data need to be more general due to the variety of observing projects, modes and strategies, and typically attempt flagging, calibration and "reference images"
- Examples:
 - EVN Calibration pipeline
 - VLA CASA scripted pipeline
 - ALMA pipeline
- Code, documentation "available" (support?)



← → C 🏠 🔒 https://science.nrao.edu/facilities/vla/data-processing/pipeline

Science

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• Examples:

• Code,

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Science				download after this	
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VLA Scripted Calibratio ×

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ripted Calibration Pipeline al Description calibration pipeline performs basic flagging and calibration using CASA. It is to work for Stokes I continuum data, but may work in other circumstances Starting with the D-configuration, Semester 2013A, it will be run ically at the completion of all astronomical scheduling blocks (SBs), and the calibration tables and flags are saved in the archive. The pipeline products quality assurance checks by NRAO staff, and investigators are notified when rated data are ready for download. The calibrated visibility data are retained for 15 days after the pipeline has completed, to enable investigators to ad and image at their home institution. Calibrated data can also be provided nominal time period, by re-generating the measurement set and applying ed calibration and flag tables. calibration pipeline runs on each completed SB separately; there is currently sion for it running on collections of SBs. The pipeline relies entirely on scan intents to be defined in each SB. In order for the pipeline to run fully on an SB it must contain, at minimum, scans with the following intents:

- 1. a flux density calibrator scan that observes one of the primary calibrators (this will also be used as the delay and bandpass calibrator if no bandpass or delay calibrator is defined)
- 2. complex gain calibrator scans.

The SB may also contain scans to be used specifically for bandpass and delay calibration, if desired. However, if multiple fields are defined as bandpass or delay

calibrators, only the first one will be used by the pipeline. Note that a single scan or field may have multiple intents specified. Scans intended to be used to set attenuators or requantizer gains should have scan intents of setup intent; they must not have scan intents that may result in their being used for calibration.

Facilities

In overview, the VLA calibration pipeline does the following:

- Loads the data into a CASA measurement set (MS), applies Hanning smoothing to them, and obtains information about the observing set-up from the MS
- Applies online flags and other deterministic flags (shadowed data, end channels of sub-bands, etc.)
- Prepares models for primary flux density calibrators
- Derives pre-determined calibrations (antenna position corrections, gain curves, atmospheric opacity corrections, requantizer gains, etc.)
- Iteratively determines initial delay and bandpass calibrations, including flagging of RFI and some automated identification of system problems
- Derives initial gain calibration, and derives the spectral index of the bandpass calibrator
- Derives final delay, bandpass, and gain calibrations, and applies them to the data

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- 2. Features and limitations 5. Applying Pipeline Calibration
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 - variable
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← → C f https://science.nrao.edu/facilities/vla/data-processing/pipeline

VLA Scripted Calibratio ×

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Running the Pipeline

Stokes I Continuum

To run the script on datasets that contain only continuum data (64 MHz or 128 MHz spectral windows):

1. Put your data (SDM-BDF or measurement set) in its own directory for processing. For example:

mkdir myVLAdata mv mySDM myVLAdata/ cd myVLAdata

2. Start casapy from myVLAdata (this is important — do not try to run the pipeline from a different directory by giving it the full path to a dataset, as some of the CASA tasks require the MS to be co-located with its associated gain tables; also, do not try to run the pipeline from inside the SDM-BDF or MS directories themselves). It is also important that a fresh instance of CASA is started from the directory that will contain the SDM-BDF and MS, rather than using an existing instance of CASA and using "d" to move to a new directory from within CASA, as the output plots will then end up in the wrong place and potentially overwrite your previous pipeline results.

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3. From the CASA prompt, type:

execfile('/home/mymachine/pipe_scripts/EVLA_pipeline.py')

- The pipeline will then prompt you for the SDM-BDF name; if you have only an MS, give it the root name of the MS (i.e., omit any '.ms').
- 5. The pipeline will then prompt you for whether or not you want to use Hanning smoothing (this can be important for strong, narrow-band RFI, but there are some situations where it is not desirable: for low frequencies in Aconfiguration it may increase bandwidth smearing, and for spectral line observations it will make the spectral resolution worse).
- 6. Go and make some coffee.
- The pipeline will automatically generate a QA2 score of Pass, Partial, or Fail for the pipeline as a whole and for each step along the way. For some basic help interpreting your QA2 score, please see our <u>QA2 interpretation page</u>.

Spectral Line Data

If your calibrators are strong enough that the heuristics in the VLA calibration pipeline will work on narrower bandwidths then some simple edits to the master EVLA_pipeline.py script is all that is needed in order for it to work on a spectral line datasate. In particular, you will want to comment out the call to flagdata() that is executing the flagging task with mode='rflag' in the EVLA_pipe_targetflag.py script. This runs the target through an algorithm that searches for and flags RFI (rflag), and may therefore remove your spectral line as well. You may also want to answer "n" to the Hanning smoothing option, and depending on the strength of your line, you may want to modify the inputs to "statwt" to exclude channels containing line emission.

