

What is this radio interferometry business anyway?

What are you letting yourself in for?



EUROPEAN ARC
ALMA Regional Centre || UK

What is useful to know

- Basics of interferometry
- Calibration
- Imaging principles
- What provides detectable sources?
 - ALMA spatial coverage
 - Spectral details: see OT session
- Simulations for ALMA

What is useful to know

- Basics of interferometry
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- Imaging principles
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 - Spectral details: see OT session
- Simulations for ALMA

sim•u•late ('sim yə,leɪt)

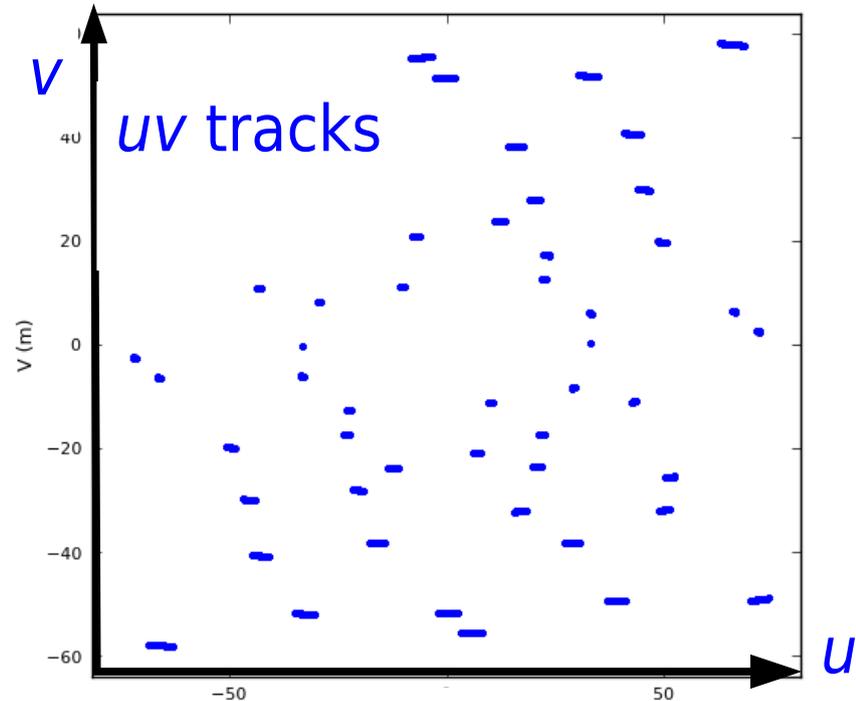
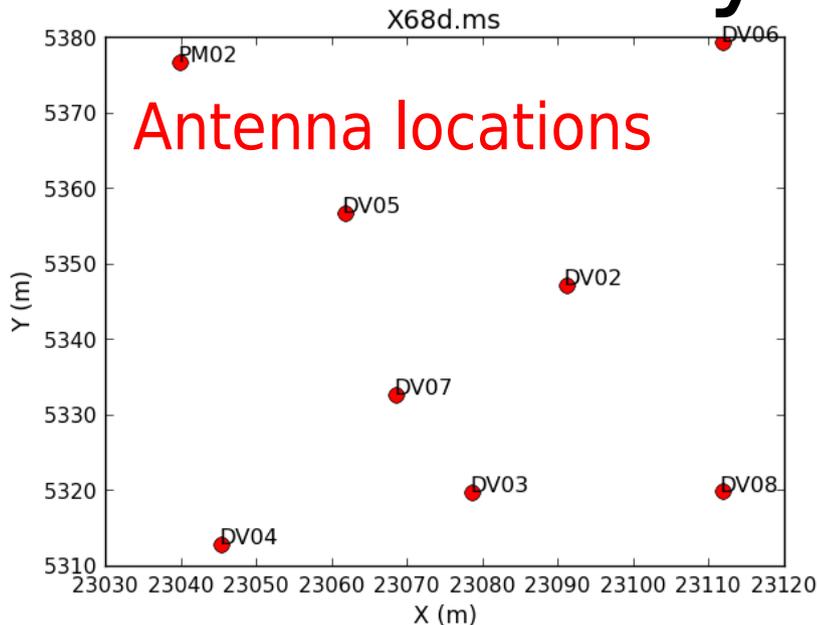
to intend to deceive; make a pretence of; feign:

e.g. to simulate illness:

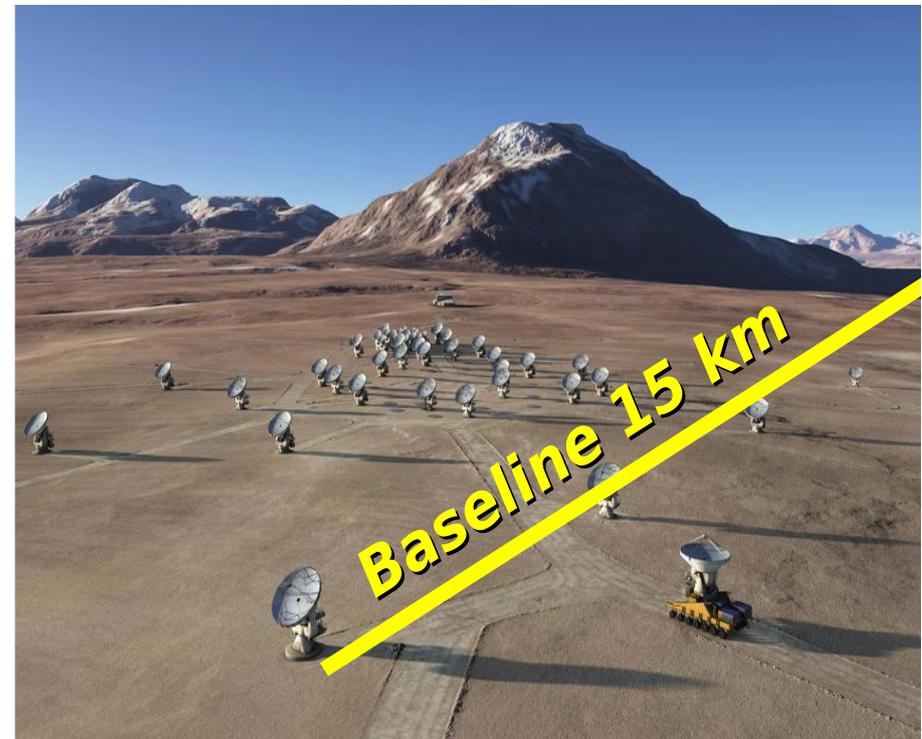
Friquet under the pretext of having a swollen face which he had managed to simulate by introducing a handful of cherry kernels into one side of his mouth, and had procured a whole holiday from Bazin.
Twenty years after (Alexandre Dumas)



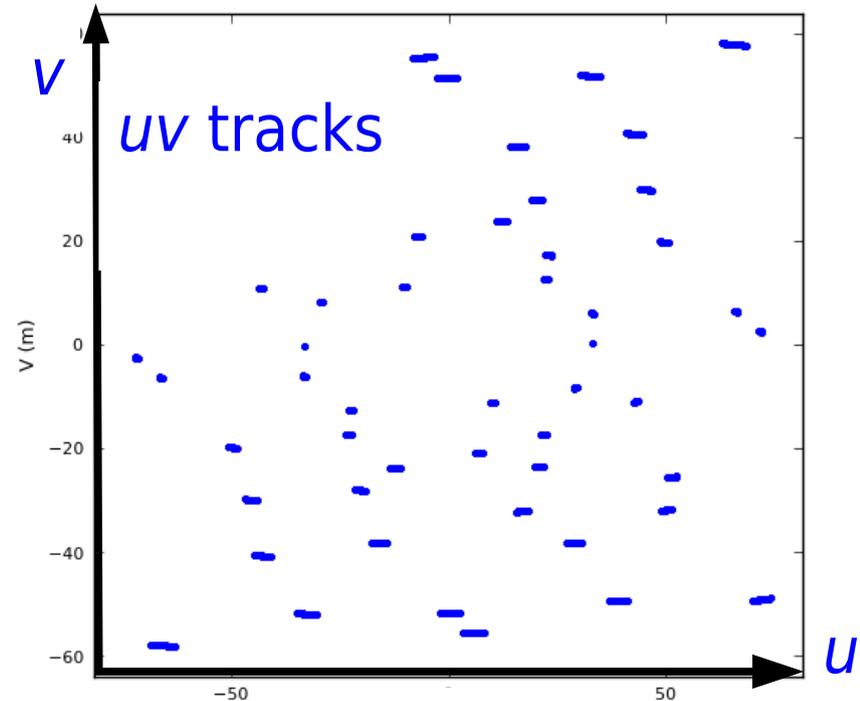
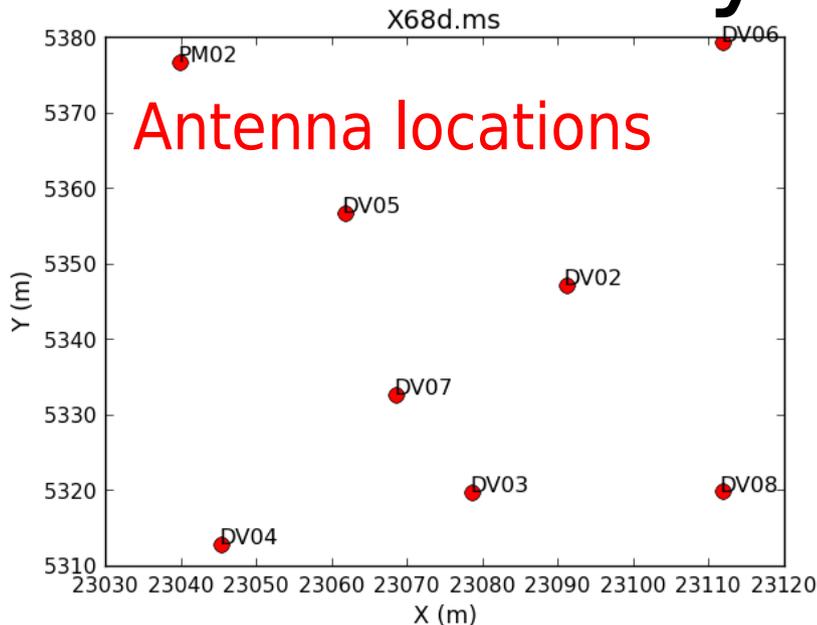
Interferometry



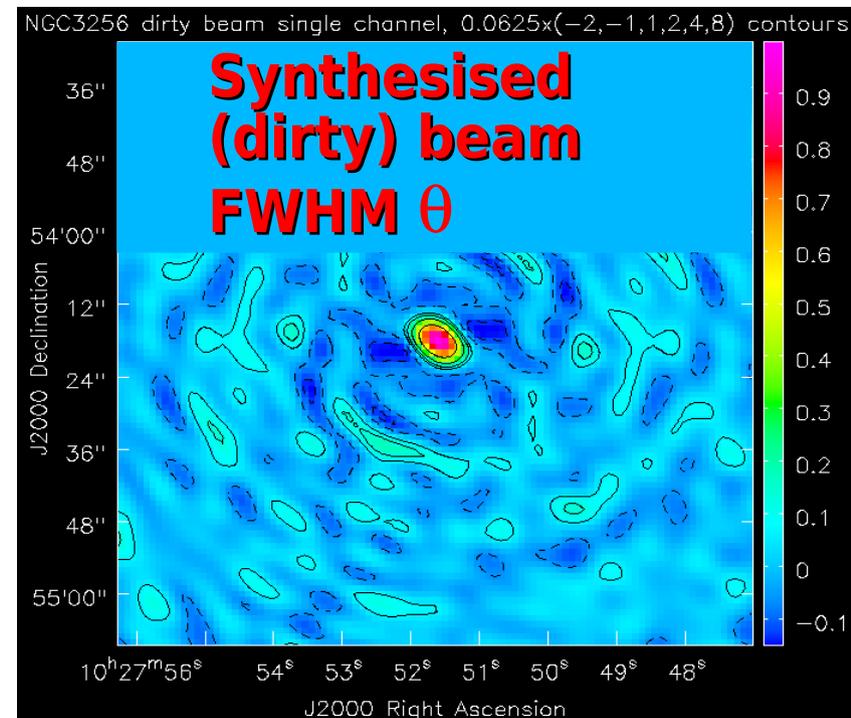
- Earth rotation aperture synthesis
- Vectors between pairs of baselines sweep out uv tracks
 - Record combined signals per sec
- Maximum resolution (synthesised beam) $\theta \sim \lambda / B_{\max}$
 - B 15 km, λ 1 mm = $\theta \sim 14$ mas
- Field of view $\lambda / D_{\text{antenna}} \sim 20''$
 - Equivalent to single dish resolution



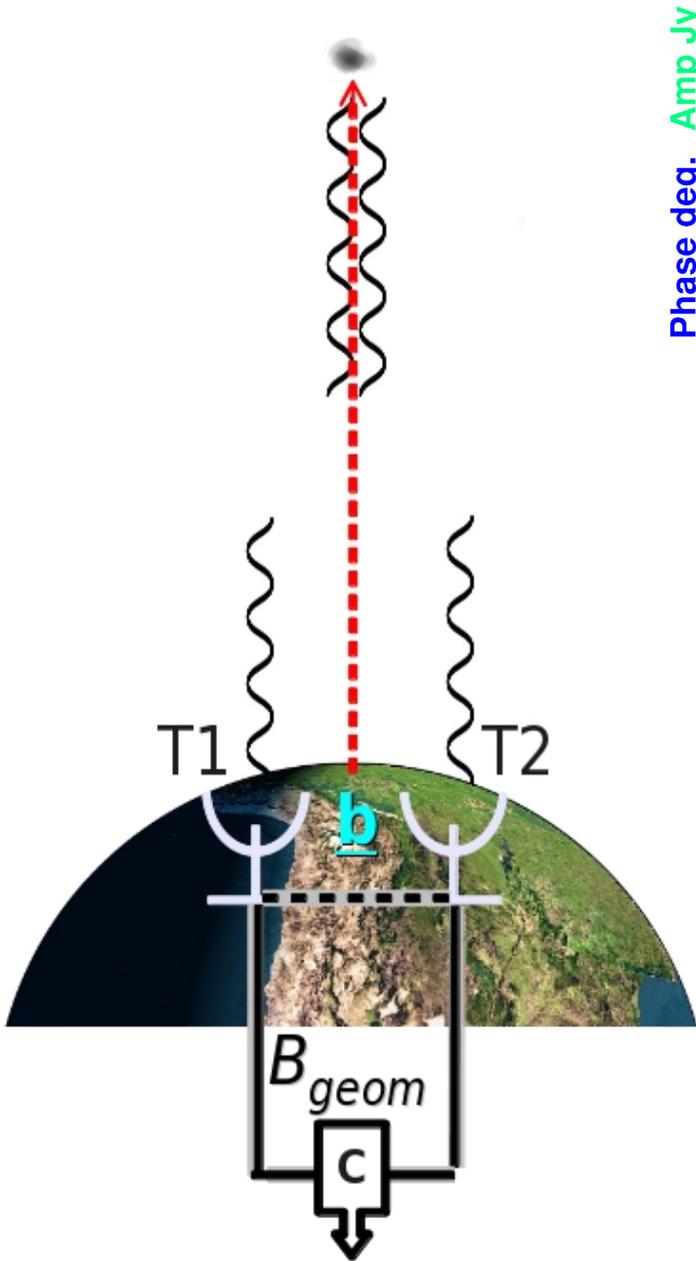
Interferometry



- Earth rotation aperture synthesis
 - Fourier transform \Leftrightarrow Dirty Beam
- Sensitivity helped as noise decorrelates *but*
 - Sparse coverage gives sidelobes
- Max. angular scale imageable
 - $\sim 0.6 \lambda / B_{\min} \sim 8''$ (λ 1 mm)
 - no ACA, compact 12-m config