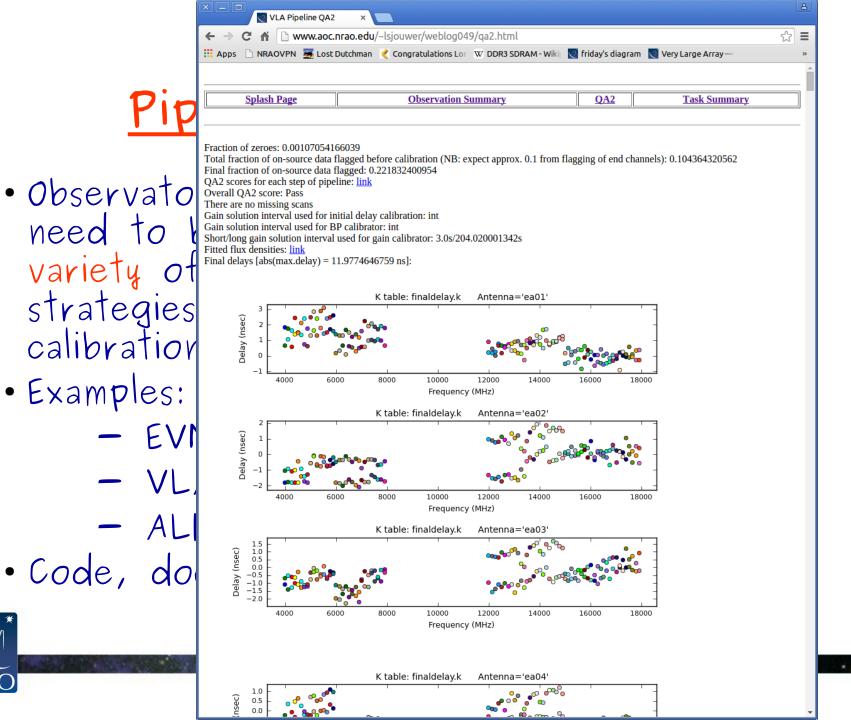
Mixed set-ups

In the case where a mixed continuum/spectral line set-up has been used, or multiple receiver bands have been observed, it may be the case that a single pipeline heuristic (e.g., gain calibration solution interval) is not appropriate for the entire dataset. In this case, the MS can be split by correlator set-up/receiver band (typically specified by selecting on spectral windows or scans) after applying the online flags, and the pipeline run on the split datasets individually. To do this:

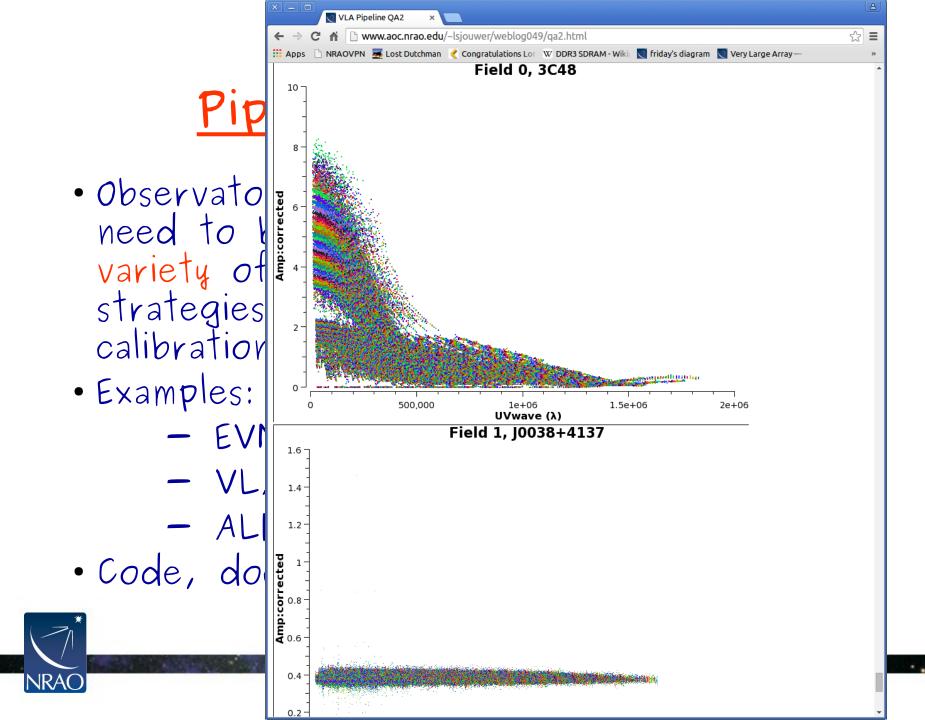
- 1. Copy a version of EVLA_pipeline.py into your local directory being used for data reduction
- 2. Edit EVLA_pipeline.py, commenting out all "execfile" calls *after* EVLA_pipe_flagall.py
- Run the pipeline on the full SDM-BDF/MS through EVLA_pipe_flagall.py, to apply all online flags. Include Hanning smooth at this point, if you are going to use it: execfile('EVLA_pipeline.py')
- Using the <SDMname>.listobs output, identify the groups of spws and/or scans to split (e.g., all spws associated with a particular observing band, or all spws with a particular spectral set-up)

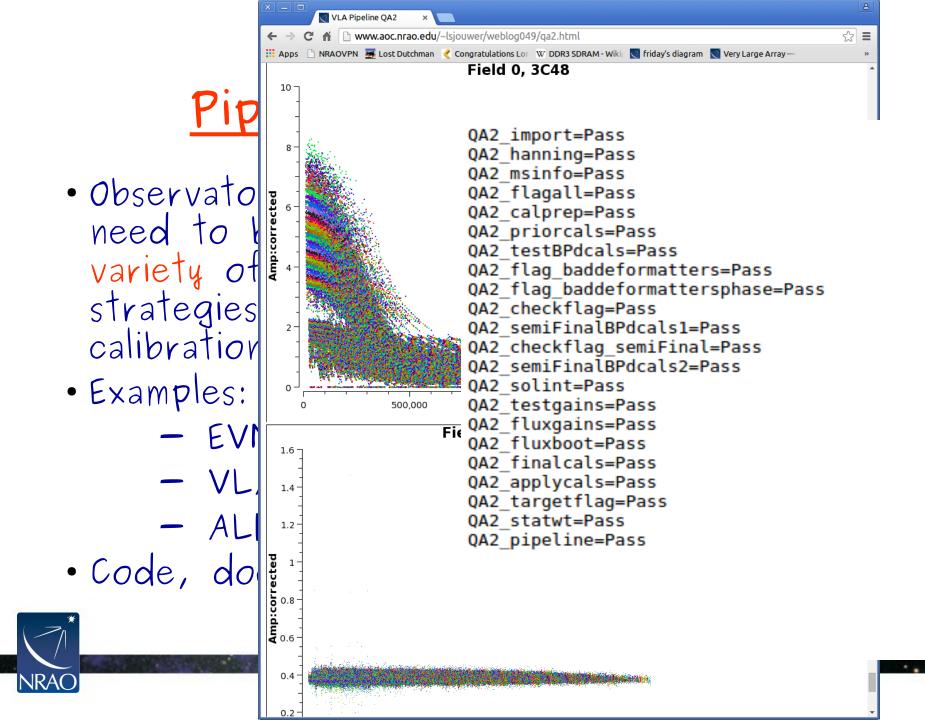
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 - VLA CASA scripted pipeline
 - ALMA pipeline Liz in a few...
- Code, documentation "available" (support?)



- Pipelines delivered as part of a data reduction package, like CASA and AIPS for a specific array or general use
- General examples in AIPS and CASA:
 - VLBAPIPE/VLBARUN in AIPS
 - VLARUN/DOOSRO/PIPEAIPS in AIPS
 - VLA pipeline in CASA
 - ALMA pipeline in CASA
- Code and documentation distributed with the package, and support is available.



File	e Edit View	Search Terminal Help	
	S 3: Adverbs		phase calibration to VLBA data ! Comments
	S 3: S 3: S 3:		e you MUST type RUN VLBAUTIL and define the procedures in AIPS.
	S 3: S 3: DATAIN	*all ' ' P -1	Load the data from disk Disk file name
	S 3: OUTNAME S 3: OUTDISK		Compress data? Use -1, 0 or 1 File name (name) Working disk with ample space
	S 3: S 3: INNAME S 3: INCLASS		OR existing file Input file name Input file class
• Pipelines delivered a	S 3: INSEQ S 3: INDISK S 3:	0 0	Input file sequence number Disk number for input file
koduction prokago	S 3: OPTYPE S 3:		For CONT, PSEU or SPEC (LINE)
	S 3: CLINT S 3: CHREFAN S 3: TIMERAN		CL table interval in minutes. Reference antenna NAME A good bandpass scan, or use
	S 3: INVER	Θ	scan# in TIMERANG(1)+rest=0 PC table to use -1 => don't use Pulse cals
• General examples in	S 3: CALSOUR	*all ' '	do manual phase cal List ALL Fring fit & CAL sour FIRST is bandpass calib
- VLBAPIPE/VL	S 3: SOURCES S 3: S 3: S 3: S 3: S 3: S 3: S 3: S 3	; *all ' '	ONLY FOR PHASE REFERENCING: Source *PAIRS* to calibrate START each pair with phase referencing calibrator, if 2nd='*': all non-CALSOUR are phase-referenced to 1st
	S 3: S 3: SOLINT S 3:	Θ	Time interval for fringe-fit
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– ALMA PIPEline 🏻	S 3: DOPLOT S 3:	Θ	<= 0 no plots;=1 some plots >1 huge number of plots
• Code and documenta	S 3: OUTFILE S 3: S 3: S 3: S 3:	: *all ' '	DIRECTORY FOR HTML AND PLOT FILES: if you want an html file with plots please set the dir where the html and plot files can be put.
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	euro AIPS (31DEC15) 12 04-SEP-2015 09:12:22 Page 1	
	Explanation of VLBARUN in AIPS version 31DEC15) V
	VLBARUN Type: Procedure	; 3
	Use: VLBARUN is the procedure that uses the VLBA calibration procedures	; 3
	(VLBAUTIL) to calibrate VLBA data. See the explain file for a detailed	; 3
	description of the procedure. Simple visibility flagging, bandpass calibration, and	; 3
	ionospheric (total electron content) corrections are applied before	; 3
	fringe fitting and averaging. It may attempt to self-cal the	; 3
	calibrators and will image the targets.	; 3
	NOTE: currently this procedure is intended for simple experiments!	; 3
		; 3
	\$; 3
	Type RUN VLBAUTIL and RUN VLBARUN to define the VLBARUN procedures.	; 3
		; 3
	The procedure is run by typing : (CO) VLBARUN	; 3
	The procedure will check the inputs (as far as it can) to avoid later interruptions, and then proceed directly, if the data is already on	; 3
	disk.	; 3
		; 3
	CLEAN STARTING CONDITIONS It is best to use one project per user number, as otherwise you may get	; 3
	into trouble if different projects use the same source names.	; 3
	It is not recommended to run two pipelines with the same user number	; 3
	simultaneously, nor overlapping at any time during the processes.	; 3
	Clean up all files resulting from previous attempts of running the	; 3
	procedure, except for the original UVDATA and perhaps, when restarting	; 3
	a specific frequency-ID, also not the F(X)POL files. When restarting	; 3
	from disk, make sure the UV data has no extra SN, CL, FG etc tables. Use the procedure P_RESTART (which is defined in VLBARUN) to do this.	; 3
		; 3
	If you wish to flag some additional data (because the procedure did	; 3
	not flag all the bad data automatically), make sure you put the flags in FG table number 1.	; 3
		; 3
	If you have any antennas that do not have Tsys or Gain curves missing	; 3
	from the data, please load them with ANTAB into TY and GC tables #1.	; 3
	It is a VERY good idea to run TASAV before you do this to keep the	; 3
	original TY, GC, BL and also FG tables number 1 in case of disasters.	; 3
	Make sure there is enough disk space available on OUTDISK, about 4 to	; 3
	5 times the expected compressed UVDATA set. For spectral line probably	; 3
	you need much more because it will make spectral line image cubes.	; 3
		; 3
	DATAIN48-character name of the disk file from which to read a	; 3
	FITS file. It must be in the form	; 3
	<logical>:<file name=""> or</file></logical>	; 3
	<pre>on</pre>	; 3
	where <node> is the remote computer name, <logical> is the</logical></node>	; 3
	environment variable (logical name) for the disk area in which the file named <file name=""> is stored. <node> is</node></file>	; 3
/	usually omitted when the file is local to the current	د ,
	computer. If DATAIN is not found, the task will try	
	DATAIN with the character 1 appended. Beginning 2003-Oct-16 FITLD can read more than one disk	
R	file at a time. In that case, they must all have the	
`	same name except that the last letter(s) are the	
	AIPS 3: ** press RETURN for more, enter Q or next line to quit print **	