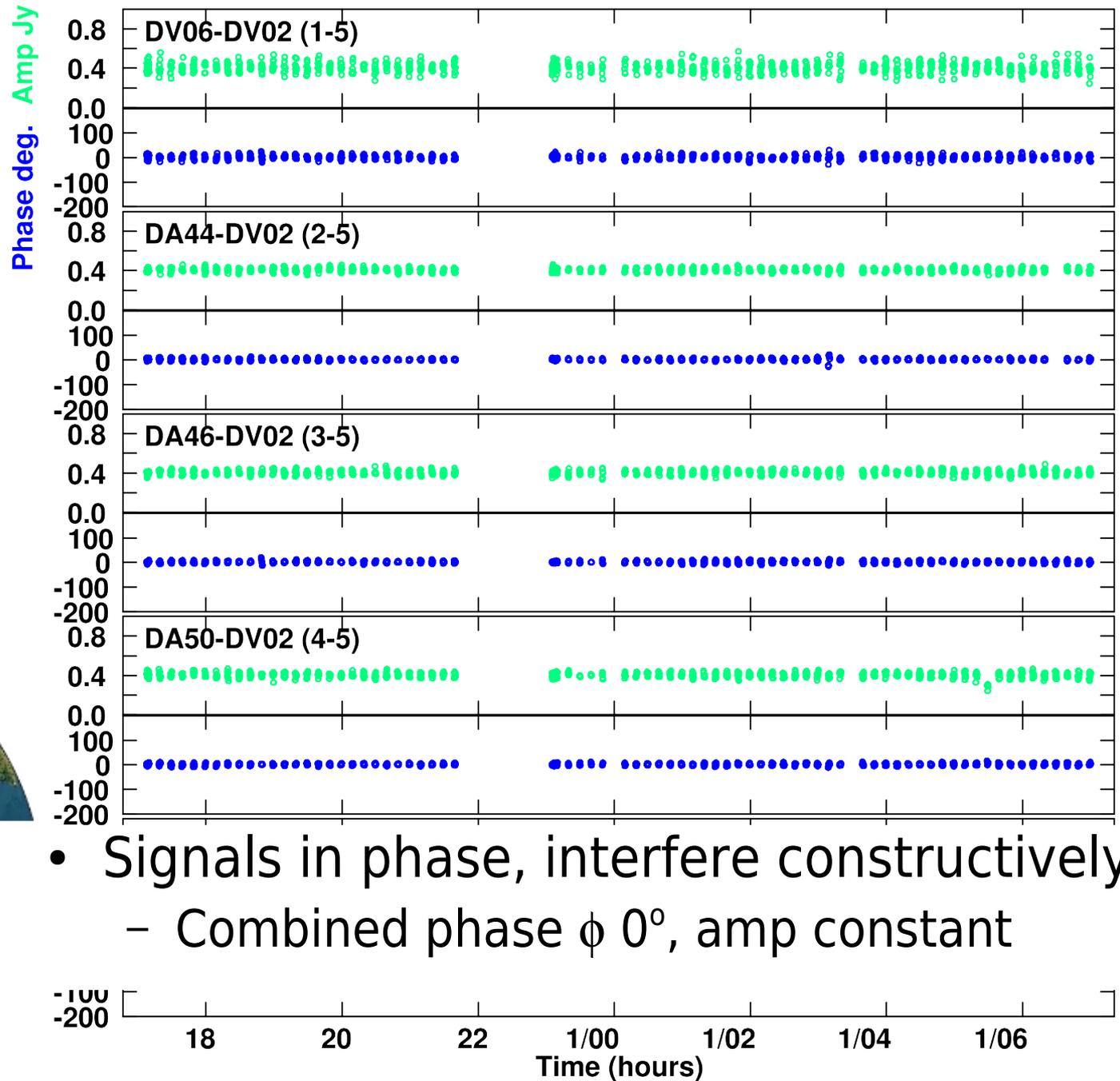


(1)
core

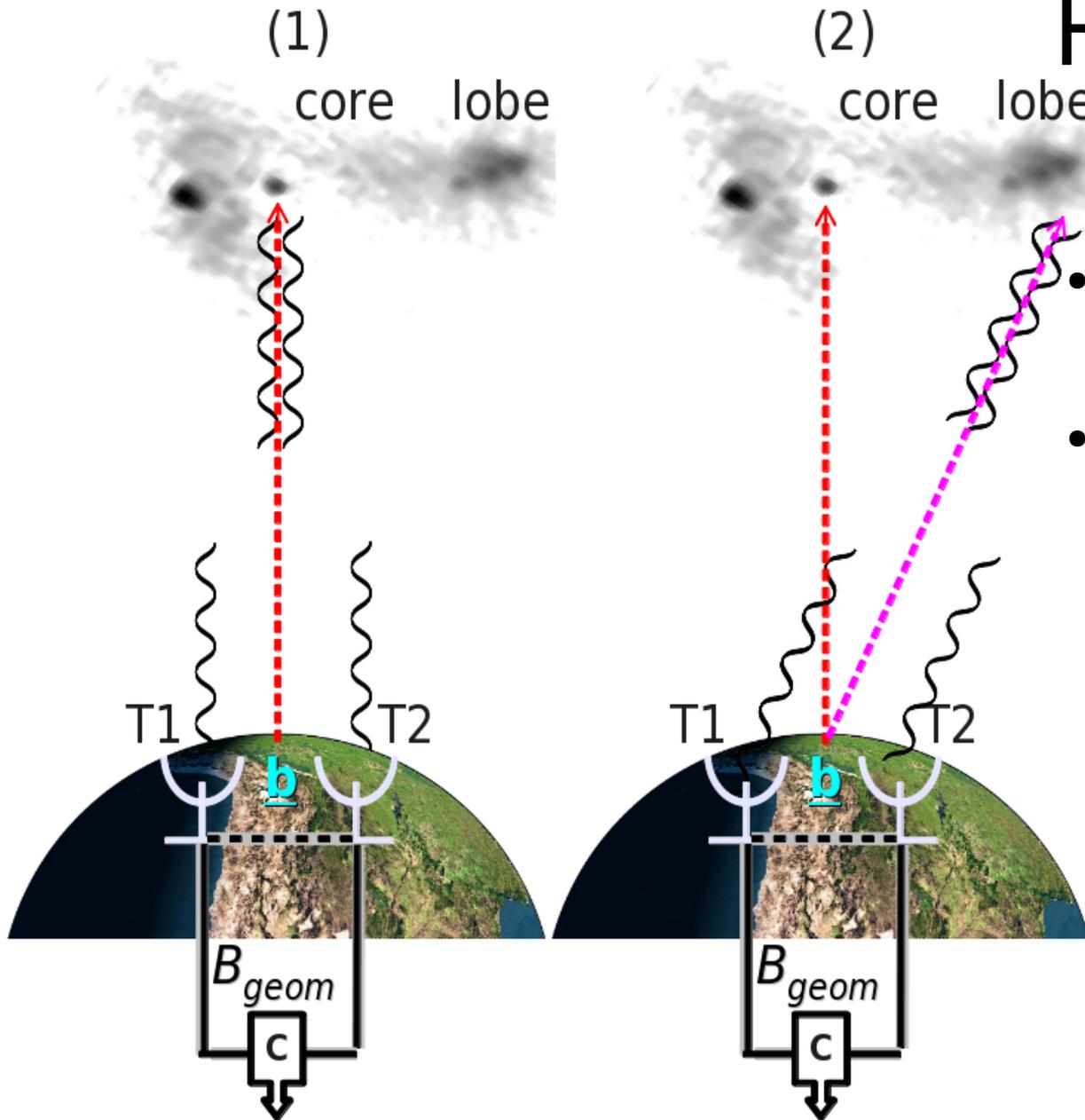


Correlator

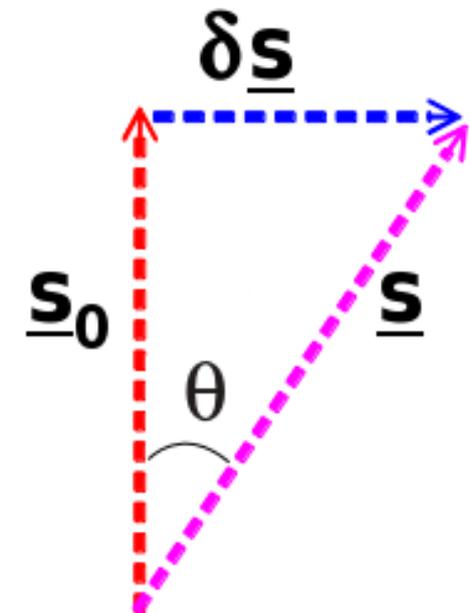
Point source overhead



Resolved source overhead

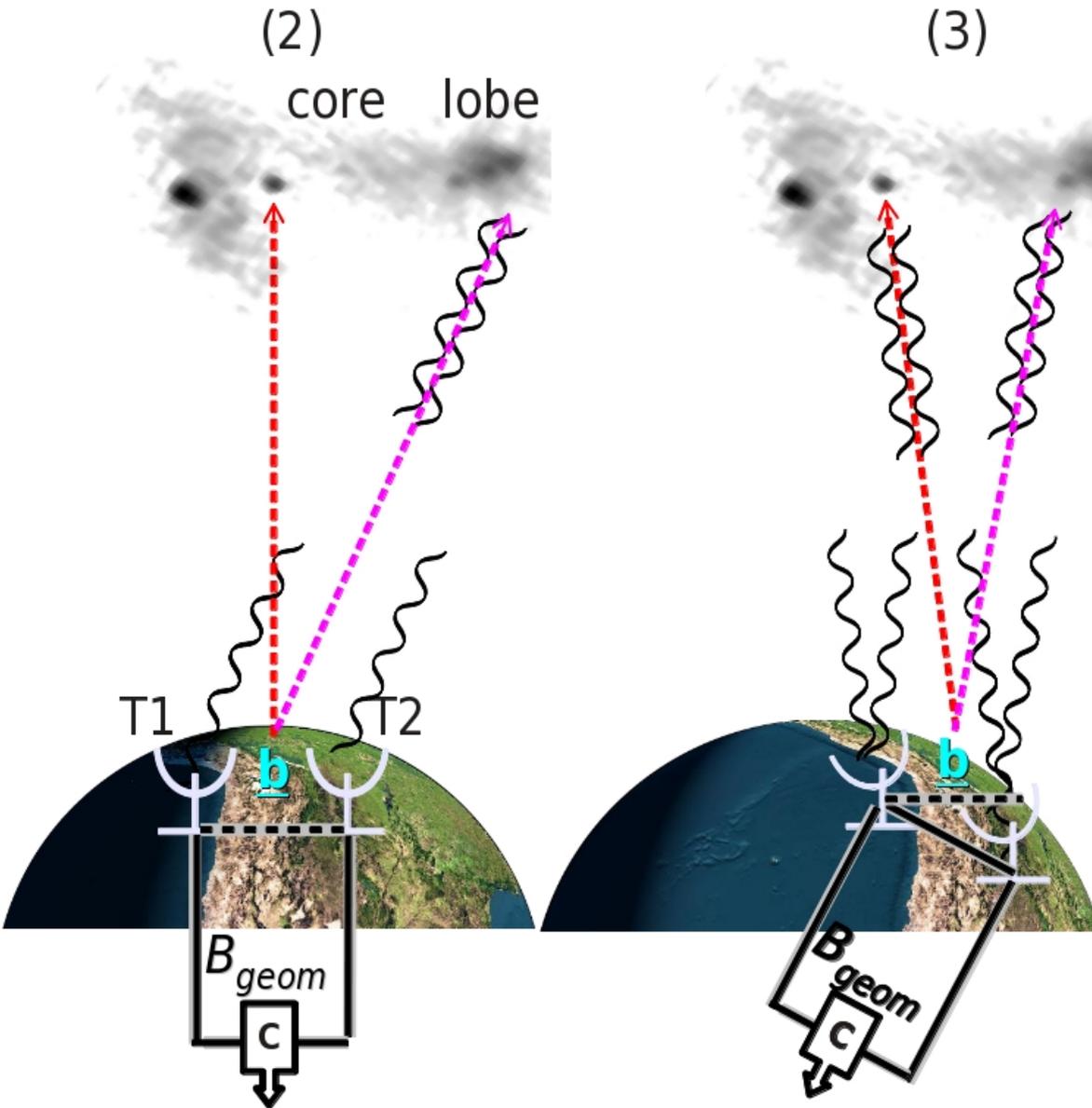


- Signals from overhead vector \underline{s}_0
- Signals from lobe
 - Angular offset vector $\delta \underline{s}$
 - Path length $\underline{s} = \delta \underline{s} \cdot \underline{s}_0$

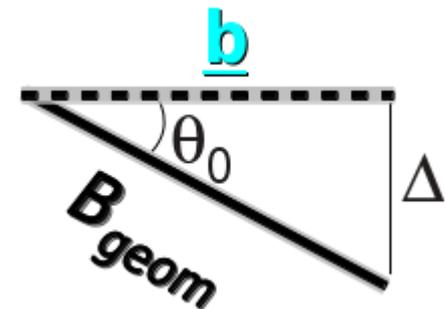


- Combined ϕ depends on $\delta \underline{s}$
- Complex visibility amplitude is sinusoidal function of ϕ

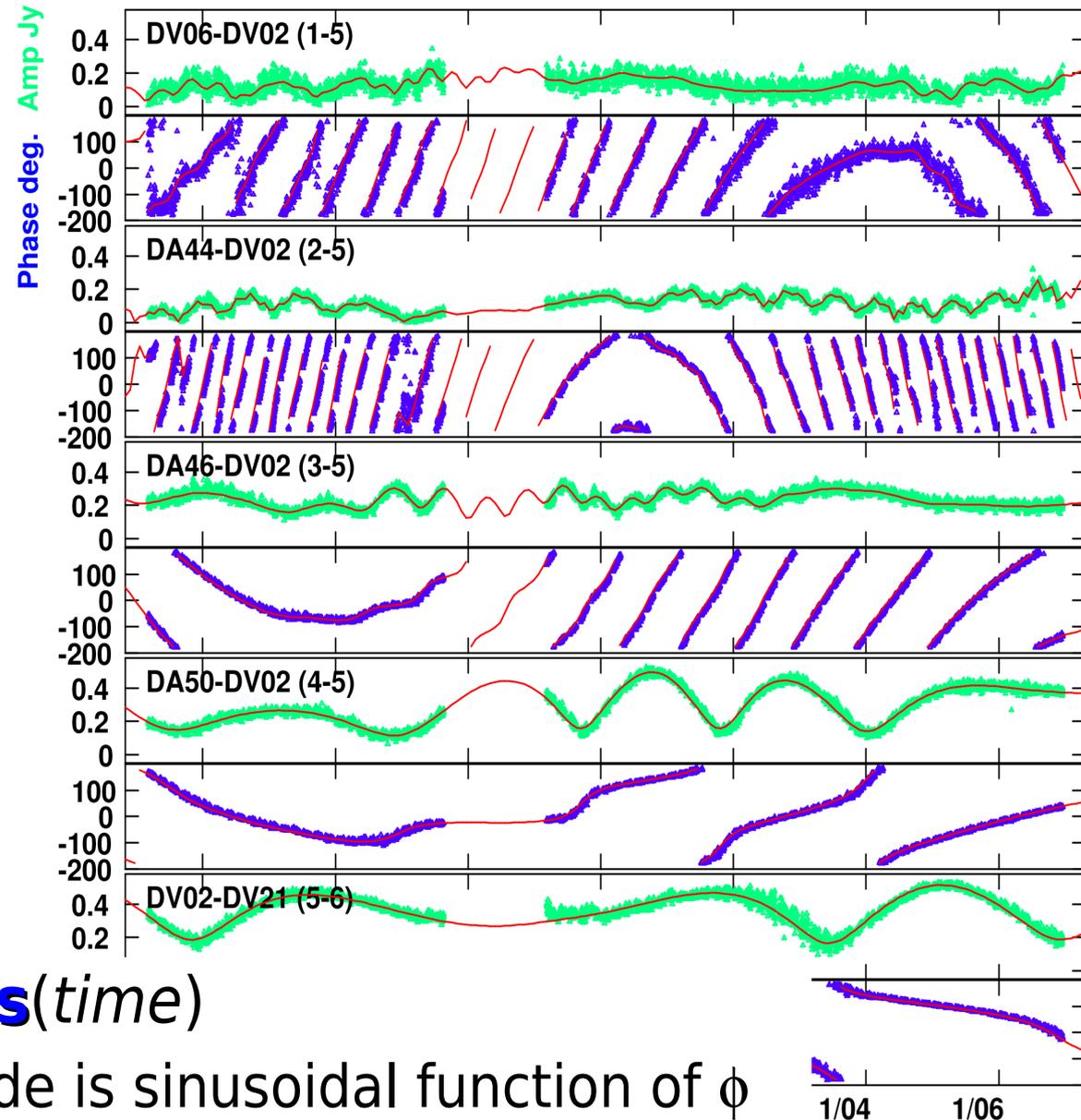
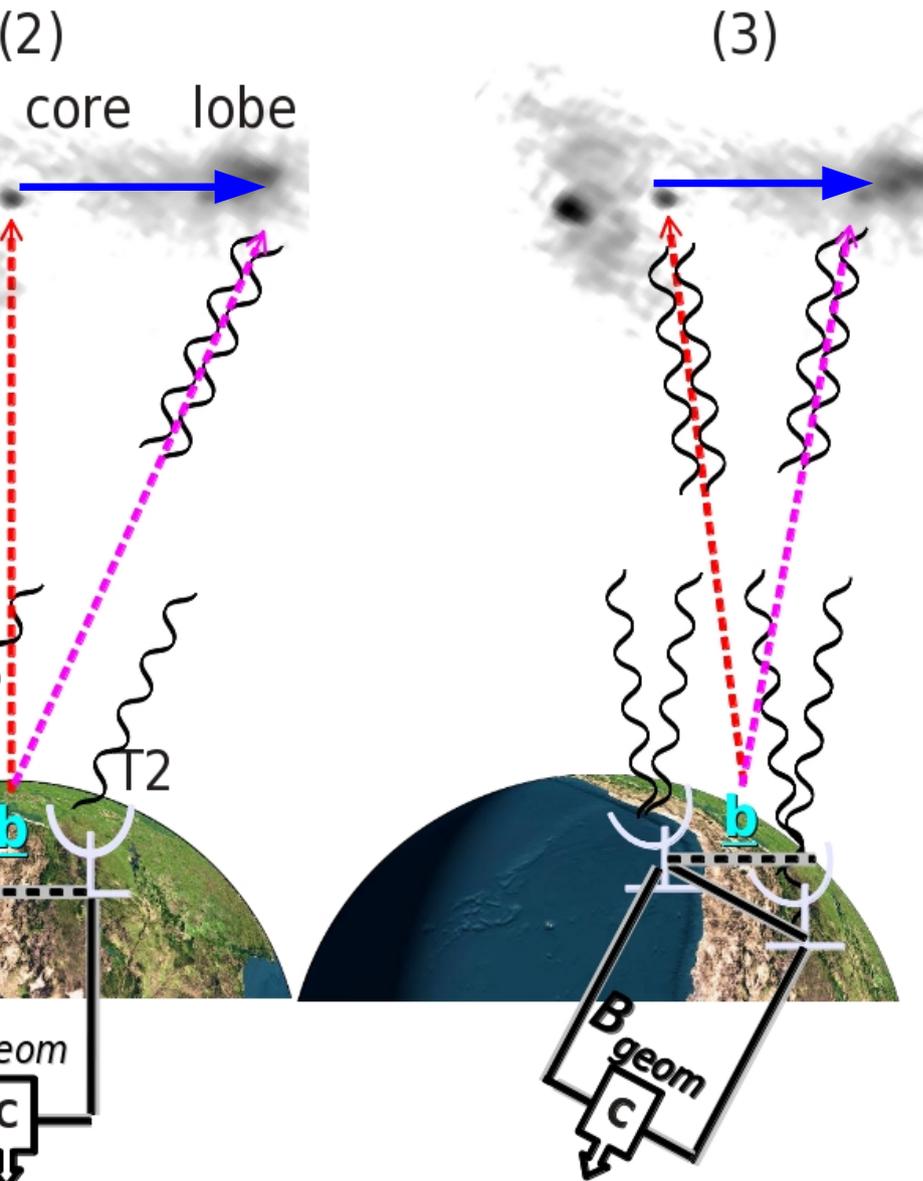
Earth rotation aperture synthesis



- Telescopes separated by baseline B_{geom}
- Earth rotates
 - Projected separation $b = B_{geom} \cos \theta_0$
- Samples different scales of source
- Additional geometric delay path Δ
 - Remove in correlator



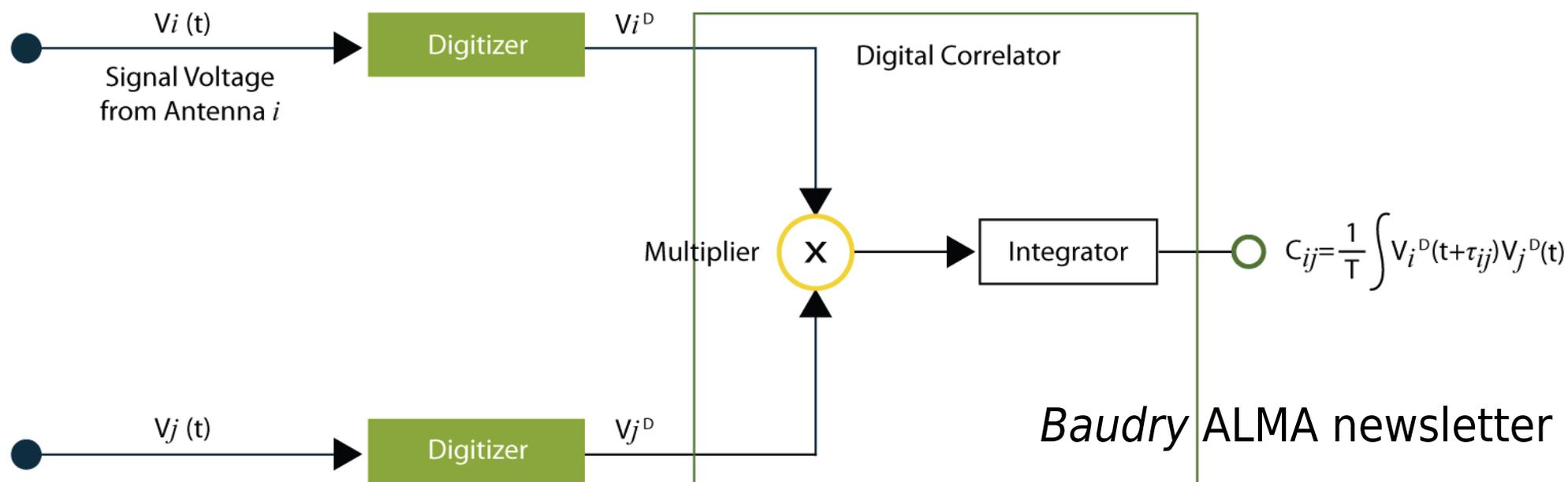
Earth rotation aperture synthesis



- Combined ϕ depends on $\delta s(\text{time})$
- Complex visibility amplitude is sinusoidal function of ϕ

Correlation

- Digitise and combine signals in correlator
 - Create spectral channels by adding ~msec time lags
 - Make parallel (and cross) polarizations
 - (another) FT into frequency domain
 - Output averaging determines integration time
- Produces complex visibility data
 - Time series of amplitudes & phases per baseline
 - per polarization, per spectral channel



From interferometry to images

- Fourier transform of **complex visibility** amplitude and phase gives **sky brightness**