Ed	lit View S	earch Termina	l Help	
	barun			
				hase calibration to VLBA data !
		Values		Comments
3 3:				
3:		To sup this		YOU MUST THESE BUILD VI PAUTTI and
33: 33:				you MUST type RUN VLBAUTIL and define the procedures in AIPS.
33:		KUN VEBANU		ler the the procedures th AIPS.
33:				Load the data from disk
	DATAIN	*all ' '		Disk file name
3 3:	DOUVCOMP	- 1		Compress data? Use -1, 0 or 1
3 3:	OUTNAME			File name (name)
	OUTDISK	1		Working disk with ample space
3-3:				OR existing file
	INNAME			Input file name
	INCLASS			Input file class
	INSEQ INDISK	0 0		Input file sequence number Disk pumber for ipput file
3 3: 3 3:		0		Disk number for input file
	OPTYPE			For CONT, PSEU or SPEC (LINE)
3:				
	CLINT	0		CL table interval in minutes.
3 3:	CHREFANT			Reference antenna NAME
	TIMERANG	*all 0		A good bandpass scan, or use
3 3:				scan# in TIMERANG(1)+rest=0
	INVER	Θ		PC table to use
3:				-1 => don't use Pulse cals
3:		*-11 ! !		do manual phase cal
) 3: } 3:		*all ' '		List ALL Fring fit & CAL sour FIRST is bandpass calib
33:		*all ' '		ONLY FOR PHASE REFERENCING:
33:	SUGREES			Source *PAIRS* to calibrate
3 3:				START each pair with phase
3 3:				referencing calibrator, if
3 3:				2nd='*': all non-CALSOUR
3 B:				are phase-referenced to 1st
3:				
3:	SOLINT	0		Time interval for fringe-fit
33: 33:	IMSIZE	Θ	Θ	Image size for target SOURCES
33:	INSIZE	0	0	Image size for target SOURCES =-1 for no images
	FACTOR	Θ		CALSOUR IMSIZE (FACTOR×128)
3 3:				
3 3:		Hint: when	setting dir	ectory and e-mail lower-case
3 3:		letters ca	n be retaine	ed by NOT using the close quote.
3:	DOPLOT	Θ		<= 0 no plots;=1 some plots
3:				>1 huge number of plots
3:	OUTFILE	*all ' '		DIRECTORY FOR HTML AND PLOT
3:				FILES: if you want an html
3 3: 3 3:				file with plots please set the dir where the html and
33:				plot files can be put.
	OUTTEXT	*all ' '		E-MAIL ADDRESS: if you want
3 3:				an e-mail when the script
3 3:				is complete, set the
3 3:				address here.
3 3:	BADDISK	*all 0		Disks to avoid for scratch