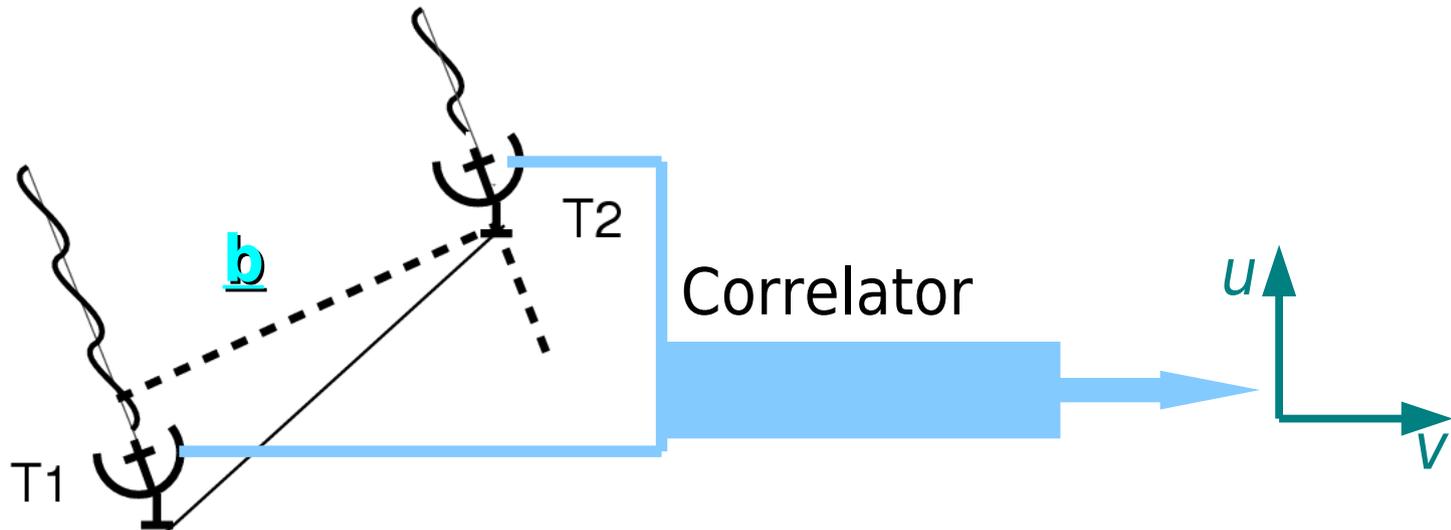
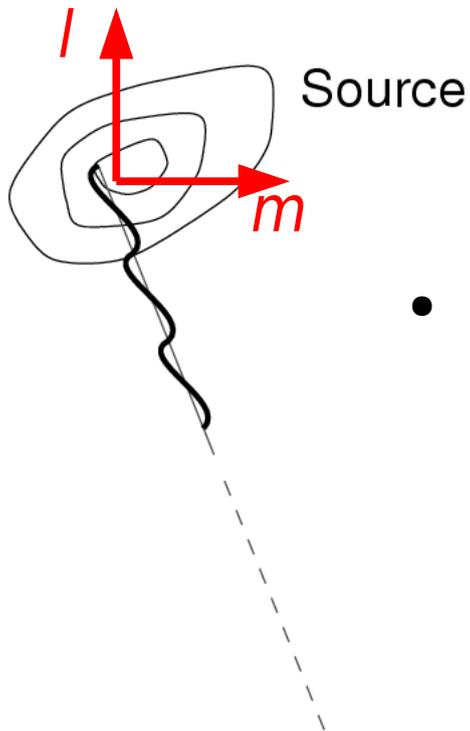
$$\sum V_v(u_v, v_v) e^{[2\pi i(uv_l + vvm)]} dudv = I_v(l, m)$$

– or $V(u, v) \Leftrightarrow I_v(l, m)$ for short

- Sensitivity:

$$\sigma_{rms} \propto \frac{T_{sys}}{\sqrt{N(N-1)/2} \delta\nu \Delta t}$$

- Number antennas (ALMA's huge collecting area!)
- $\delta\nu$ freq. width per image, Δt total time on source

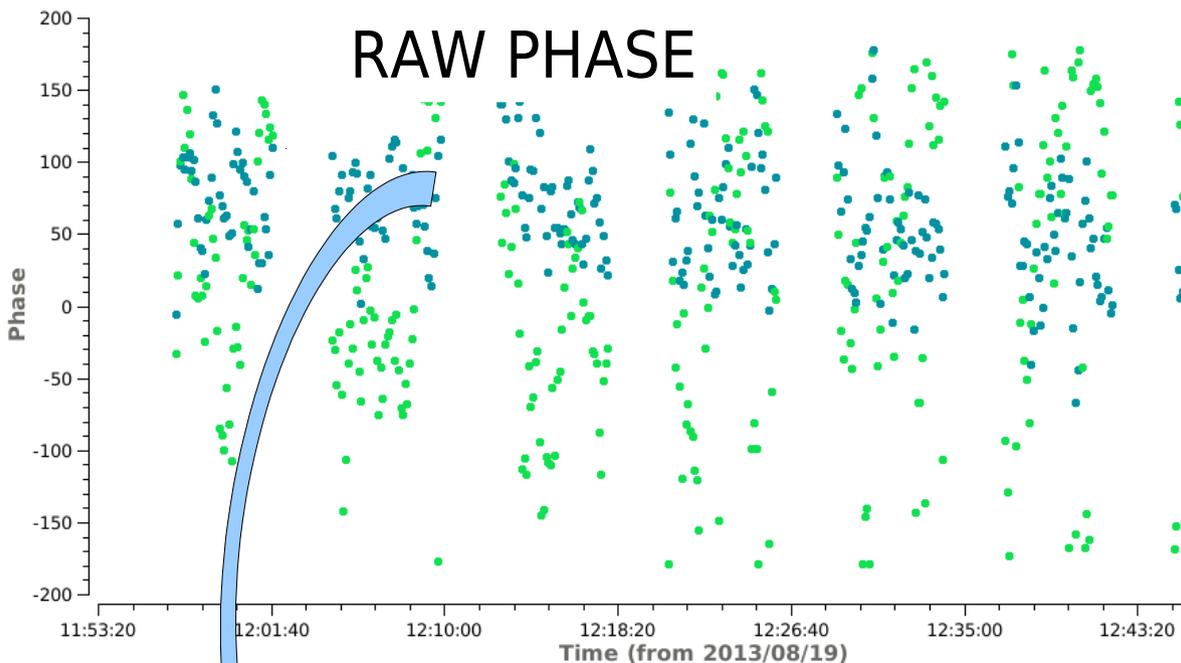


ALMA instrumental calibration

- Pointing corrections before correlation
- Water vapour in the troposphere
 - Refraction: delay to phase of incoming wavefronts
 - Water Vapour Radiometry (WVR)
 - Measure 183-GHz atmospheric line
 - Derive path length corrections at observing ν every second
 - Amplitude absorption and emission
 - System temperature measurements every few min (T_{sys})
- Residual delay and bandpass errors
 - Phase & amplitude corrections as a function of ν
 - Derive from bright astrophysical source
 - Good signal to noise in a single channel
- Planets, large moons, asteroids to set flux scales
- Phase-referencing corrects time-dependent errors

PWV ~0.6, Band 9 raw 0.25 - 2.5 km baselines

RAW PHASE



WVR before & after

Phase

Long baseline

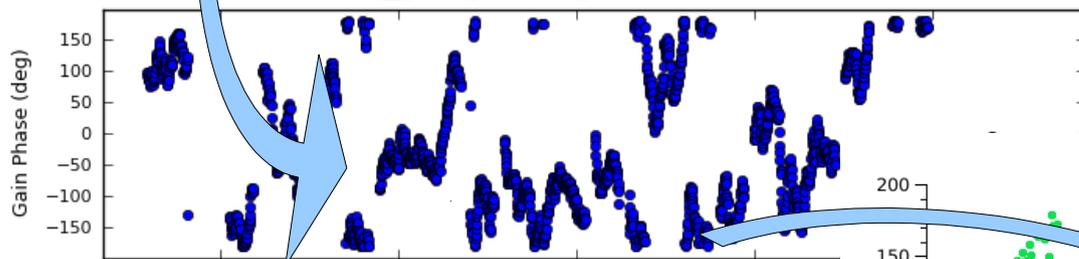
Short baseline

WVR corrections

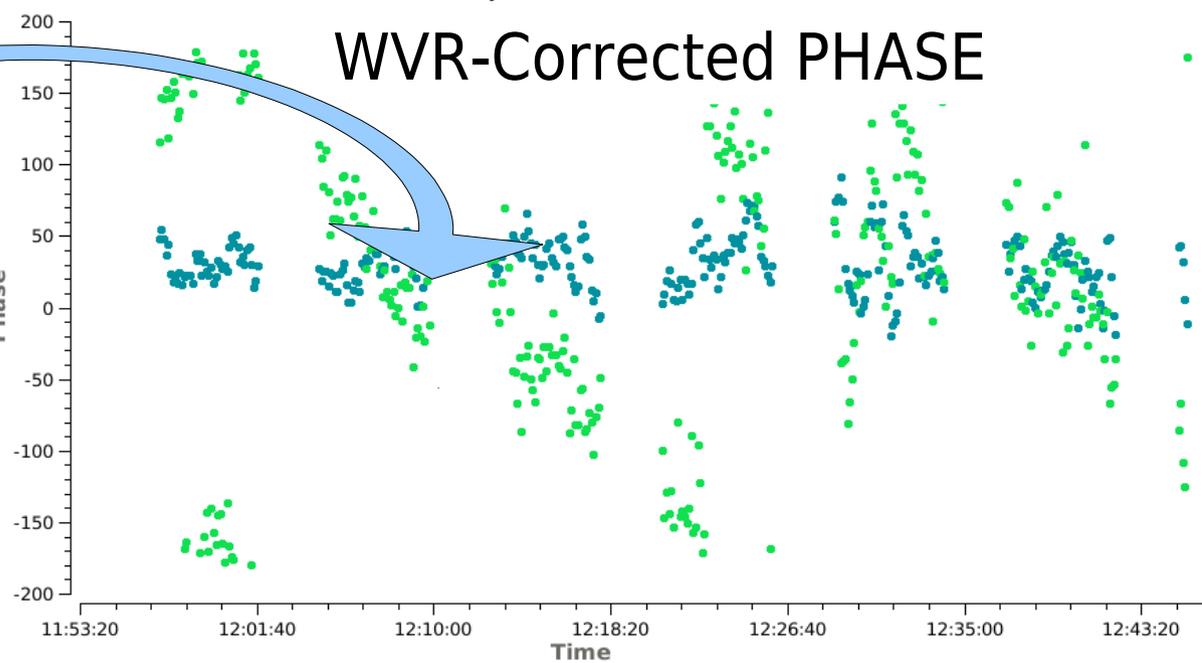
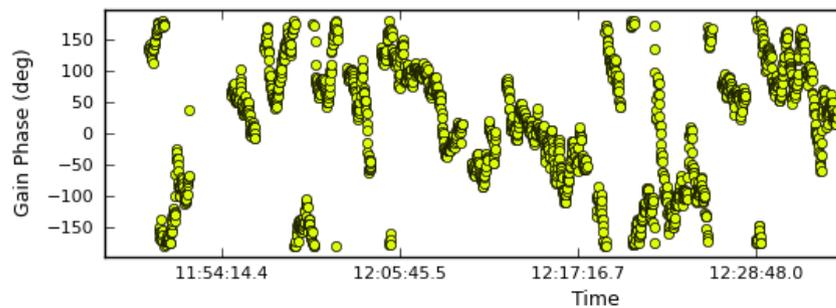
Long Short

PWV ~0.6, Band 9 wvr 0.25 - 2.5 km baselines

WVR-Corrected PHASE



WVR Corrections

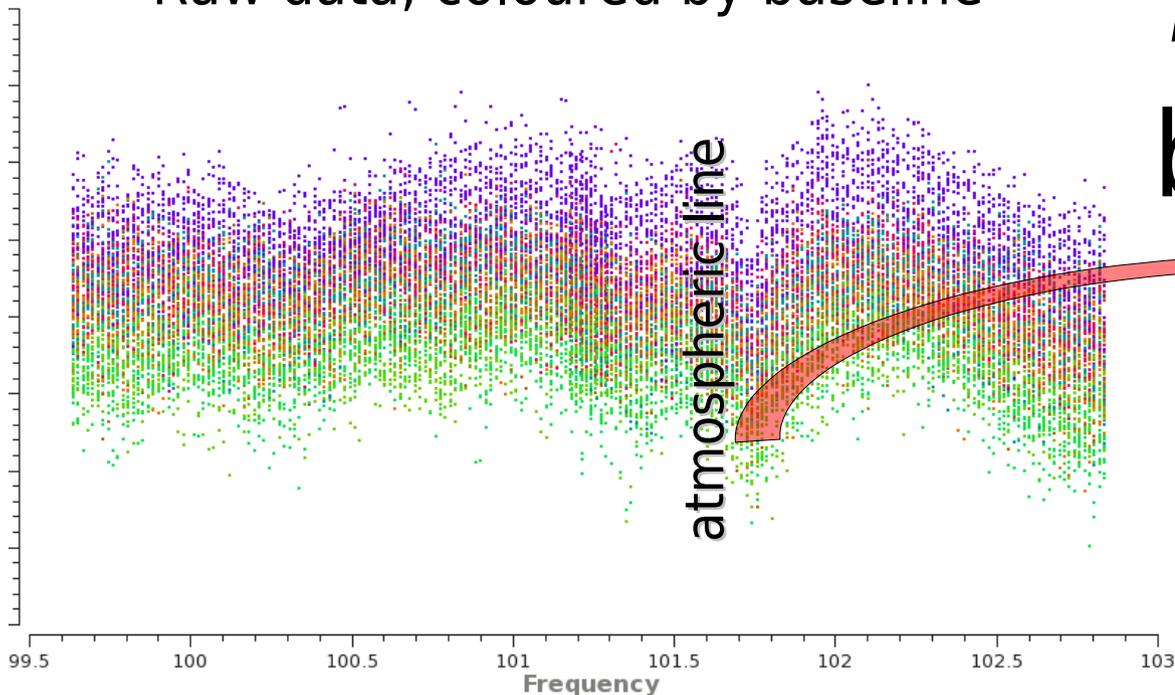


Raw data, coloured by baseline

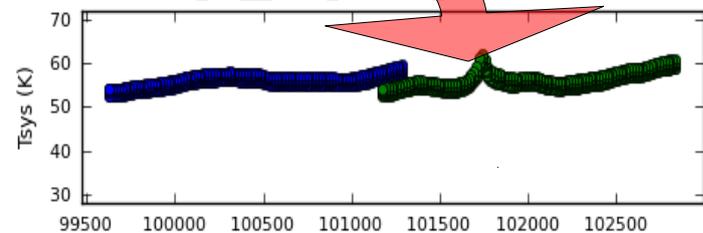
T_{sys} correction before & after

Visibility amplitude

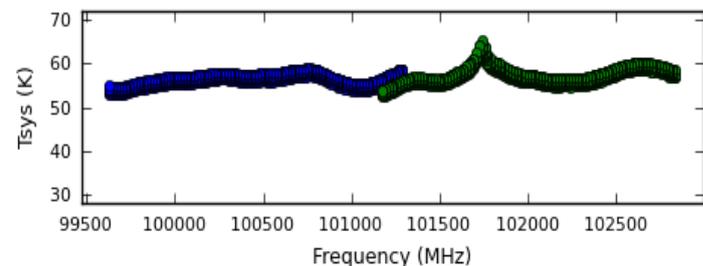
atmospheric line



TSYS table: cal-tsys_uid__A002_X1d5a20_X330.calnew Antenna='DV06'

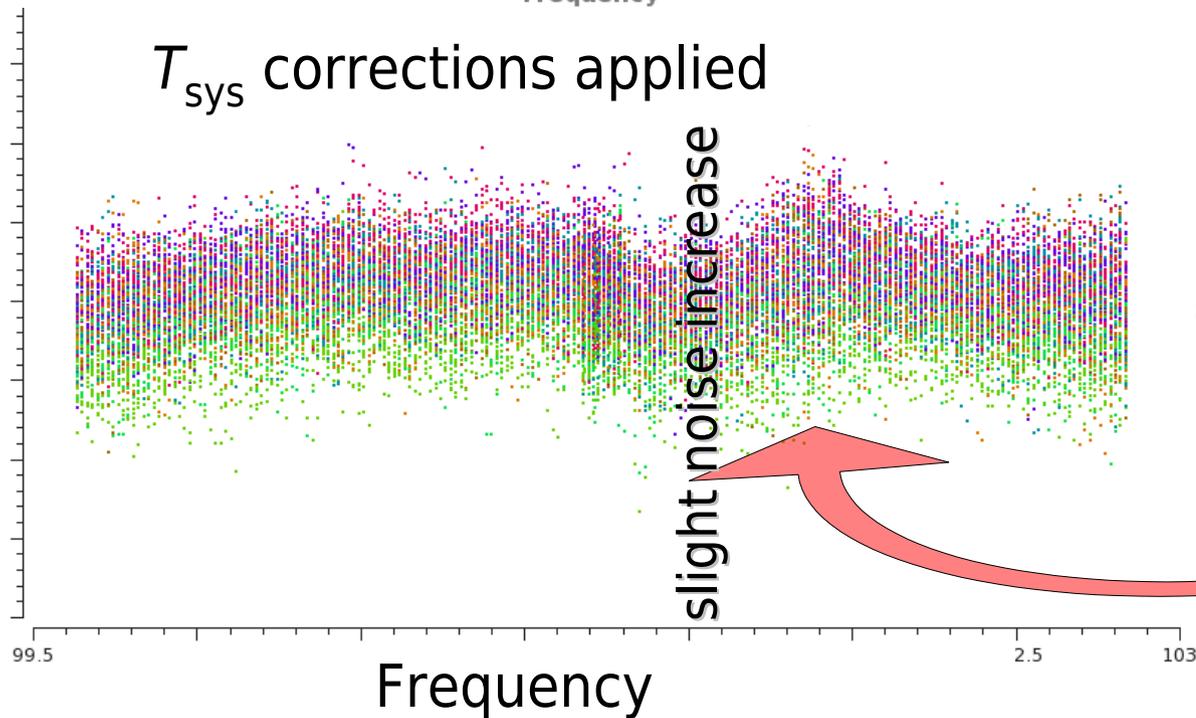


T_{sys} corrections

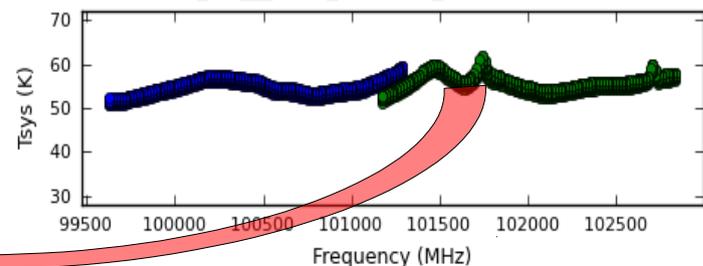


T_{sys} corrections applied

slight noise increase

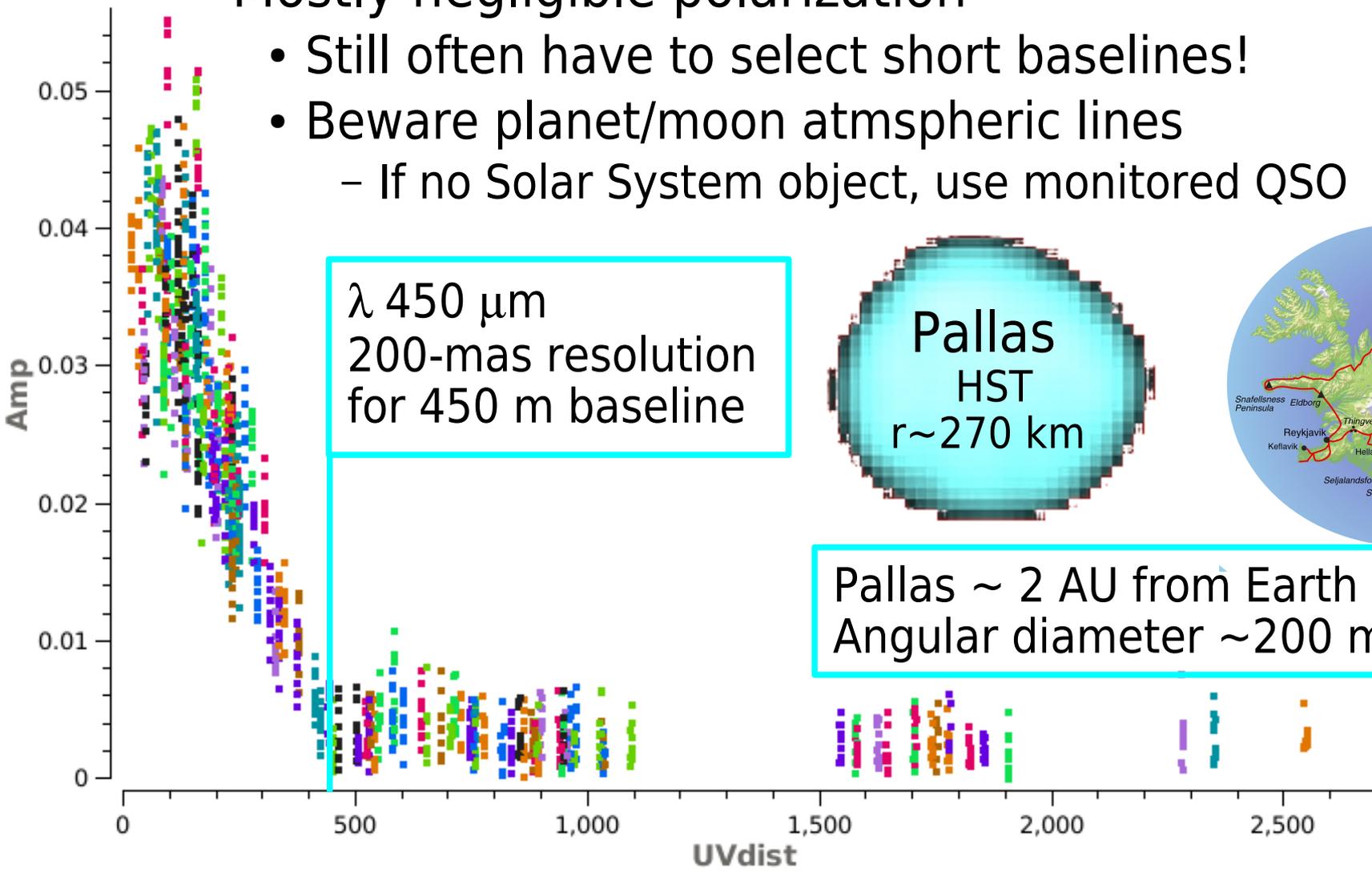


TSYS table: cal-tsys_uid__A002_X1d5a20_X330.calnew Antenna='DV10'



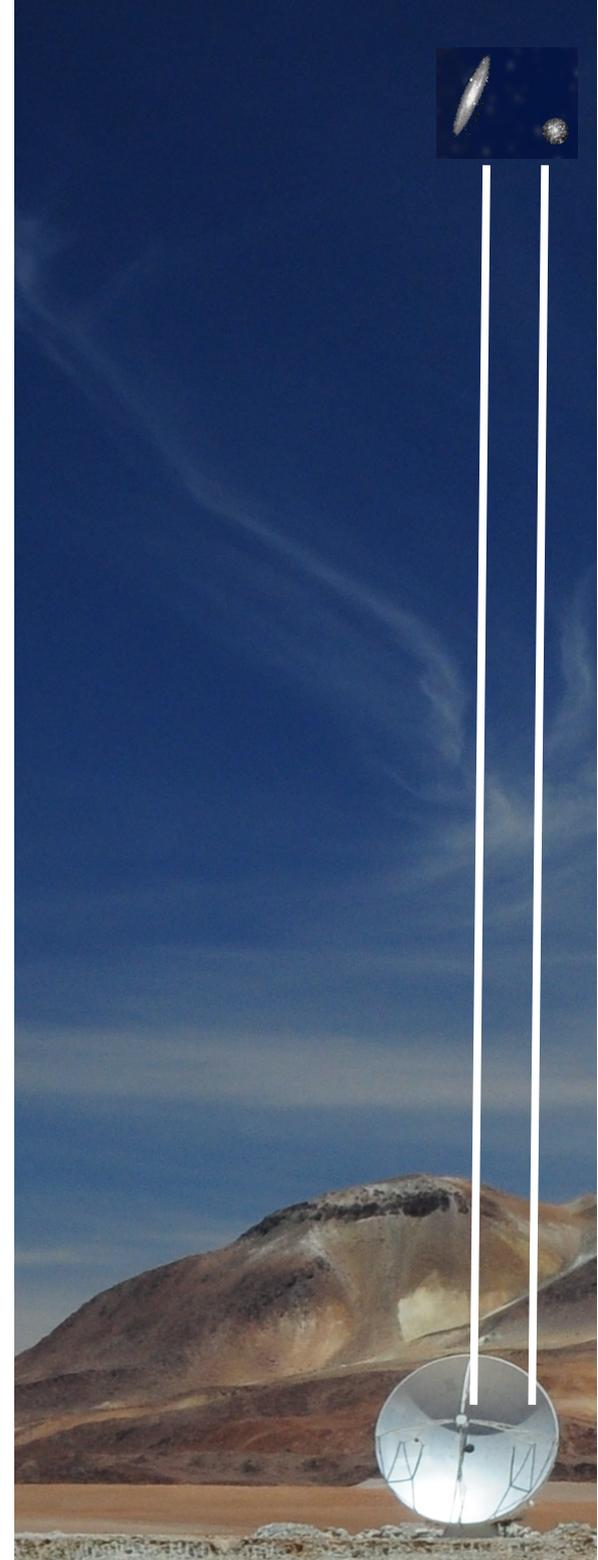
Calibration sources: flux density

- Primary flux calibration uses planets, moons, asteroids
 - Models and ephemerides available
 - Mostly negligible polarization
 - Still often have to select short baselines!
 - Beware planet/moon atmospheric lines
 - If no Solar System object, use monitored QSO

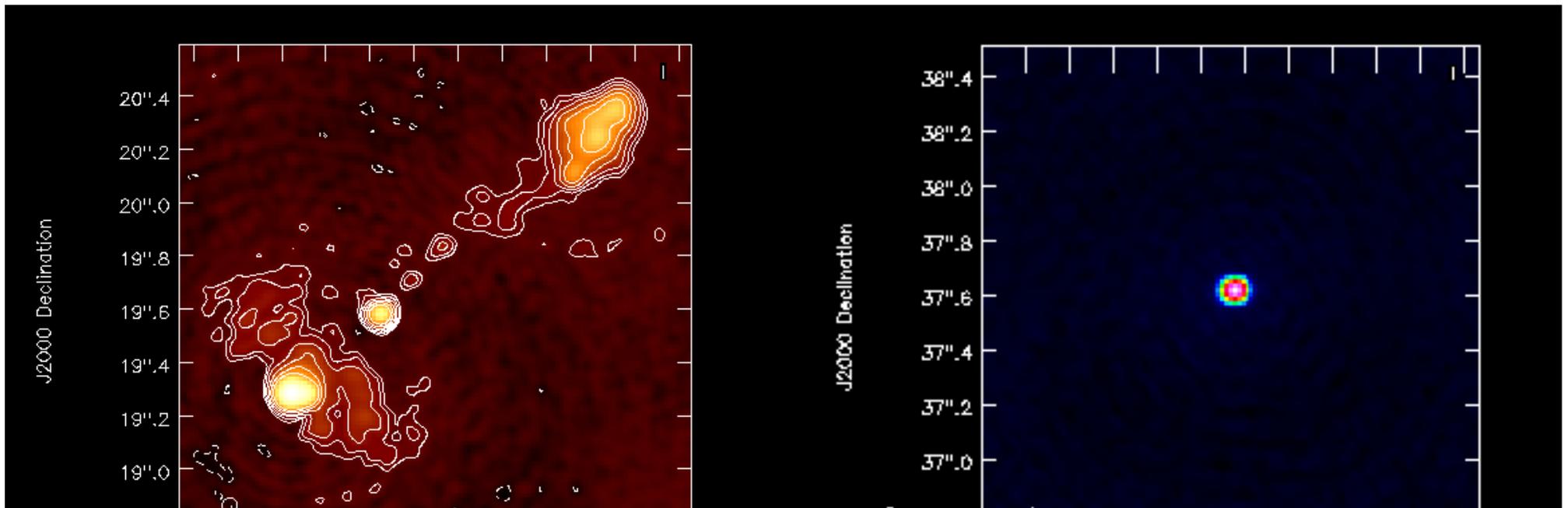


Phase referencing

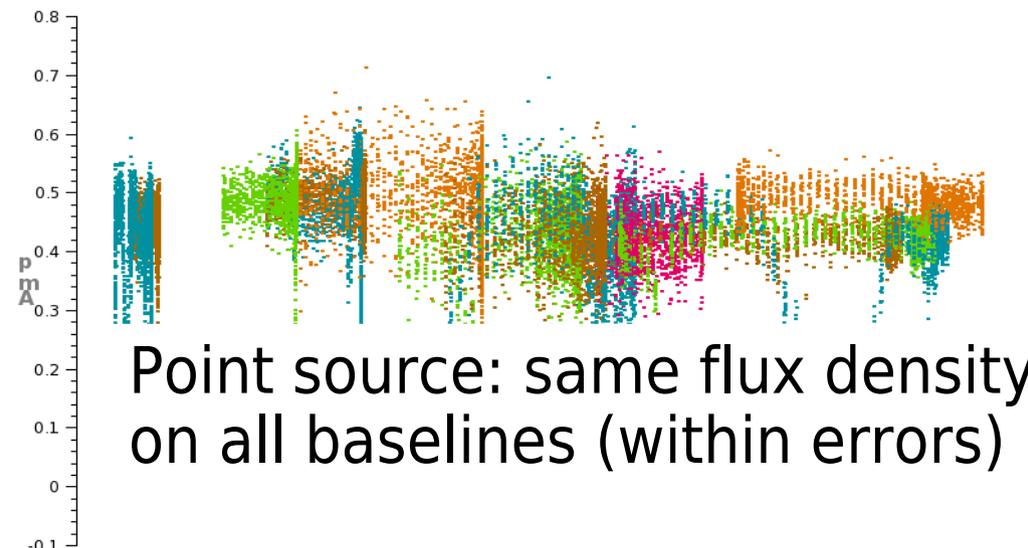
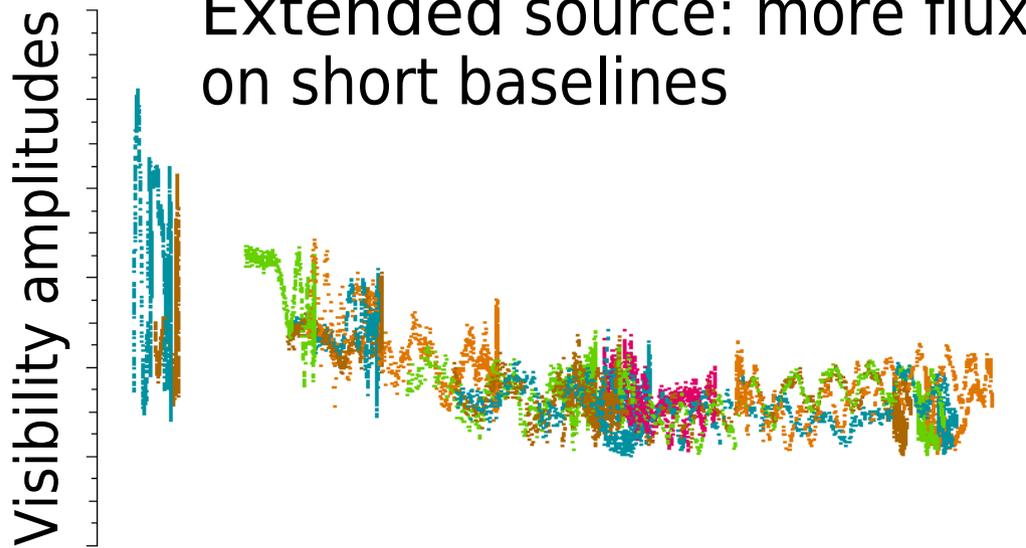
- Observe phase-ref source close to target
 - Point-like or with a good model
 - Close enough to see same atmosphere
 - Few - 10 degrees (isoplanatic patch)
 - Bright enough to get good SNR quicker than atmospheric timescale τ
 - (after WVR applied)
 - τ 10 min/30 s short/long B & low/high ν
- Nod on suitable timescale e.g. 5:1 min
 - Derive time-dependent corrections to make phase-ref data match model
 - Apply same corrections to target
 - May correct amplitudes similarly
- Self-calibration works on similar principle



Source structure in uv plane



Extended source: more flux on short baselines

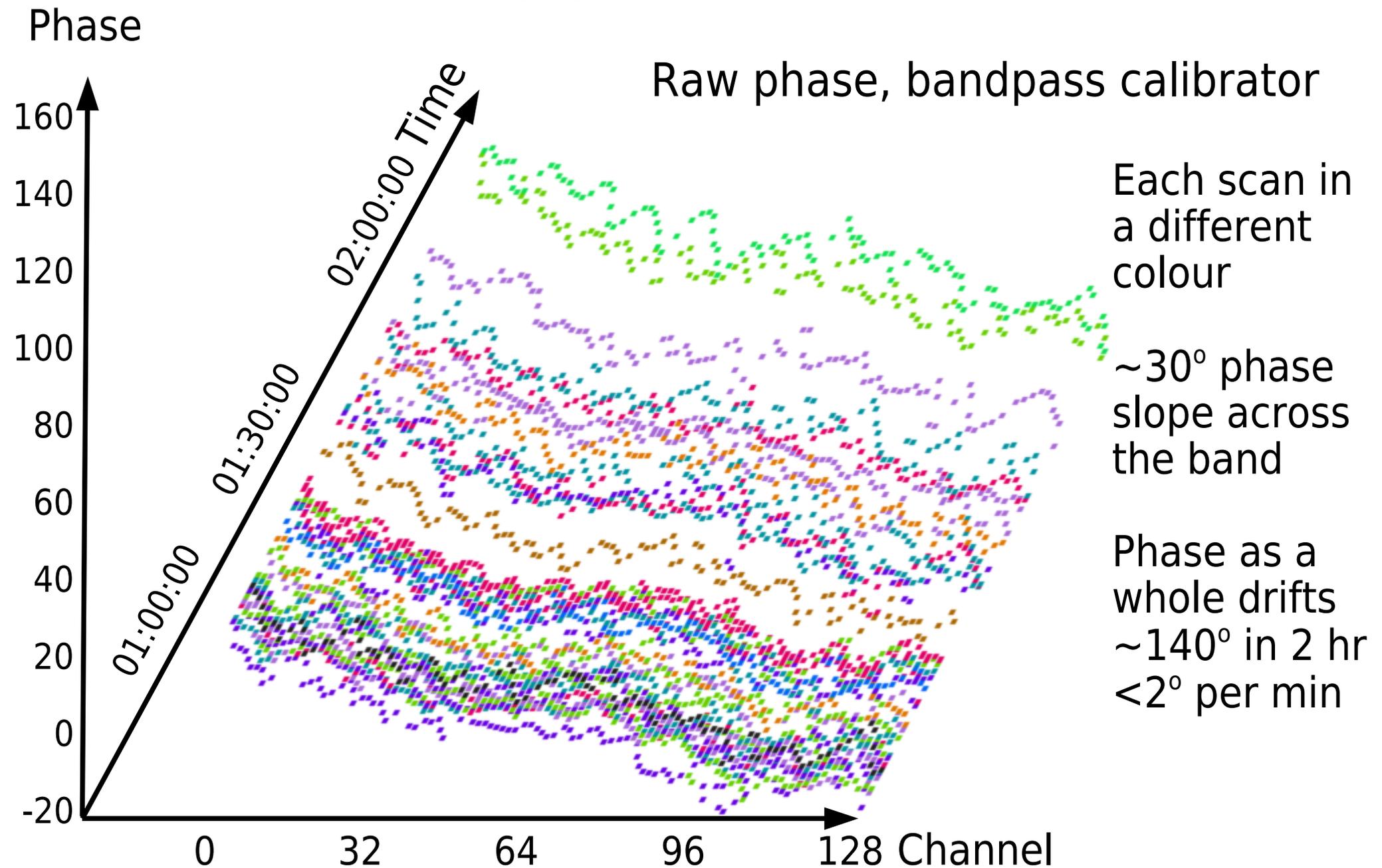


Point source: same flux density on all baselines (within errors)

Baseline length in wavelengths (uv distance)

UVDist_L

Phase errors in 3D



Calibration strategy

- Need Signal to Noise Ratio $\sigma_{\text{ant}}/S_{\text{calsource}} > 3$

- per calibration interval per antenna

$$\sigma_{\text{ant}}(\delta t, \delta \nu) \approx \sigma_{\text{array}} \sqrt{\frac{N(N-1)/2}{N-3}}$$

- σ_{array} is noise in all-baseline data per time-averaging interval per frequency interval used for calibration
- Have to average in time and/or frequency
 - Bandpass first or time-dependent cal. first?
 - *Do not average over interval where phase change $d\phi > \pi/4$*
 - *Keep polarizations separate if possible in early calibration*
- Usually start with bandpass calibration
 - Instrumental artefacts, shallow atmospheric lines...
 - May need to perform time-dependent ϕ calibration first

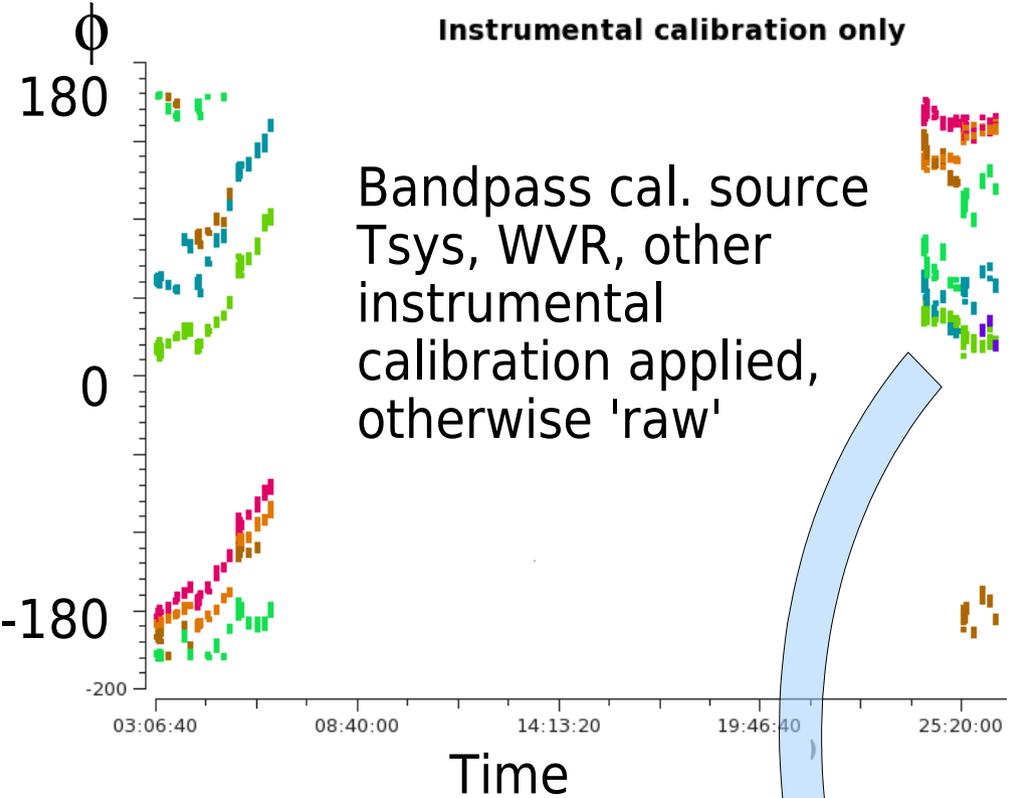
This example: $d\phi < \pi/4$ over inner 50% band

- Bandpass calibrator – bright as possible
 1. Average inner 50% band, perform time-dependent phase & amp calibration (G1) with solint required for SNR
 - If atmospheric lines, chose channel intervals to avoid
 2. Apply calibration (G1), average all times for freq. dependent phase and amplitude calibration, i.e. bandpass calibration (B1).
 - Smooth every e.g. 20 channels if necessary for SNR
 - *G1 is not used any more*
- Phase-reference – fairly bright source
 3. Apply B1 and perform time-dependent phase calibration (G2) averaging all channels, shortest dt for enough SNR
 - Apply B1 for all calibration hereafter, to all sources
 4. Apply B1 and G2 and perform time-dependent amp. cal.
 - Amp calibration needs higher SNR than phase-only; for bright sources you can do it all in step 3.