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F	File Edit View Se	earch Terminal Help	
	inp pipeaips	Annual and the first of F	
	IPS 3: PIPEAIPS: IPS 3: Adverbs	Values	or conn. elem. interferometers Comments
	IPS 3: IPS 3:		
Α.	IPS 3:	** Type RUN PIPEAIPS to	load this procedure **
	IPS 3: IPS 3: WORKDISK	Θ	Working disk, thus in/outdisk
	IPS 3: CATNUM	Ō	Catalog number of the UV-file
	IPS 3: INNAME IPS 3: INCLASS		Input UV file name (CATNUM<1) Input UV file class(CATNUM<1)
	IPS 3: INSEQ	Θ	Input UV file seq. (CATNUM<1)
	IPS 3: TINT	Θ	Re-average visibilities (sec)
Α.	IPS 3: IPS 3: FASTSW IPS 3:	Θ	or corr.avg. time if known > 0 Correct fast-sw source names
	IPS 3: VLANTCOR	0	Run VLANT? Only do once!
• Pipelines delivered a	IPS 3: AUTOFLAG IPS 3:	Θ	Level of automatic flags used < 0: no automatic flagging.
	IPS 3:		= 0: default FLAGR
	IPS 3: IPS 3: PHAINT	Θ	= 1: flag beginning of scans phase solution interval (min)
reduction Dackage, I	IPS 3: AMPINT	õ	ampl. solution interval (min)
	IPS 3: BASEBAND	Θ	Data has N equal basebands:
	IPS 3: IPS 3: BPNORM	0	see help and FRING aparm(5) Bandpass 'divide-by' control
IUN a specific array	IPS 3:		see help, BPASS bpassprm(5)
	IPS 3: REFANT IPS 3: DOMODEL	0 - 1	Reference antenna number > 0 Use standard flux
	IPS 3: DOMODEL	-1	calibrator models
UCHERAL EXAMPLES IN	IPS 3:		Note that most standard flux
	IPS 3: IPS 3:		calibrators have models but the absence of a model will
	IPS 3:		make this CRASH. (see HELP)
	IPS 3: UVRANGE IPS 3:	0 0	UV range for flux calibrator
	IPS 3:	** use next 2 lines if i	(may be used if no model) flux calib. is NOT standard **
	IPS 3: AMPCAL		Alternative flux calib. name
	IPS 3: FLUX IPS 3: PHACAL	0 *all ' '	Flux calib. total flux dens. Phase calibrators
	IPS 3:	5	'*' = any CALCODE (continuum)
	IPS 3: IPS 3: BNDCAL	*all ' '	All others are your targets
	IPS 3: BNDCAL		Bandpass calibrators (max 5) > 0 no pause after GETJY
	IPS 3: AUTOPLOT	0	> 0 make diagnostic plots
- ALMA pipolino	IPS 3: IPS 3: DOTMACES	<pre>** the following lines - 0</pre>	are for auto-imaging ** > 0 apply calibration and
- ALMA pipeline	IPS 3: DOIMAGES IPS 3:	, , , , , , , , , , , , , , , , , , ,	image
A	IPS 3: IMGTYPE		'CONT', 'PSEU', or 'LINE' for
· Codo and dooumont	IPS 3: IPS 3:		continuum (single image), pseudo cont (image per IF)
 Code and documental 	IPS 3:		or line (full image cube)
	IPS 3: ARRYSIZE IPS 3:	Θ	Max baseline in kilometers = 0 let procedure find array
The package, and su	IPS 3: IMSIZE	0 0	Square size of image (pixels)
	IPS 3: NITER IPS 3:	Θ	Max number of iterations/chan
	IPS 3: IPS 3: CUTOFF	0	= 0 recommended for LINE Clean threshold (Jy)
	IPS 3: ALLIMG	0	> 0 also image continuum
	IPS 3: IPS 3:		calibrators > 1 line calibrators too
	IPS 3: DOEVAUV	0	Only for IMGTYPE='PSEU' and
	IPS 3: IPS 3:	** interactive self cal	if > 0 then run 'EVAUV' too
			or next line to quit print **

#

File	Edit	View	Search	Terminal	Help					
	natio			C15) PS in AIR				09:13:10	Page	1
	PIPE cali incl	ibrati luding	is a pr .on and phigh f	imaging	of line y data.	e and	quick and d continu ll polari;			
NOTE :	То 1 То 1	load t (t > RES > RUN > COM > COM review > TAS	he proc his is TORE 0 PIPEA PRESS inputs	cedure in only red (recomme IPS s type: AIPS';INF	nto AIPS quired (ended, r	S typ once		vLARUN/DOOSF	0 versio	ns

Adverbs

CATNUM, or all of INNAME, INCLASS, INSEQ (and WORKDISK for both): The catalog number of the file to calibrate; for VLA data loaded with BDF2AIPS this would be UVEVLA for a yet unprocessed file. Add flagging info on missing receivers, etc., already here in FG1. PIPEAIPS converts this into a SPLAT0/SPLATL pair to keep the data in spectral window form but also using a channel 0 for speed. If a a first instance of PIPEAIPS has run, the 'SPLAT0' should be chosen. If INNAME etc are used, then set CATNUM to a non-positive value (<=0) i.e. CATNUM=0; GETNAME <catno> Do not use both CATNUM and IN<*>

TINT:

Some (VLA) data sets have unnecessary short (i.e., 1 sec) visibility integrations. Set this to a larger value (>=1, typically an integer multiple of the original correlator integration interval) to decrease the data size by this factor. Leave zero to do no averaging, though if the correlator averaging time is known, setting it to that interval (in sec) will take out the guess work in finding a value from the data.

FASTSW:

Sometimes, with fast-switching, single calibrator may have more than one name. Set FASTSW positive to check the positions (closer than 3 mas in R.A. and DEC.), qualifier and calcode. If sources have the same position, PIPEAIPS will rename them all with the shortest name. This will prevent multiple images of the same source. Up to 100 source names can be modified.

VLANTCOR

Skip running VLANT if < 0 or for an input file with class 'UVLANT' or for an input file with class 'SPLAT*' (i.e. 'SPLAT0' and 'SPLATL'). VLANT should be run only once so set negative if you know it was run. If set to 0, the pipeline runs VLANT and will change the class of the input file (e.g. 'UVEVLA' or 'UVDATA') to 'UVLANT' and thus skip it on successive runs of PIPEAIPS.

AUTOFLAG:

< 0 -> no automated flagging.

NOTE: if an FG table is detected, it WILL NOT DO any form of automated flagging on the data. You may not want to do autoflagging when you have very short scans (i.e. in fast-switching mode) and flag by hand. The highest FG-table is always kept.