First time-dependent phase correction

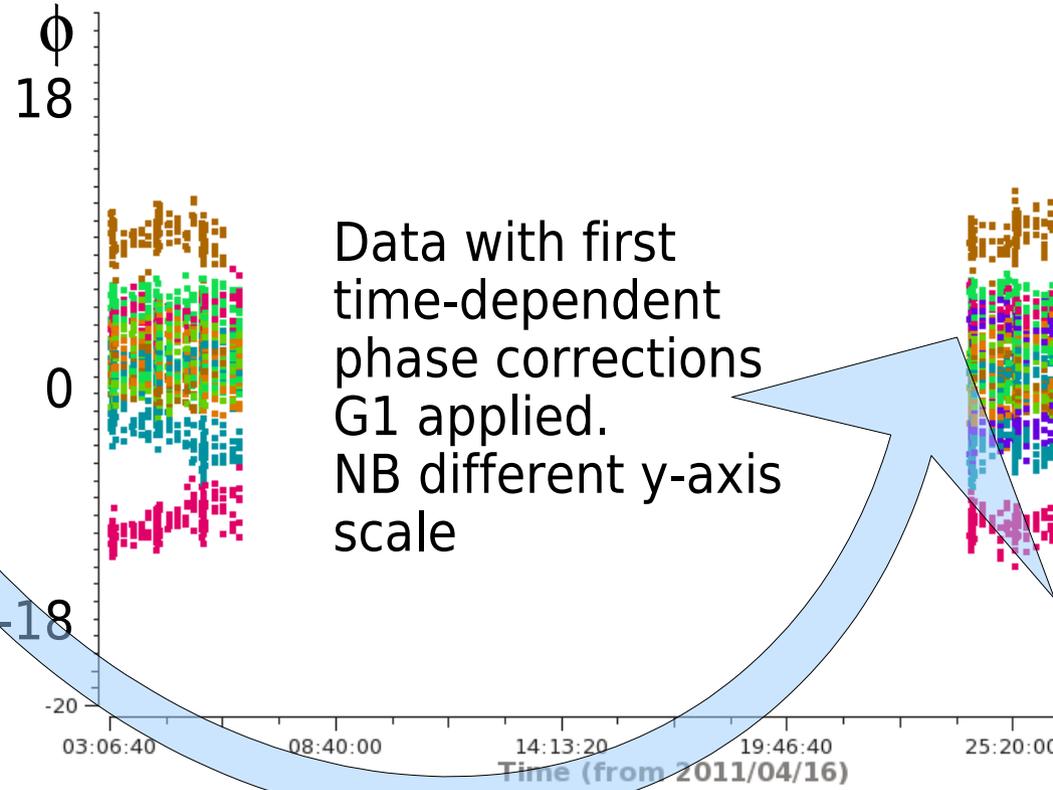
Instrumental calibration only

Bandpass cal. source
Tsys, WVR, other
instrumental
calibration applied,
otherwise 'raw'



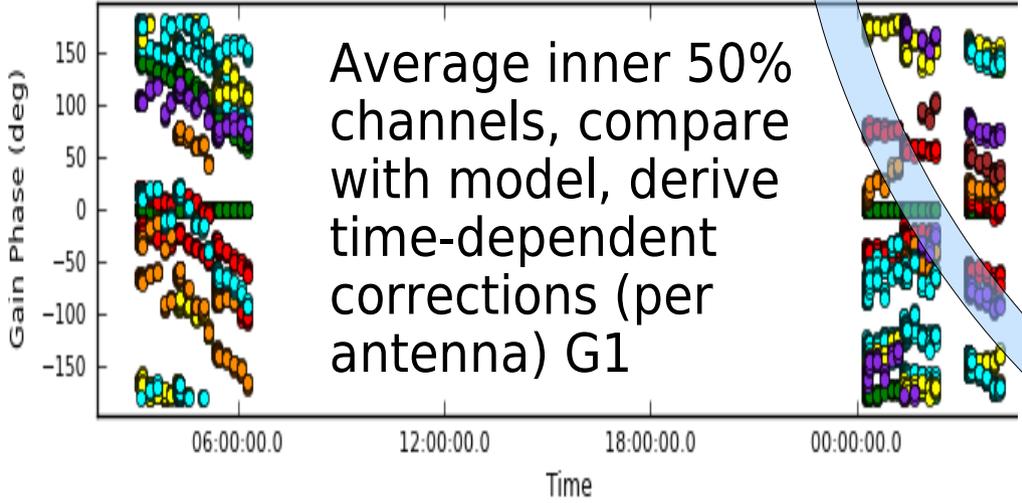
Time-dependent phase-cal applied

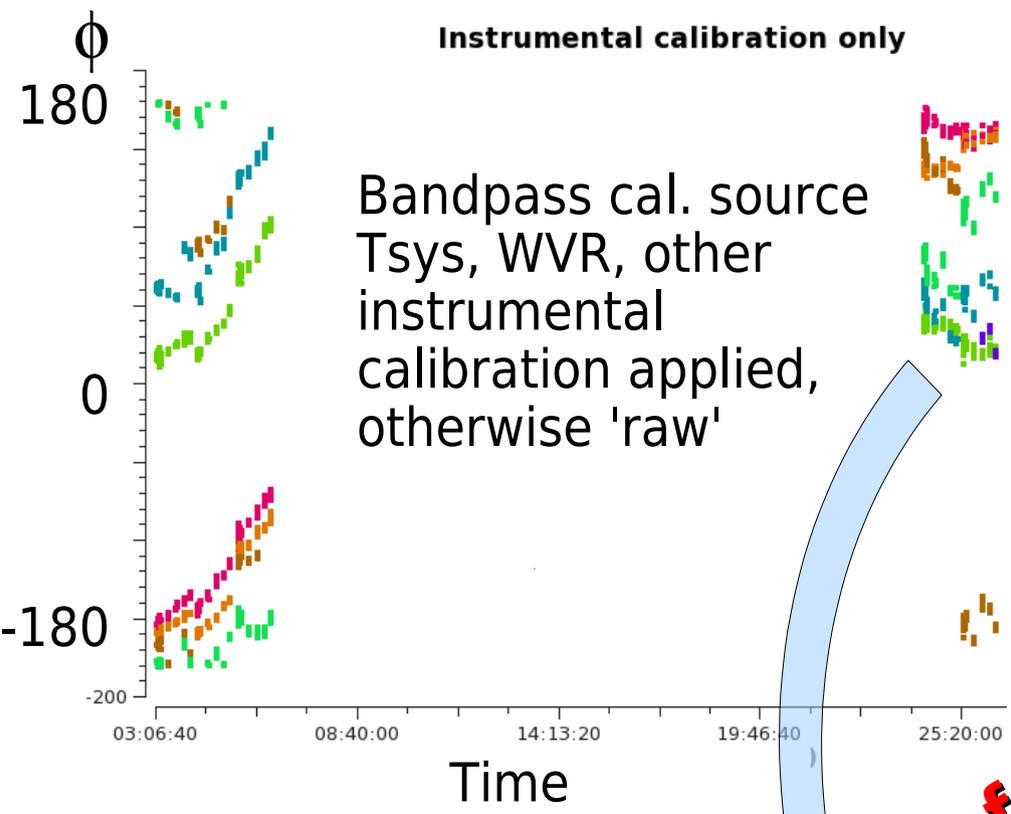
Data with first
time-dependent
phase corrections
G1 applied.
NB different y-axis
scale



G table: cal-ngc3256.G1api

Average inner 50%
channels, compare
with model, derive
time-dependent
corrections (per
antenna) G1

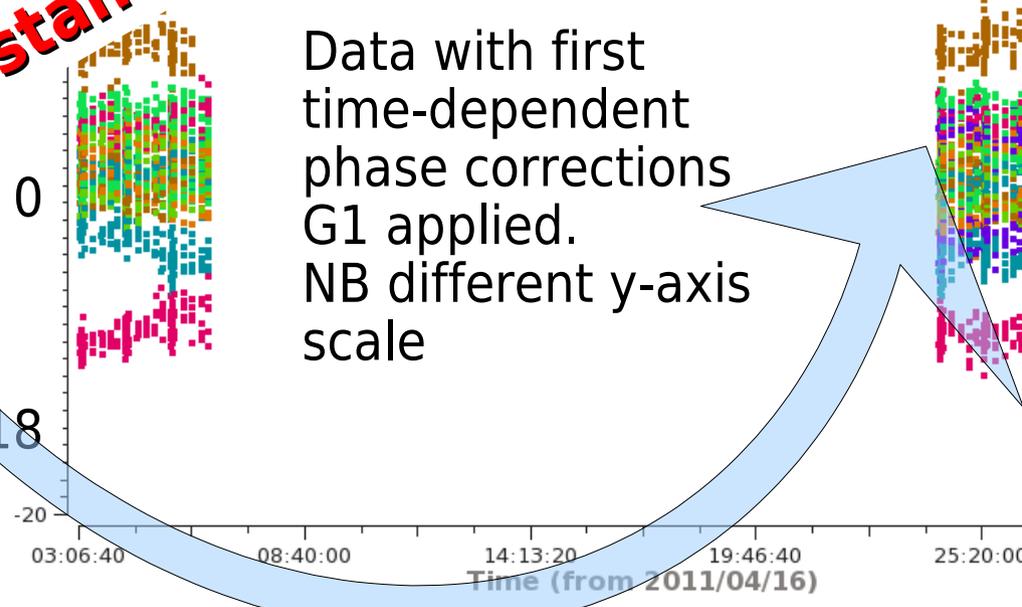
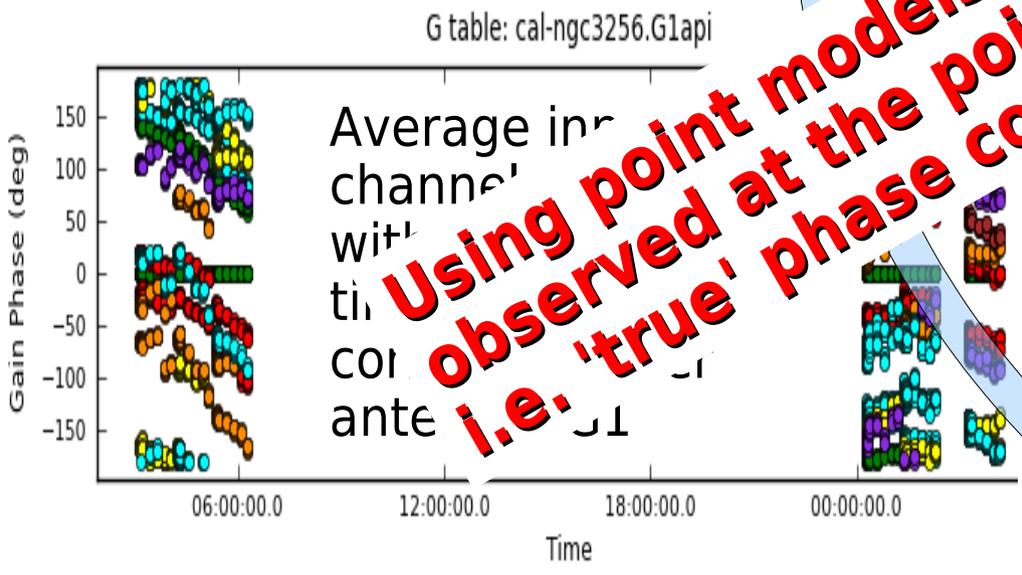




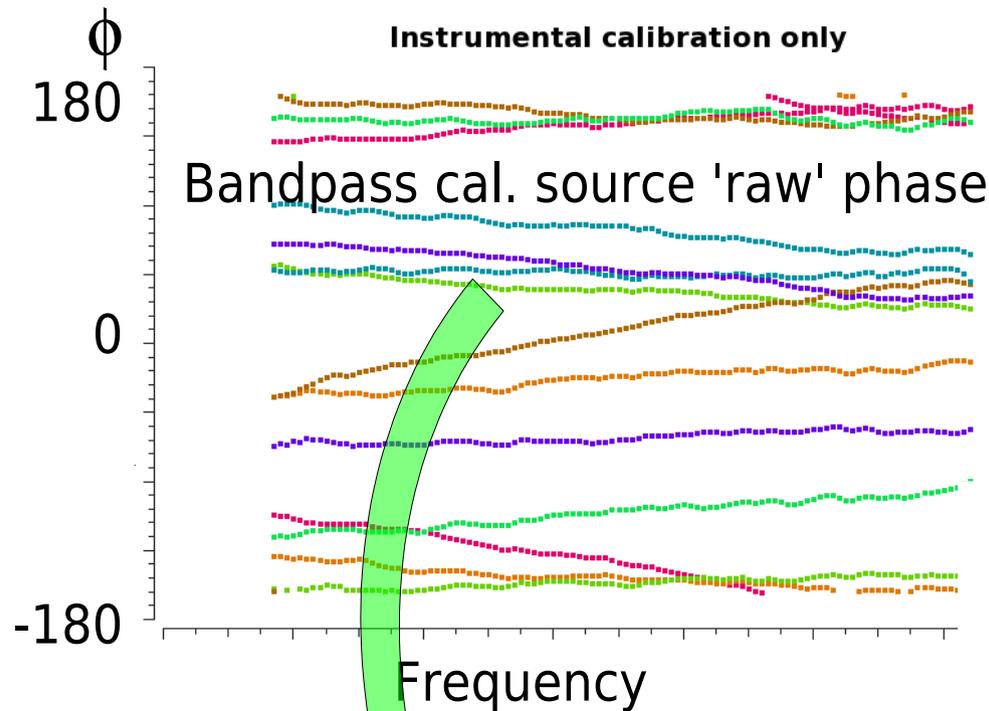
First time-
dependent
phase

corrections
constant phase-cal applied

**Using point models for calibration sources,
observed at the pointing centre
i.e. 'true' phase constant 0, amp also constant**

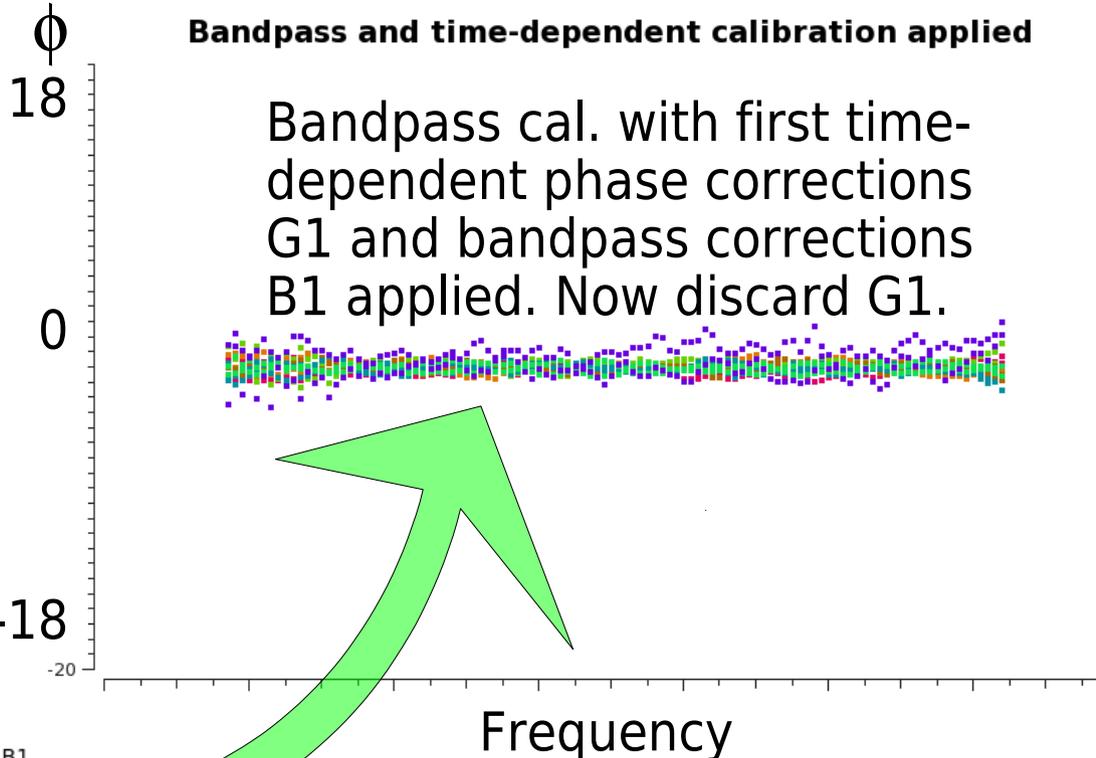


Bandpass calibration

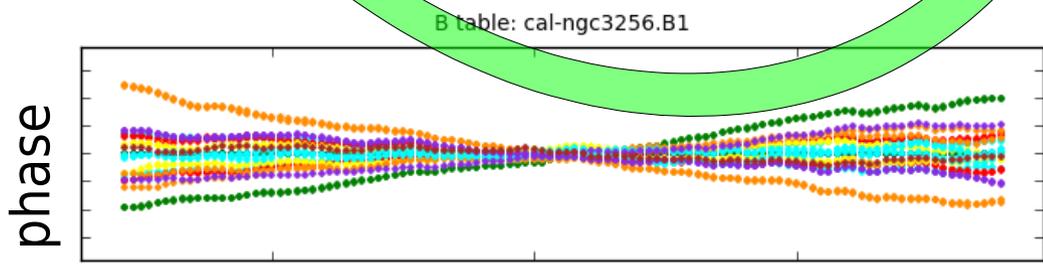
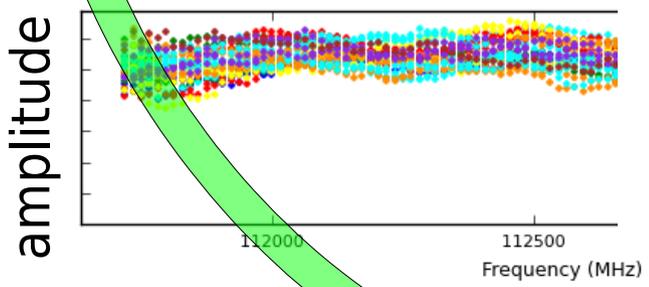
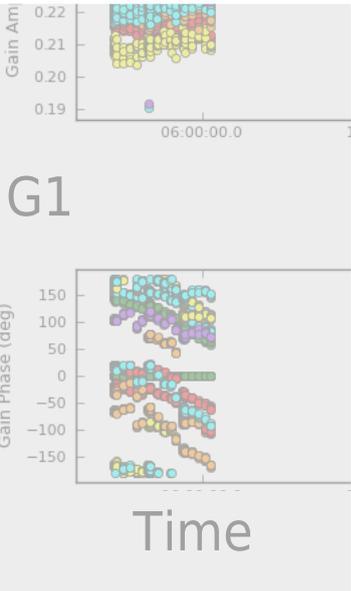


Bandpass and time-dependent calibration applied

Bandpass cal. with first time-dependent phase corrections G1 and bandpass corrections B1 applied. Now discard G1.