0 -> Perform FLAGR (OPTYPE'TIME') on the raw multi-source data set PIPEAIPS estimates the integration time and SOLINT, in FLAGR, is set

AIPS 3: ** press RETURN for more, enter Q or next line to quit print ** .

Ed	lit View Se	earch Termina	al Help	
) pi	peaips			
				or conn. elem. interferometers
		Values		Comments
3:				
3:		** T DI		
3: 3:		** Type Ru	JN PIPEAIPS to	load this procedure **
	WORKDISK	Θ		Working disk, thus in/outdisk
	CATNUM	õ		Catalog number of the UV-file
	INNAME			Input UV file name (CATNUM<1)
	INCLASS			Input UV file class(CATNUM<1)
	INSEQ	Θ		Input UV file seq. (CATNUM<1)
3:	TINT	Θ		Re-average visibilities (sec)
3:				or corr.avg. time if known
	FASTSW	Θ		> 0 Correct fast-sw source
3:	VLANTCOR	0		names Rup VIANT2 Oply de opcel
	AUTOFLAG	0		Run VLANT? Only do once! Level of automatic flags used
3:		v		< 0: no automatic flagging.
3:				= 0: default FLAGR
3:				= 1: flag beginning of scans
	PHAINT	Θ		phase solution interval (min)
3:	AMPINT	Θ		ampl. solution interval (min)
	BASEBAND	Θ		Data has N equal basebands:
3:				see help and FRING aparm(5)
	BPNORM	Θ		Bandpass 'divide-by' control
3:		<u>^</u>		see help, BPASS bpassprm(5)
	REFANT DOMODEL	0 - 1		Reference antenna number > 0 Use standard flux
33:		- 1		calibrator models
3:				Note that most standard flux
3:				calibrators have models but
3:				the absence of a model will
3:				make this CRASH. (see HELP)
	UVRANGE	Θ	Θ	UV range for flux calibrator
3:		**		(may be used if no model)
3:	AMPCAL	•• use ne>	ct 2 times tr	flux calib. is NOT standard ** Alternative flux calib. name
	FLUX	Θ		Flux calib. total flux dens.
	PHACAL	*all ' '		Phase calibrators
3:				<pre>'*' = any CALCODE (continuum)</pre>
3:				All others are your targets
	BNDCAL	*all ' '		Bandpass calibrators (max 5)
	NOPAUSE	0		> 0 no pause after GETJY
	AUTOPLOT	U	1	> 0 make diagnostic plots
3:	DOIMAGES		llowing lines	are for auto-imaging ** > 0 apply calibration and
3:		v		image
	IMGTYPE			'CONT', 'PSEU', or 'LINE' for
3:				continuum (single image),
3:				pseudo cont (image per IF)
3:				or line (full image cube)
	ARRYSIZE	Θ		Max baseline in kilometers
3:		<u> </u>		= 0 let procedure find array
	IMSIZE NITER	0 0	U	Square size of image (pixels) Max number of iterations/chan
33:				= 0 recommended for LINE
	CUTOFF	Θ		Clean threshold (Jy)
	ALLIMG	Ø		> 0 also image continuum
3:				calibrators
3:				> 1 line calibrators too
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3: ** press RETURN for more, enter Q or next line to quit print **

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- Private user "pipelines"
 - May be modified versions from the previously mentioned general pipelines
 - Sometimes just a "copy/paste" script
 - For specific observations/project, may use inflexible hard-coded parameters
 - · Code may be useful for sharing

- e.g. VIPS, AIPSLite

• None, including observatory and package ones, handle polarization data well (yet)



CASA pipelines

- CASA relatively new package (well ...)
- Premier data reduction package for ALMA, officially also for current VLA
- Still under active development, but pipelines are being pushed as high priority for user (and operations)
- Python scriptable



CASA pipelines

- Examples:
 - VLA CASA Calibration pipeline
 In: VLA/archive data or ms
 Aim: RFI flagging, full calibration
 Out: calibrated data, QA reports
 - ALMA pipeline
 - In: ALMA/archive data Aim: full calibration, "science ready / reference images" Out: calibrated data, "S.R." images, QA



AIPS pipelines

- Older (35yr), mature (still evolving) package
- Uses simple POPS interpreter
- Full suite of visibility and image analysis tasks supported
- Kludge for OS interactions (sh, csh)
- Hooks with Obit package (extra algorithms)
- ParselTongue: (deep-level python scripting)



AIPS pipelines

• Examples:

EVN Calibration pipeline In: EVN/archive data Aim: flagging, some self-calibration Out: crude 1st order maps, QA reports VLBARUN

In: user loaded flagged VLBI/A data Aim: full calibration Out: calibration to maps - user pipeline!



AIPS pipelines

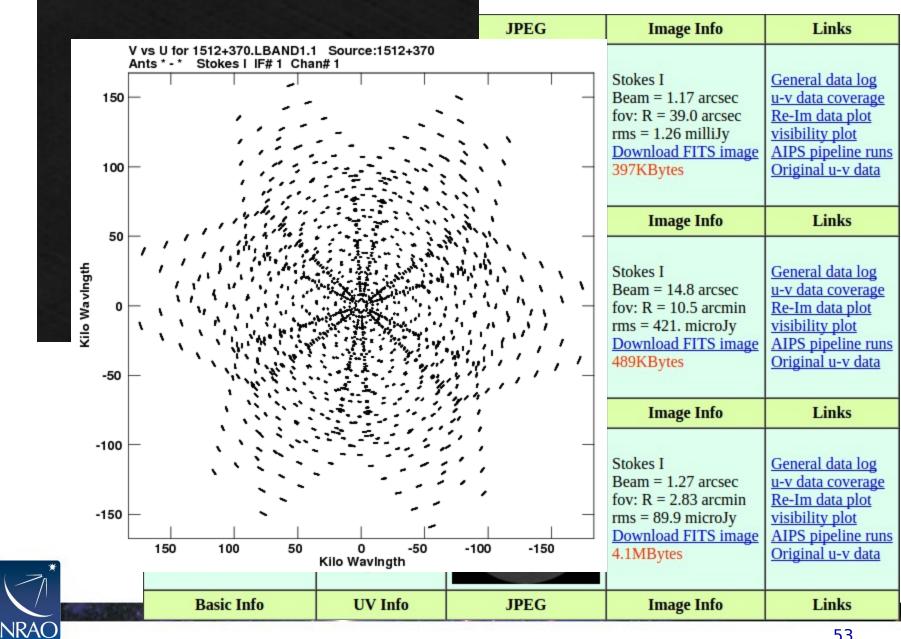
• End-to-end example: - NRAO VLA Archive Survey (NVAS): > 30 years of VLA archive > mixed bag of observing runs > user pipeline (VLARUN) > single input parameter (data set) > from archive to indexed web pages ! not infallible (simple flagging only) but good starting point for next step