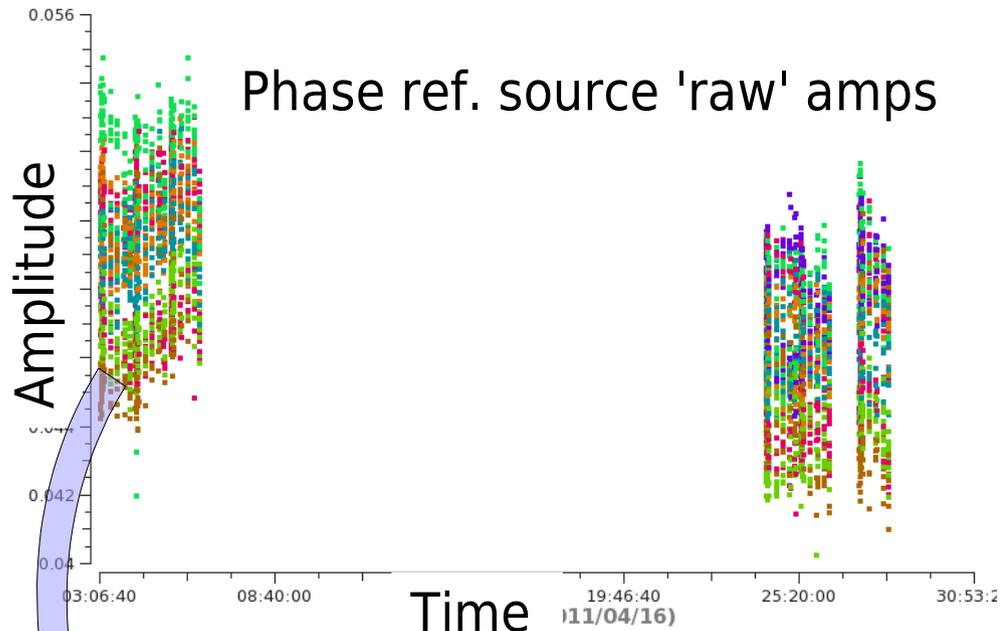
Apply 1st time-dependent corrections G1
Average all times, derive frequency-dependent calibration bandpass table B1



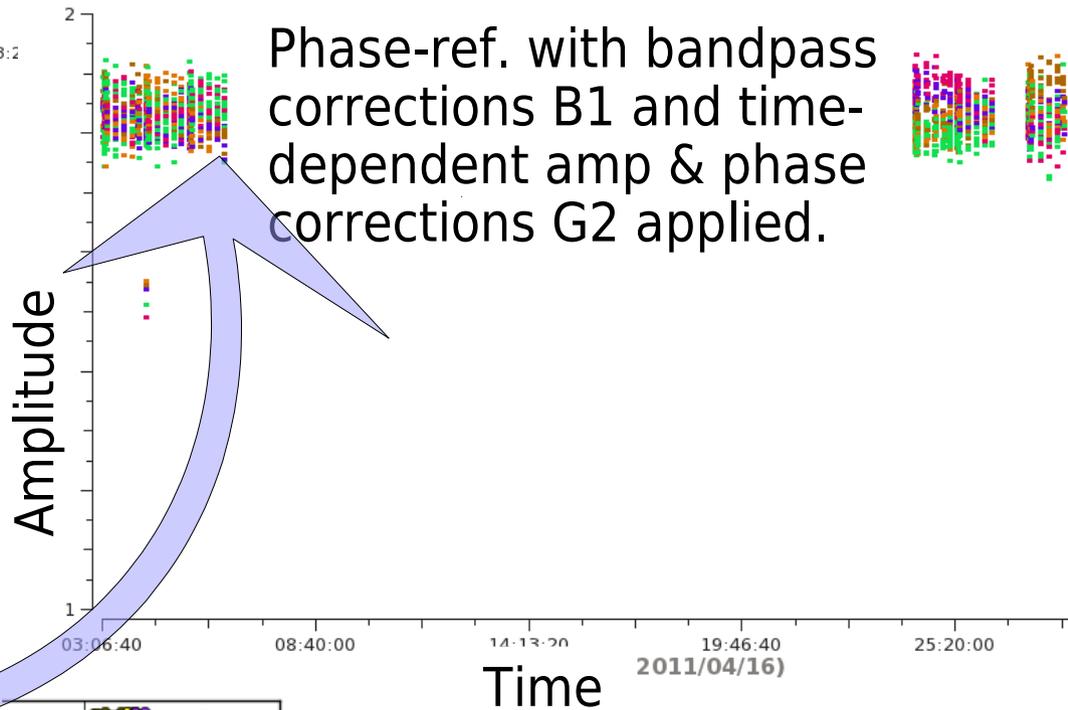
NB Cannot remove random noise!

Phase-ref amp & phase calibration

Phase ref. source 'raw' amps



Phase-ref. with bandpass corrections B1 and time-dependent amp & phase corrections G2 applied.



Apply bandpass table B1
Average all chans, derive time-dependent amp & phase corrections G2 (may need phase-only first)

amplitude

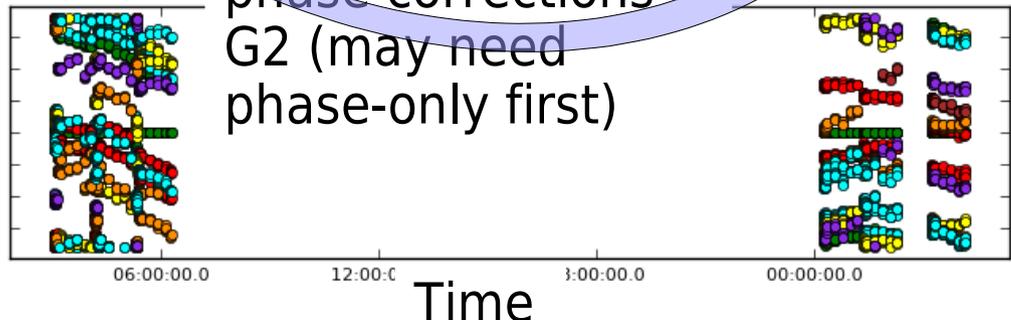
phase

B1

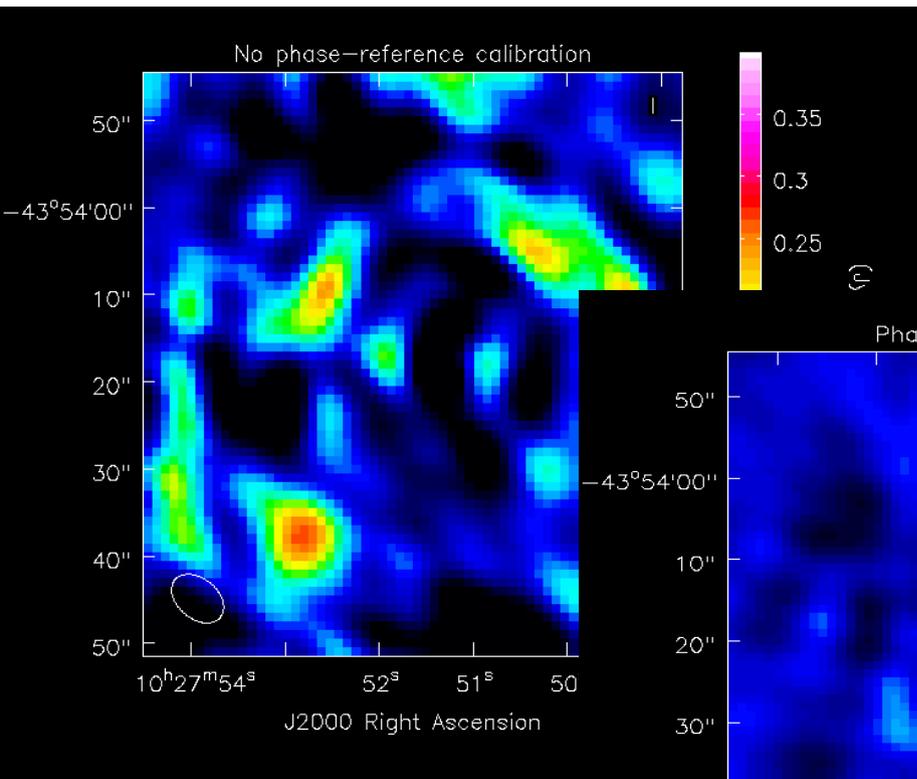
Freq

amplitude

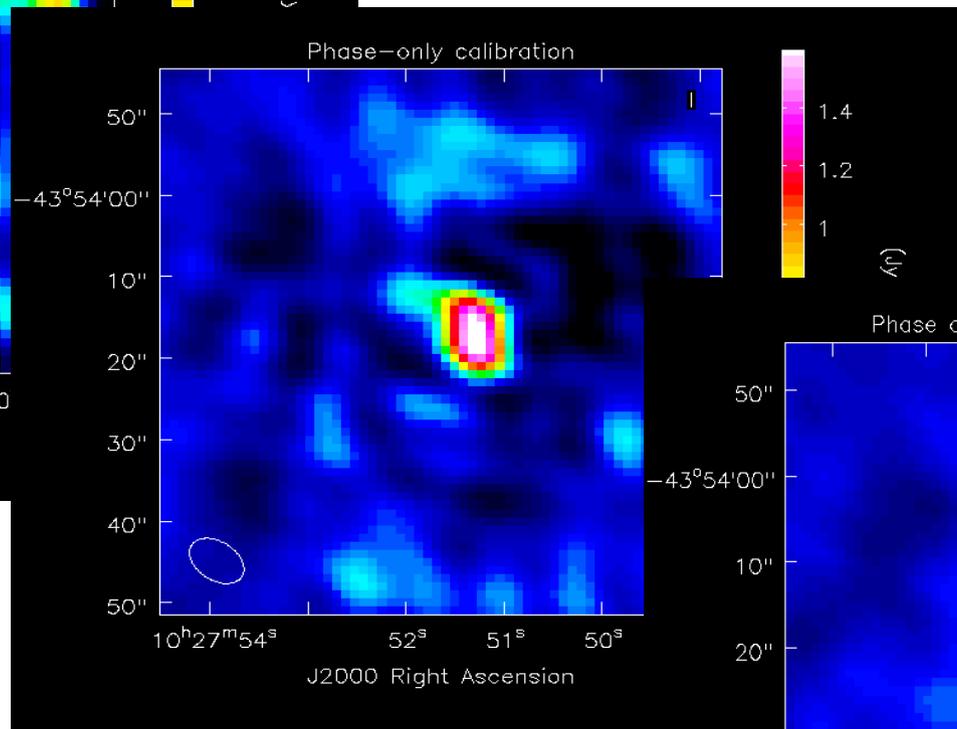
phase



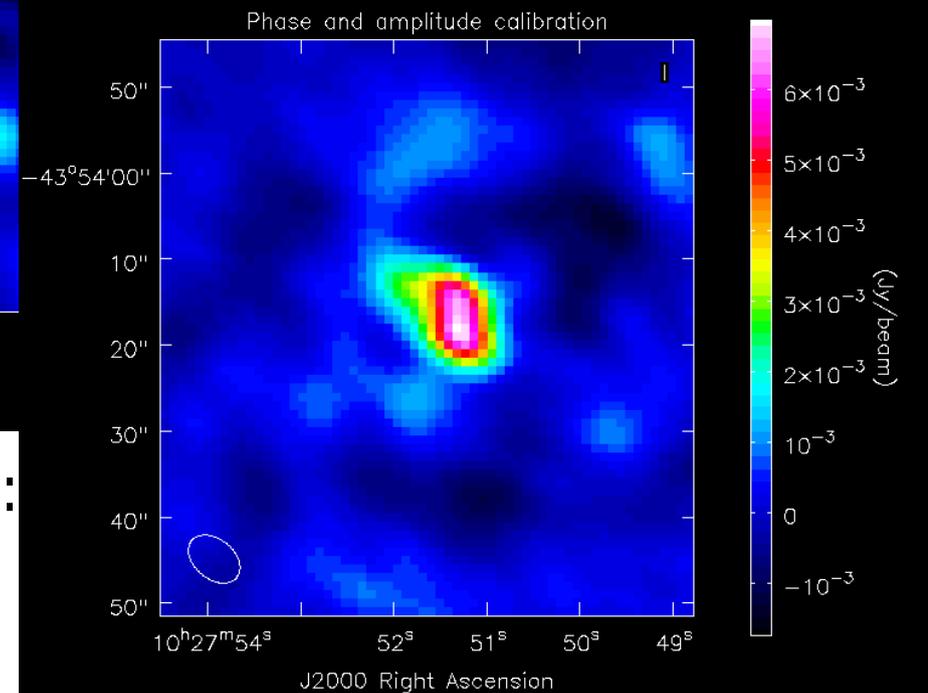
Effects on imaging



No astrophysical
calibration:
no source seen



Phase-only solutions:
source seen, snr 15



Amplitude and
phase solutions:
source seen,
snr 22

CASA calibration: Measurement Equation

$$\underline{V}_{ij} = \mathbf{M}_{ij} \mathbf{B}_{ij} \mathbf{G}_{ij} \mathbf{D}_{ij} \int \mathbf{E}_{ij} \mathbf{P}_{ij} \mathbf{T}_{ij} \mathbf{F}_{ij} S \underline{I}_v(l, m) e^{-i2\pi(u_{ij}l + v_{ij}m)} dl dm + \underline{A}_{ij}$$

Vectors

\underline{V} visibility = $f(u, v)$

\underline{I} image

\underline{A} additive baseline error

Scalars

S (mapping \underline{I} to observer polarization)

l, m image plane coords

u, v Fourier plane coords

i, j telescope pair

Starting point

Goal

Methods

Jones Matrices

Hazards

\mathbf{M} Multiplicative baseline error

\mathbf{B} Bandpass response

\mathbf{G} Generalised electronic gain

\mathbf{D} term (pol. leakage)

\mathbf{E} (antenna voltage pattern)

\mathbf{P} Parallactic angle

\mathbf{T} Tropospheric effects

\mathbf{F} Faraday rotation

Visibility data: Measurement Set format

MAIN	Model, e.g.:	Corrected data	Flags
Original visibility data	<i>FT of image made from MS</i> <i>FT of supplied model image</i> <i>FT of point flux density</i>	<i>Copy of visibilities with calibration tables applied</i> (Used in imaging not calibration)	(Edits are stored here first; backup tables can be made and used to modify)

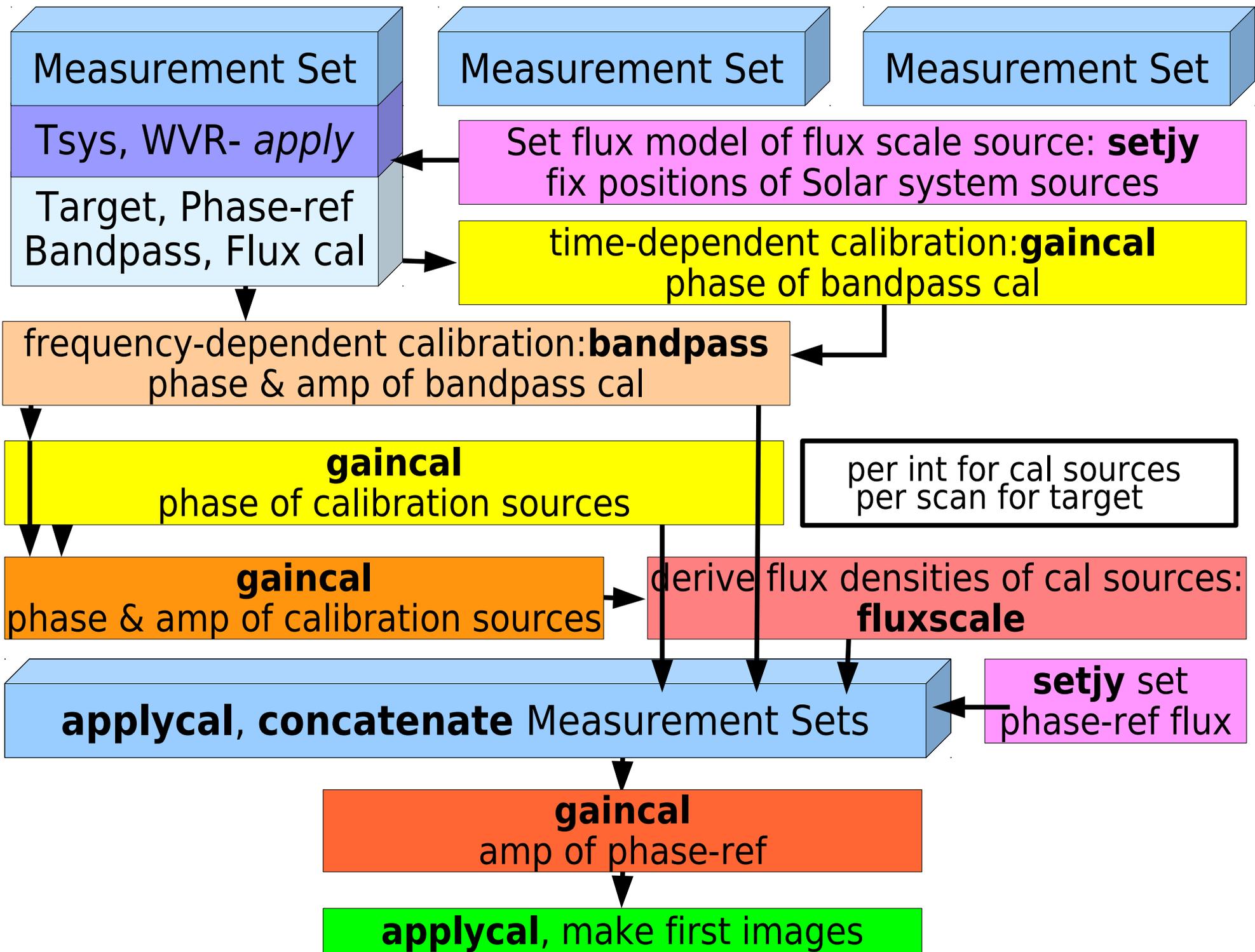
- Unix-like directory structure with binary data and ascii metadata files arranged in subdirectories
- Additional tables in MS and free-standing:
 - *Admin*: Antenna, Source etc.
 - *Processing*: calibration, flags, etc.
- ~interconvertible with FITS; similar image format

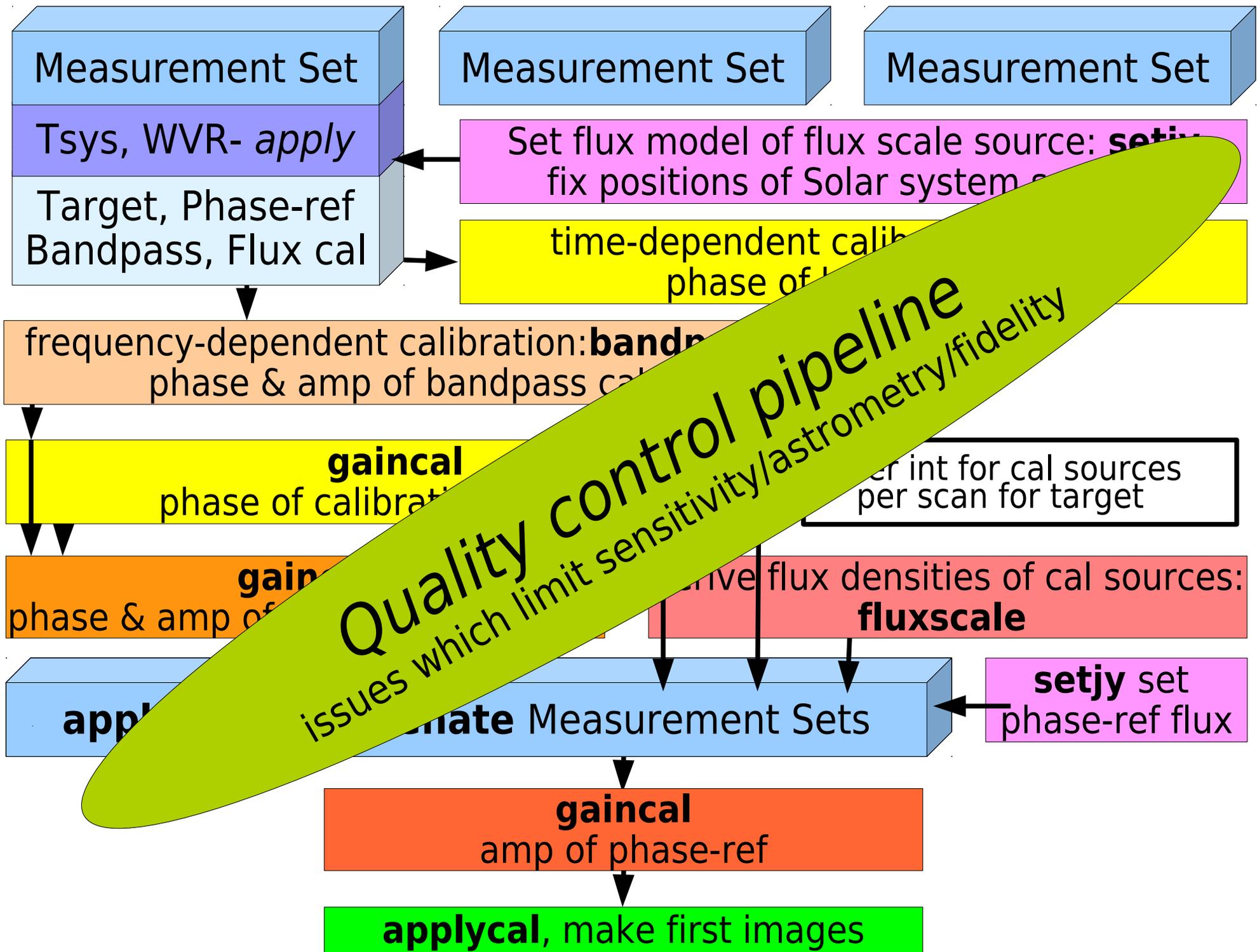
Measurement Set MAIN table

The screenshot shows the 'Table Browser' window for the file '3C277.1C.ms'. The table contains the following columns: UVW, FLAG, WEIGHT, ANTENNA1, ANTENNA2, EXPOSURE, FIELD_ID, TIME, and DATA. The 'DATA' column for row 53 is highlighted, and a callout box shows the value: '3C277.1C.ms[53, 21] = Complex Array of size [4 1]'. The array is displayed as follows:

	0
0	(-0.164379,-2.63613)
1	(0.446854,0.111045)
2	(-0.0716612,0.223381)
3	(-2.49088,-0.869153)

- Some of the columns per visibility measurement
 - Correlated amp & phase per baseline per integration
- **Data:** Complex value per spectral channel for each polarization (XX YY XY YX)





Time jargon

Total integration time = 456357 seconds

Observed from 15-Apr-1995/17:13:58.0 to 20-Apr-1995/
(UTC)

Timerange (UTC)	Scan	FldId	FieldName	nVis	Int(s)
17:13:58.0 - 17:28:38.0	1	0	3C286	1665	7.99
17:29:38.0 - 18:29:30.0	2	1	OQ208	6750	7.99
.....					
17:07:38.0 - 17:09:54.0	8	10	1300+580	270	7.99
17:10:37.0 - 17:17:49.0	9	11	3C277.1	825	7.99
17:18:36.0 - 17:19:56.0	10	10	1300+580	165	7.99
17:20:35.0 - 17:27:55.0	11	11	3C277.1	840	7.99
17:28:42.0 - 17:29:54.0	12	10	1300+580	150	7.99

- **Time on all sources**
- **Span** of observations (might be gaps)
- Flux scale/polarisation calibration **scans**
- Alternate phase-ref/target **scans**
- Single **integration time**

- Estimate hour angle coverage
- An integration is the shortest averaging time in correlated data
- A scan is usually the time between source changes
 - The phase-ref/target cycle should be less than the atmospheric coherence time

Polarization jargon: Rx feeds

CIRCULAR feeds

Left/Right/cross correlations
LL RR LR RL

Stokes V =
 $(RR - LL)/2$

Stokes Q =
 $(RL + LR)/2$

Stokes U =
 $(RL - LR)/2i$

ALMA LINEAR feeds

Correlations

XX, YY, XY, YX

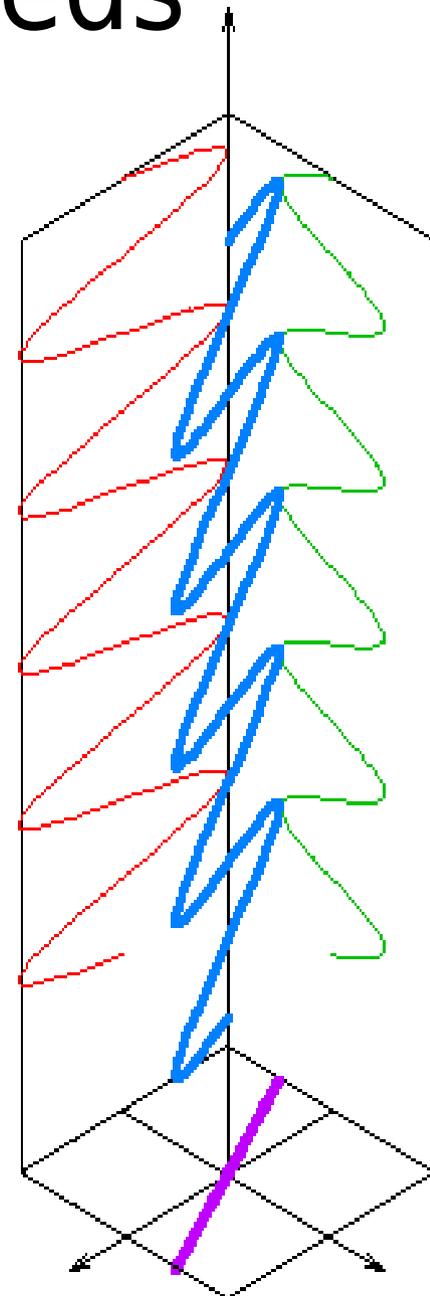
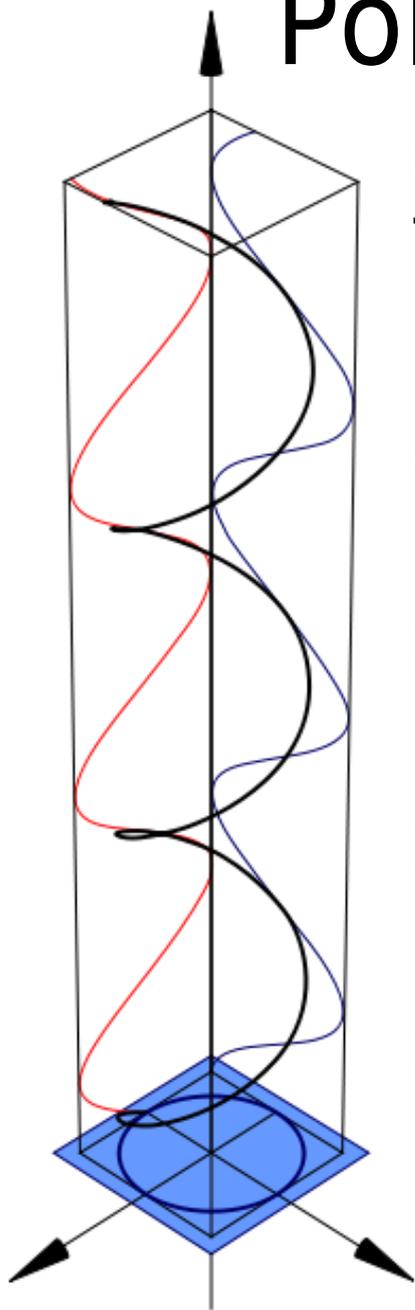
Stokes Q =
 $(XX - YY)/2$

Stokes U =
 $(XY - YX)/2$

Stokes V =
 $(XY - YX)/2i$

Polarized intensity P
 $= \sqrt{Q^2 + U^2 + V^2}$

Polarization angle χ
 $= \frac{1}{2} \text{atan2}(U/Q)$

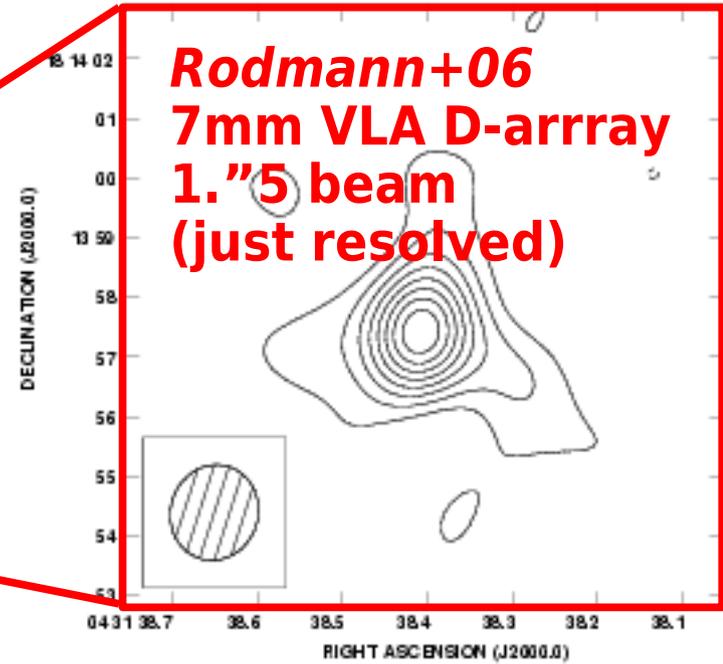
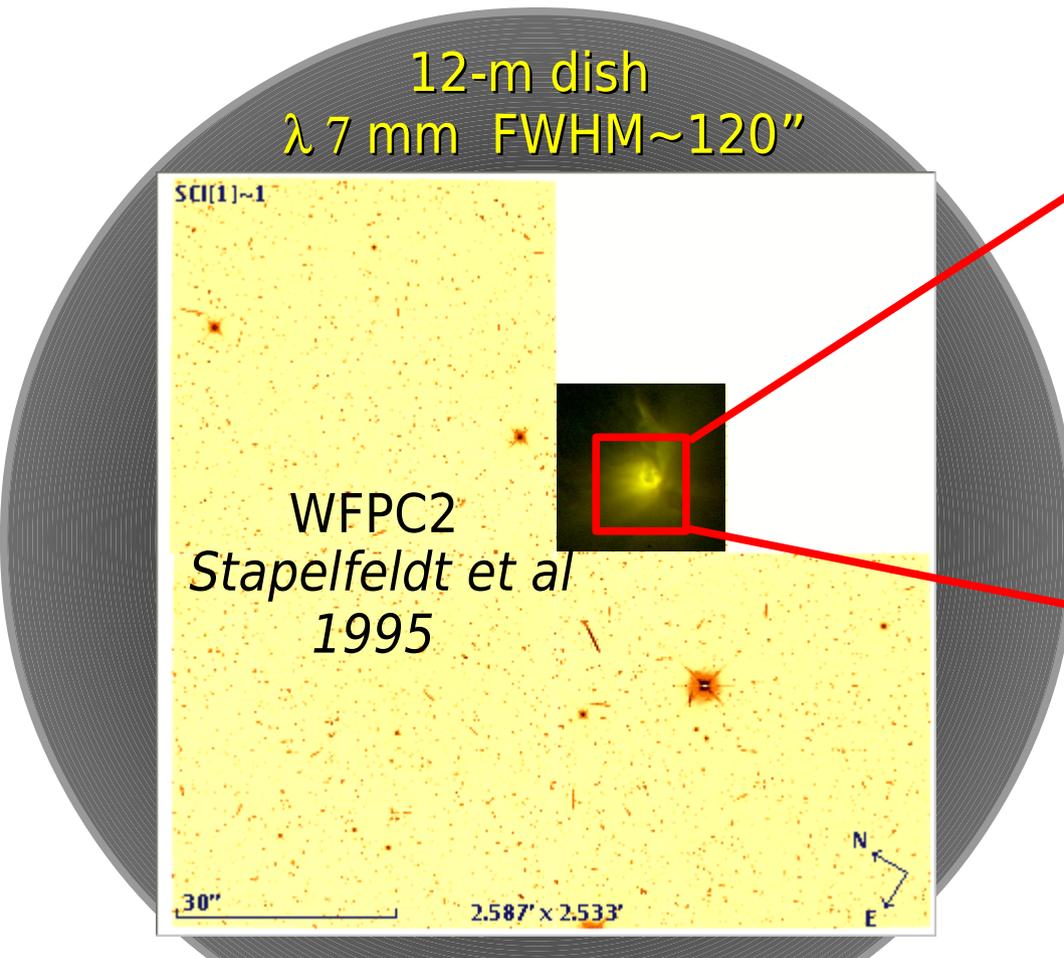


Diagrams thanks to Wikipedia

Brightness temperature

- Brightness temperature $T_b = S_{\text{source}} 10^{-26} \lambda^2 / 2k_B \Omega$
 - S (Jy) in single dish beam area Ω_{SD} (sr) at λ (m)
 - Resolved by SD? $\Omega = \Omega_{\text{SD}}$
 - Unresolved? $\Omega =$ estimated true (smaller) source size
- Predict ALMA flux density per synthesized beam θ_b
 - $S_{\text{ALMA}} = T_b 2k_B \Omega_{\text{ALMA}} / 10^{-26} \lambda^2$
 - Now $\Omega_{\text{ALMA}} = \theta_b^2$
 - Use **Sensitivity Calculator**
 - At least $5\sigma_{\text{rms}}$ on peak and $3\sigma_{\text{rms}}$ on any extended details
- Check ALMA maximum spatial scale
 - Use **OST** or **CASA** simdata to check imaging fidelity

HL Tau on arcmin-arcsec scales



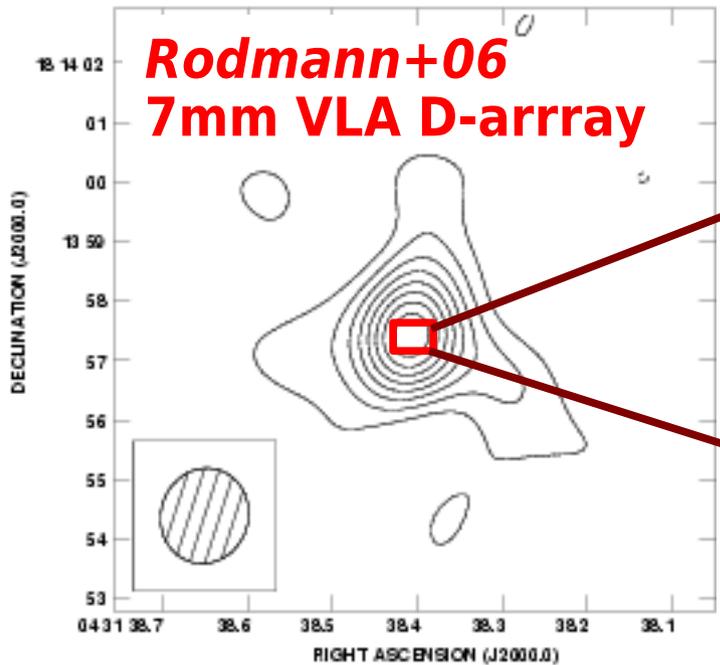
- Total 5 mJy in 0.57 asec^2
- $T_b \sim 10 \text{ K}$ average in 0.57 asec^2

- $T_b = [(S/\text{Jy}) 10^{26} (\lambda/\text{m})^2] \div [2 k_B \Omega/\text{Sr}]$

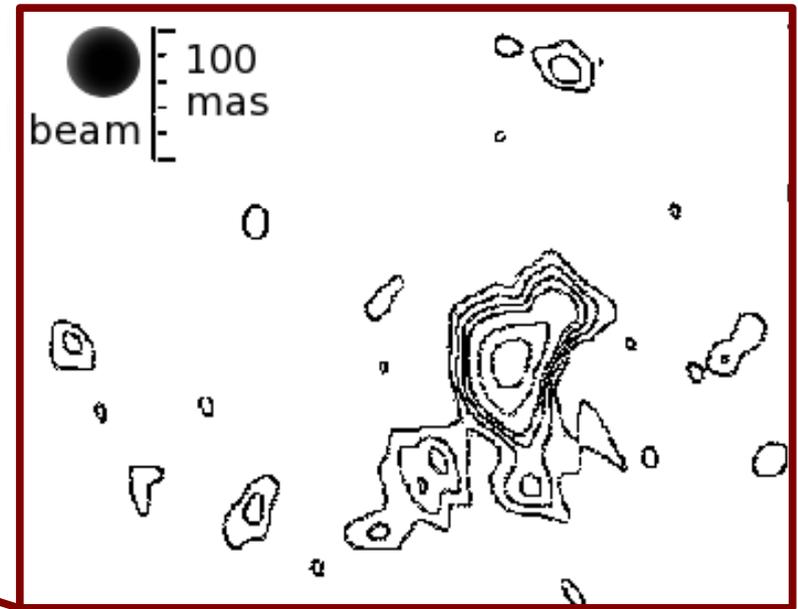
- Area Ω is *smaller* of (actual size) or (beam size)

- *Smooth* 5mJy in whole $120''$ would be $\sim 1 \mu\text{Jy}/1."5 \text{ beam}$