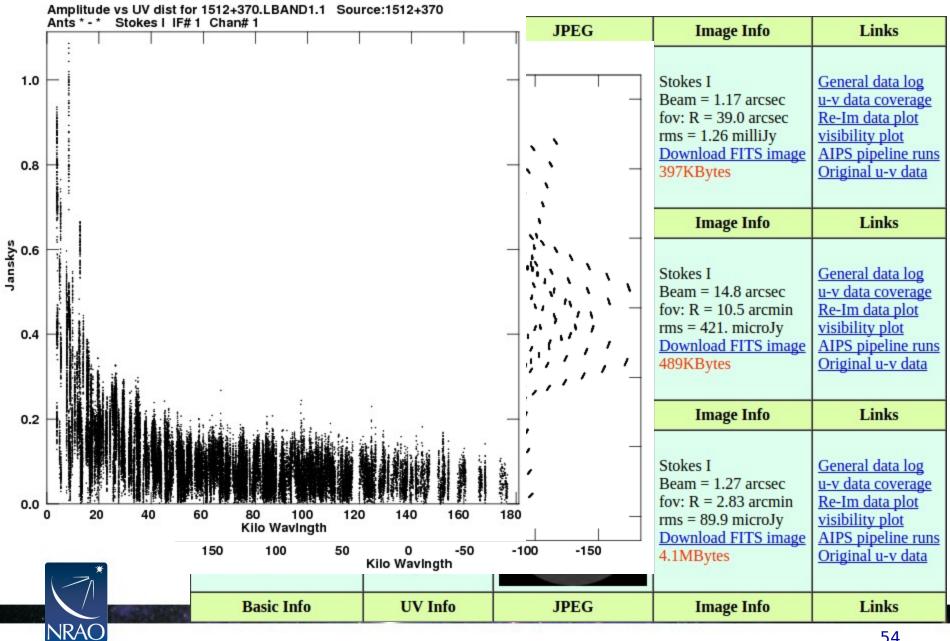


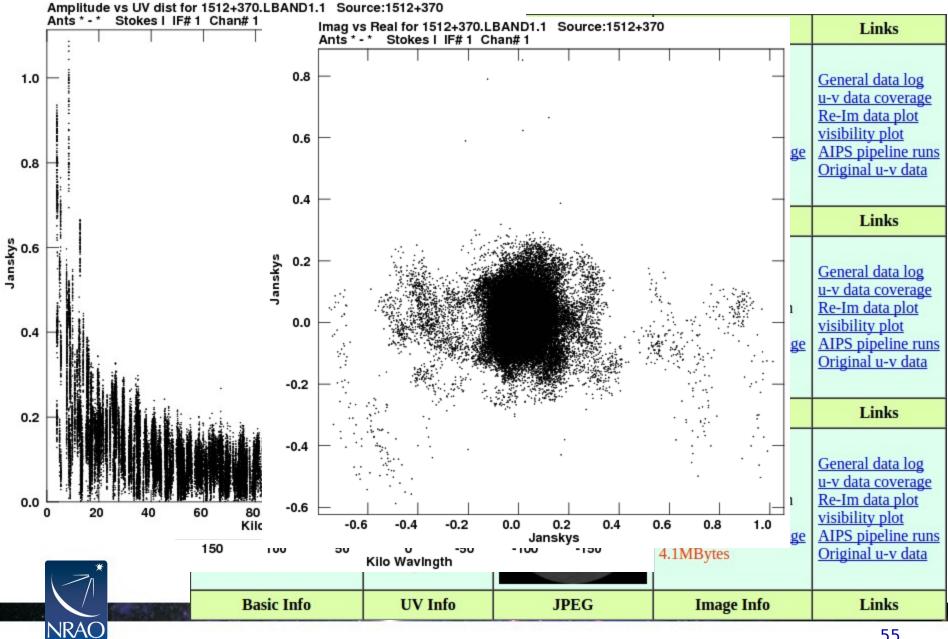
	Basic Info	UV Info	JPEG	Image Info	Links
(J2 1982 1.49	4m 0.0s 36d50'51" 000 image center) MAR 4 GHz (L-band) ion: 2009 Dec 09	Full polarization A/A configuration 27 antennas subarray 1 <u>Calibrated uv-</u> <u>FITS</u> 5.8MBytes	CONVESSION 2005 MUS-MEMO	Stokes I Beam = 1.17 arcsec fov: R = 39.0 arcsec rms = 1.26 milliJy <u>Download FITS image</u> 397KBytes	<u>General data log</u> <u>u-v data coverage</u> <u>Re-Im data plot</u> <u>visibility plot</u> <u>AIPS pipeline runs</u> <u>Original u-v data</u>
	Basic Info	UV Info	JPEG	Image Info	Links
(J2 1983 1.66	4m 0.0s 36d50'51" 000 image center) MAY 2 GHz (L-band) ion: 2009 Nov 01	Full polarization C/C configuration 27 antennas subarray 1 <u>Calibrated uv-</u> <u>FITS</u> 726KBytes	Conversion and	Stokes I Beam = 14.8 arcsec fov: R = 10.5 arcmin rms = 421. microJy Download FITS image 489KBytes	<u>General data log</u> <u>u-v data coverage</u> <u>Re-Im data plot</u> <u>visibility plot</u> <u>AIPS pipeline runs</u> <u>Original u-v data</u>
	Basic Info	UV Info	JPEG	Image Info	Links
(J2 1993 4.89	4m 0.0s 36d50'51" 000 image center) MAY 6 GHz (C-band) ion: 2007 Nov 17	Full polarization B/B configuration 27 antennas subarray 1 <u>Calibrated uv-</u> <u>FITS</u> 8.1MBytes		Stokes I Beam = 1.27 arcsec fov: R = 2.83 arcmin rms = 89.9 microJy <u>Download FITS image</u> 4.1MBytes	<u>General data log</u> <u>u-v data coverage</u> <u>Re-Im data plot</u> <u>visibility plot</u> <u>AIPS pipeline runs</u> <u>Original u-v data</u>
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		JPEG	Image Info	Links
1.00 GHz (L-band) Version: 2009 Nov 01	FITS 726KBytes		Stokes I Beam = 14.8 arcsec fov: R = 10.5 arcmin rms = 421. microJy Download FITS image 489KBytes	<u>General data log</u> <u>u-v data coverage</u> <u>Re-Im data plot</u> <u>visibility plot</u> <u>AIPS pipeline runs</u> <u>Original u-v data</u>
Basic Info	UV Info	JPEG	Image Info	Links
15h14m 0.0s 36d50'51" (J2000 image center) 1993 MAY 6 4.89 GHz (C-band) Version: 2007 Nov 17	Full polarization B/B configuration 27 antennas subarray 1 <u>Calibrated uv- FITS</u> 8.1MBytes		Stokes I Beam = 1.27 arcsec fov: R = 2.83 arcmin rms = 89.9 microJy Download FITS image 4.1MBytes	<u>General data log</u> <u>u-v data coverage</u> <u>Re-Im data plot</u> <u>visibility plot</u> <u>AIPS pipeline runs</u> <u>Original u-v data</u>
Basic Info	UV Info	JPEG	Image Info	Links







In summary:

- In practice pipelines (here) are similar in goal, but each which slightly different input and final data product
- Ask observatories for pipelines!
 → Documentation, use, pro's and con's...
- For end users/observers:
 - Does it do what I need it to do?
 - Are the data products acceptable?
 - What needs to be done further for my particular science goal?



- Typically starts out as digitally edited "log" to reduce repetitive typing
- Making it more flexible, e.g. by defining the gain calibrator name as a variable
- Grabbing information from the data, e.g. number of channels to do edge flagging
- Calculations, e.g. the pixel size from the maximum baseline in wavelengths
 - → sequence of instructions that needs less fiddling when applied to new data sets



- What should it be able to do?
 - Same observations done many times hard-coded copy/paste...
 - Same setup per source, many sources simple script (variables change)
 - Same source per setup, many setups complications... (frequency effects)
 - Everything including array configuration maximum flexibility!



- What is the starting point?
 - "Raw" data from the archive
 → modify the observatory pipeline?
 - Observatory pipeline products
 - Reference images
 - Other (manual?) processing
- What is the anticipated final product?
 - Determine success (versus "fail")



• Method:

Define sequence of steps In->Goal->Out Decide what can be automated: - simple but repetitive actions - when keeping track is important Where to put stopping points - pause for inspection checks - manually adjust/require input • Formalize when each step is done & OK - go/no-go decisions

- report results/plots in each step



Perspectives and expectations

- Observatories want their users to publish and will help to achieve this: provide pipelines and infrastructure for data reduction; you focus on the science
- New capabilities and insight, new heuristics: pipelines remain under development
- Because of the general approach, you need to decide whether the product is sufficient Products are on best effort basis



Caution:

- Pipelines can only do what they are designed to do
- Pipelines cannot correct for bad observing conditions (rfi, weather, hardware, observing strategy/errors)
- Be aware of each pipeline's limitations (designer should expose these)



Caution:

- Pipelines are great, but typically are not tuned to your science requirements!
 May do a good job, but you might do better with the proper investment
- Reprocessing might be an option (or not)
- Observations should ideally be set up with pipeline processing in mind
 Probably best to keep it simple



<u>Aim</u>

- Radio interferometry data sets are becoming complex and huge, and increasingly cumbersome to deal with
- Pipelines are already being widely used to process (radio interferometry) data
- Pipelines save a lot of time, but each have their pro's and con's