HL Tau on sub-arcsec scales

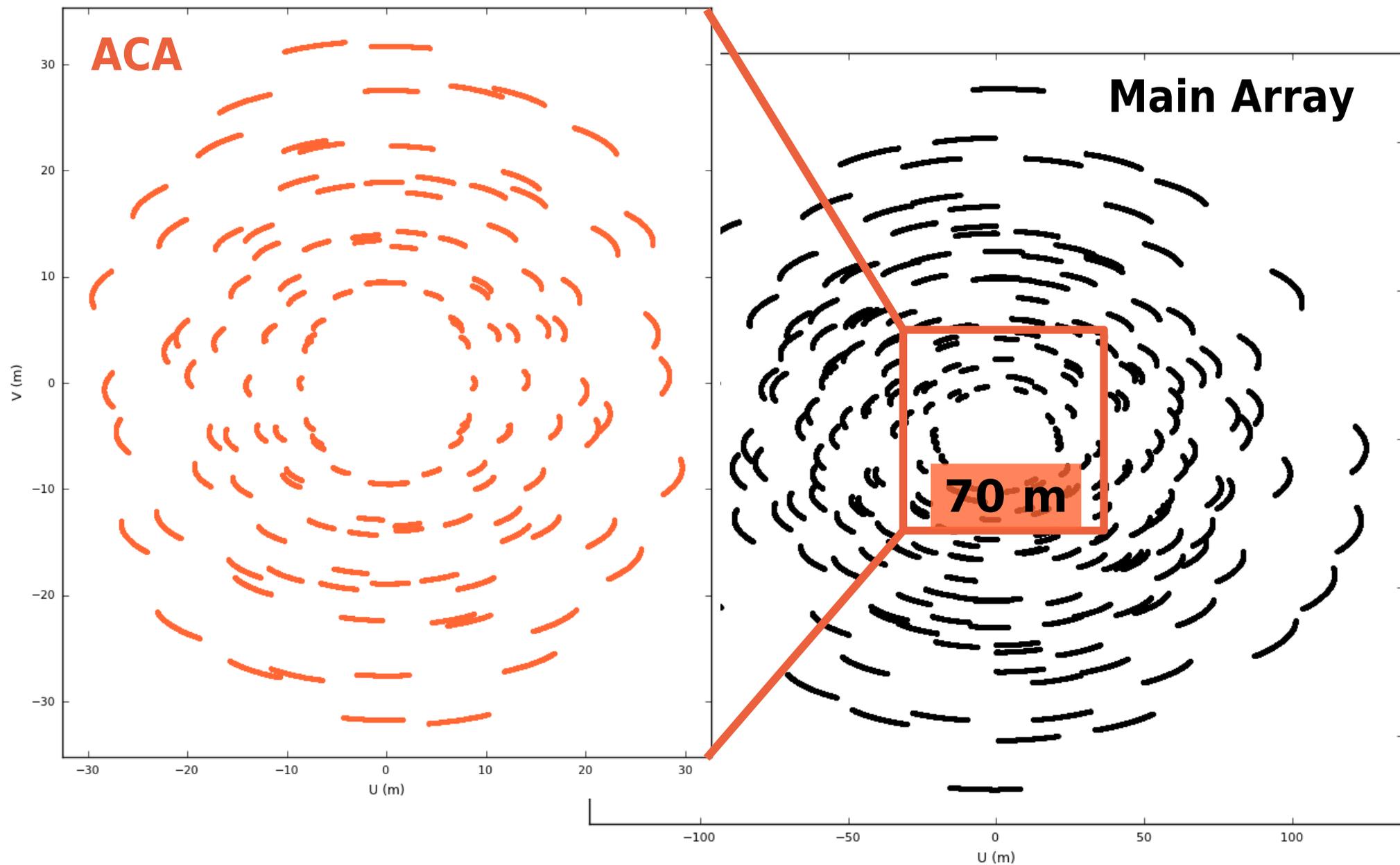


Carrasco-Gonzalez+09
7mm VLA A-array
50-mas beam



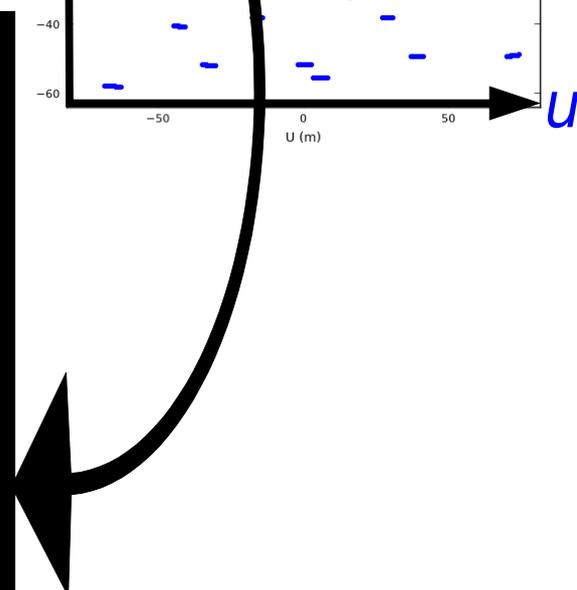
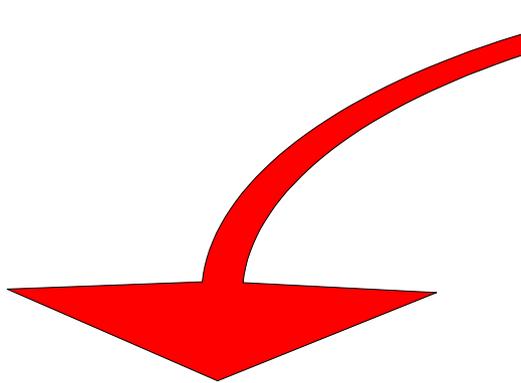
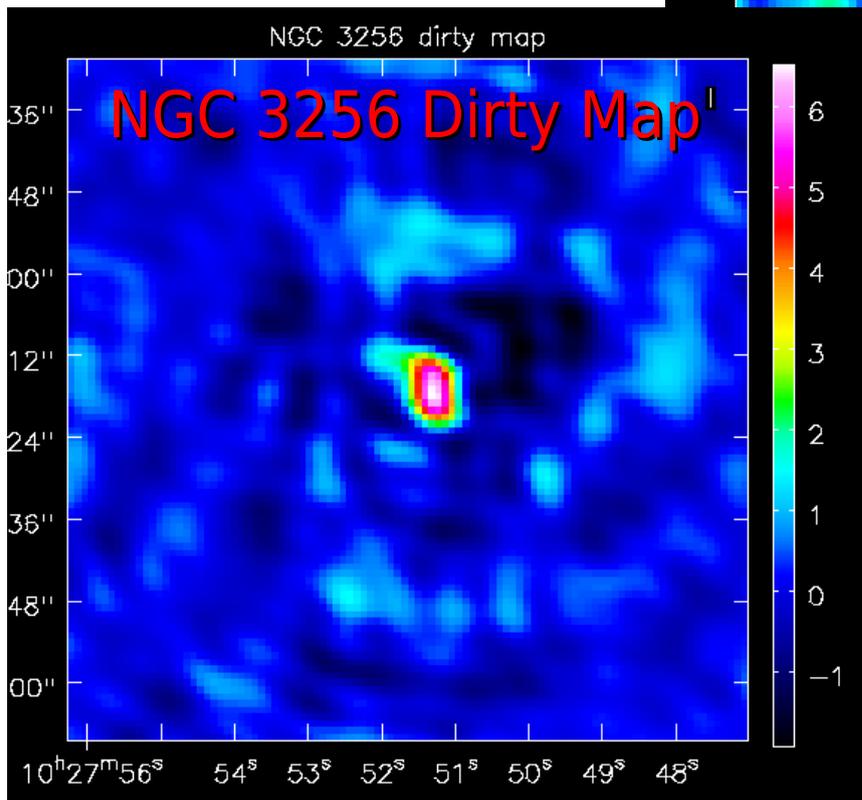
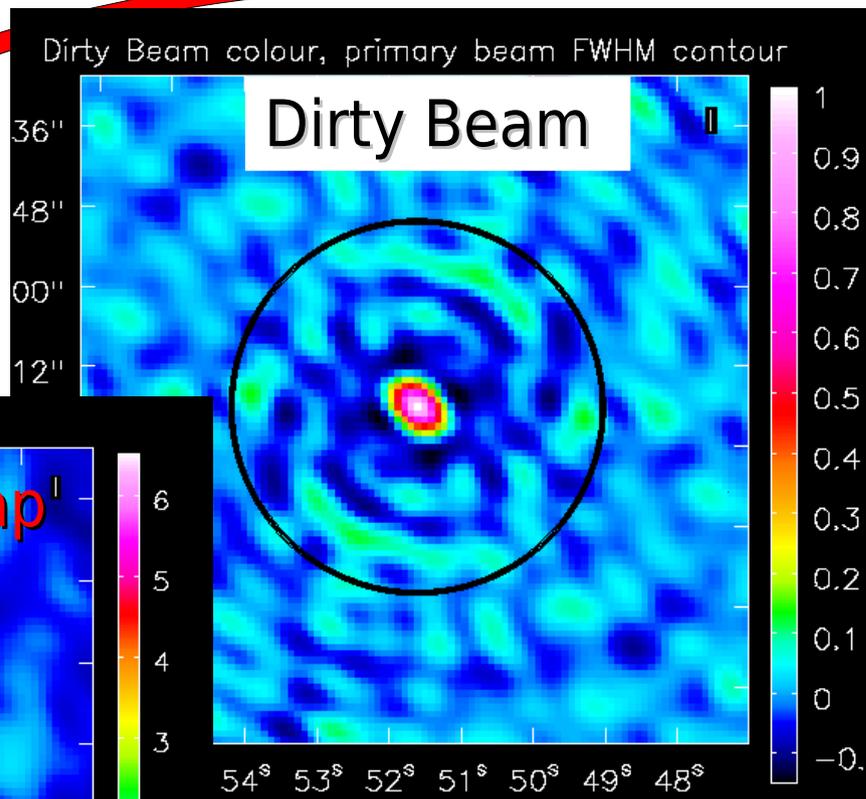
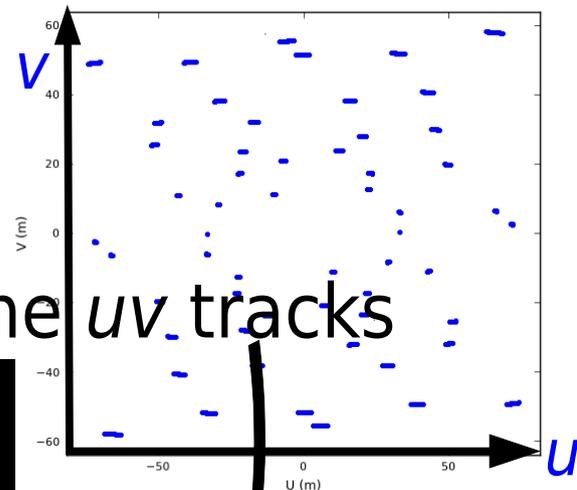
- D-array lowest contour 0.3 mJy in 1500-mas beam
 - Peak ~ 3 mJy in ~ 200 mas diameter $\equiv 0.18$ mJy in 50-mas
- A-array lowest contour 0.15 mJy in 50-mas beam
 - Missing *smooth, extended* bright flux: missing spacings
 - Missing *sub-asec* flux: small beam \Rightarrow higher T_b threshold

Solution: include ACA (also TP)



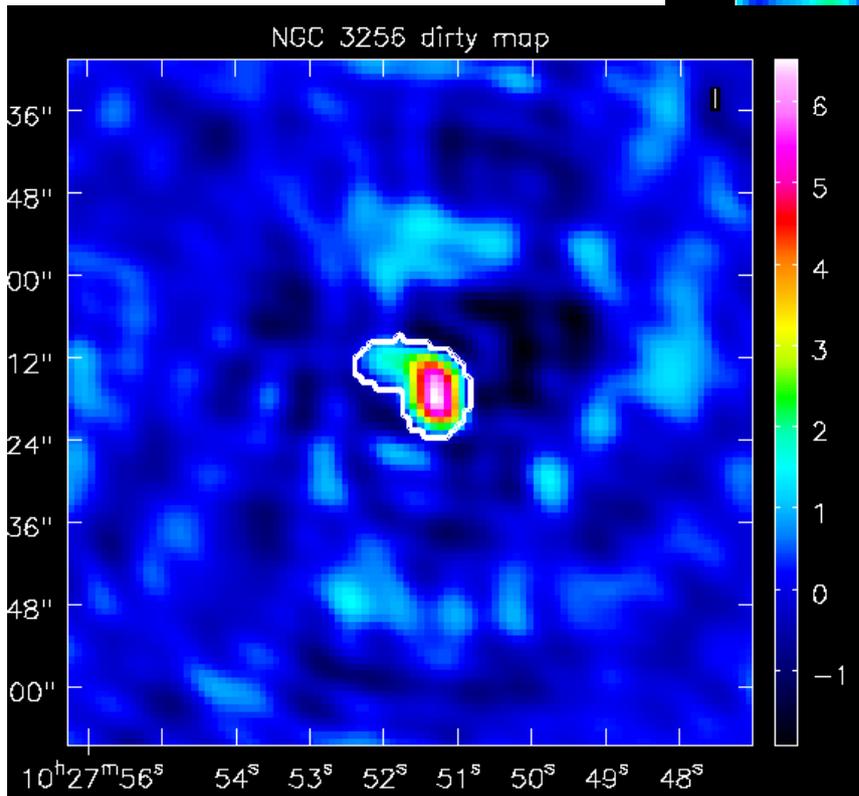
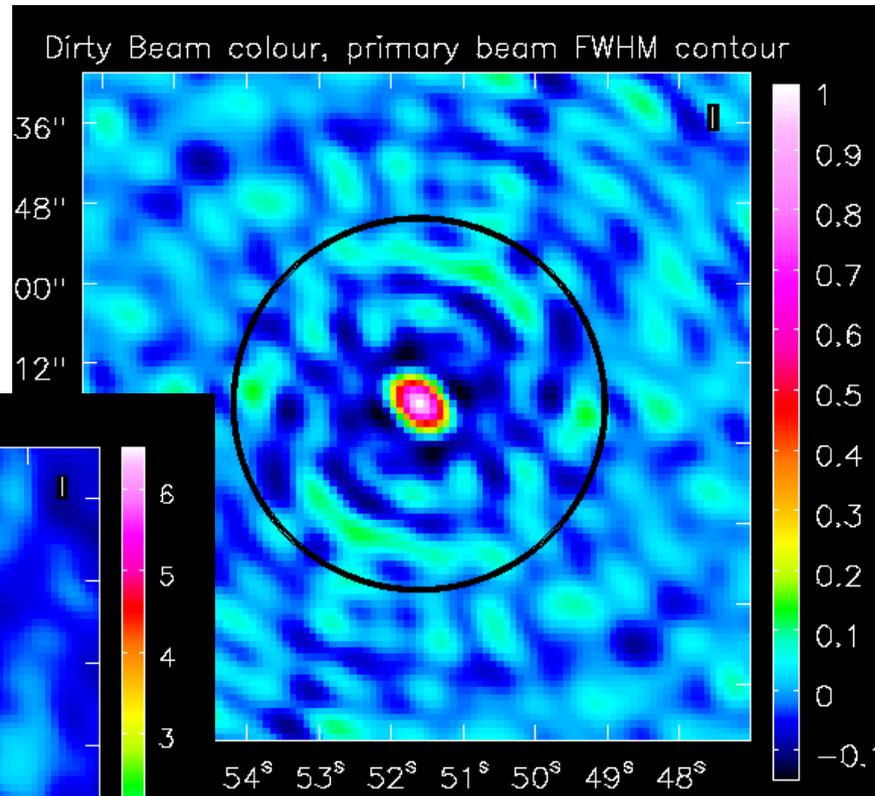
Cleaning

- Fourier transform the **visibilities** and the *uv* tracks



Cleaning

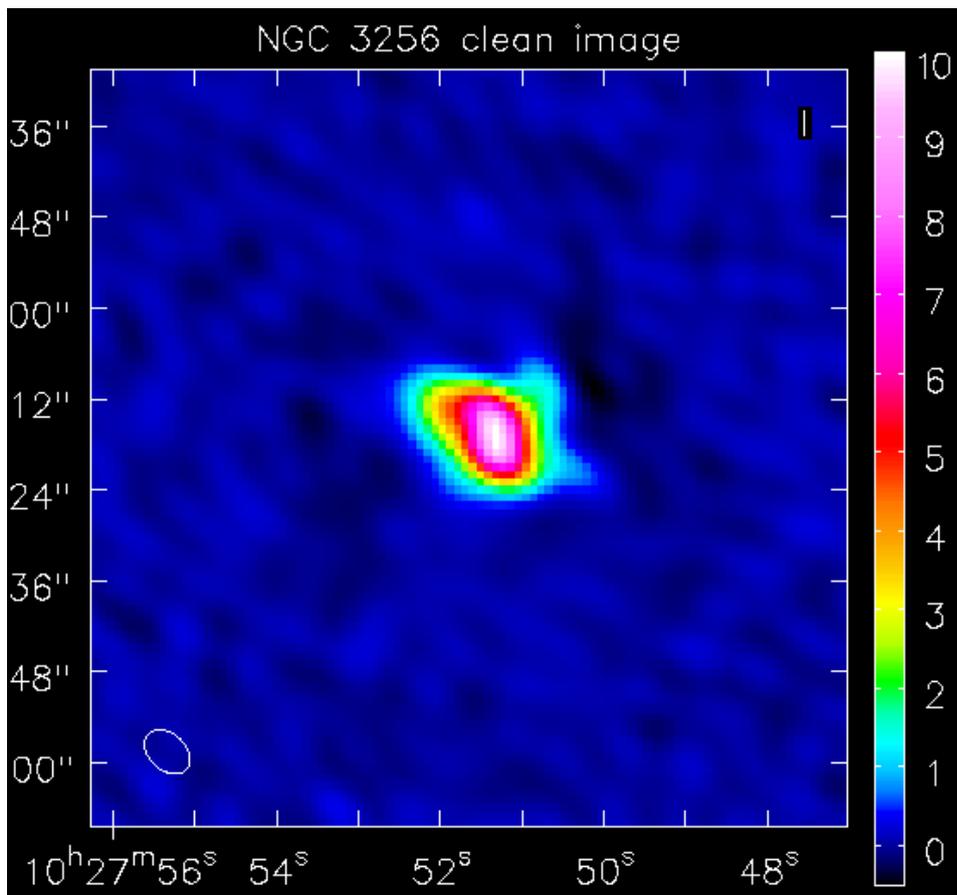
- Fourier transform the visibilities and the uv tracks
- Set a mask to include obvious emission



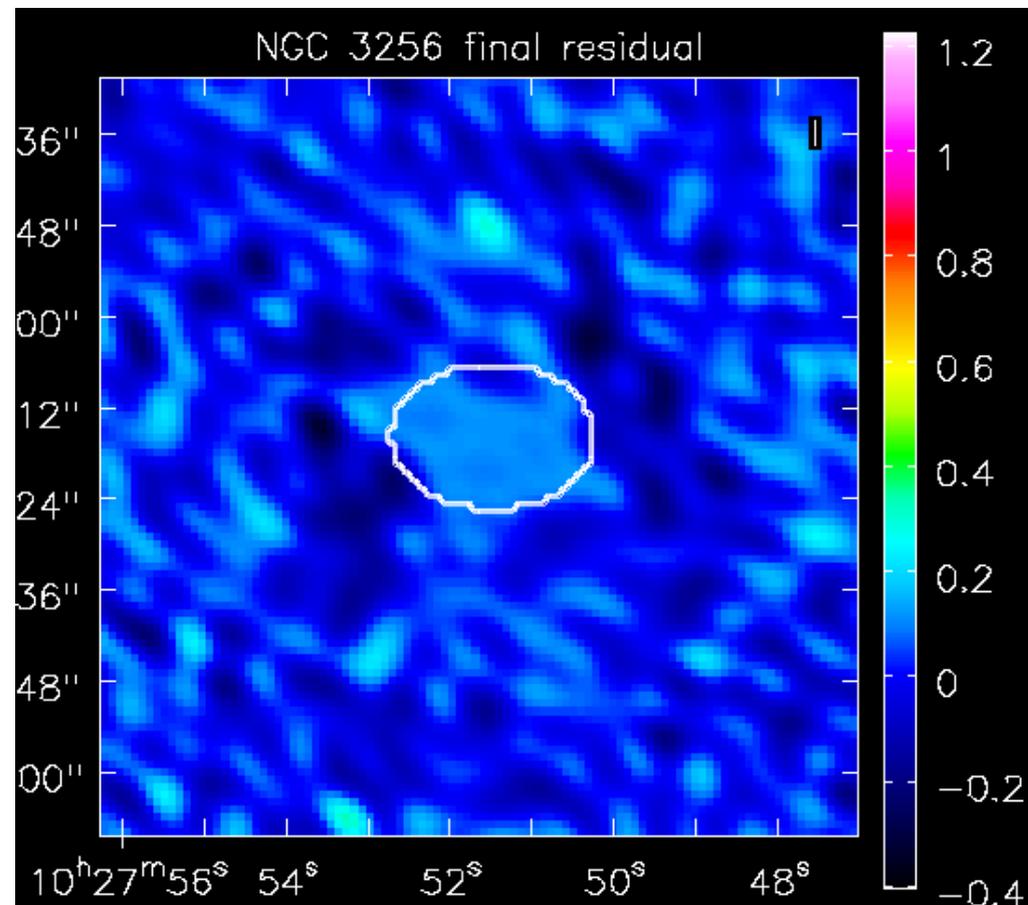
- CLEAN algorithm identifies brightest pixels
- Store e.g. 10% of each peak as Clean Component

CLEANed image

- Improved signal-to-noise in final image

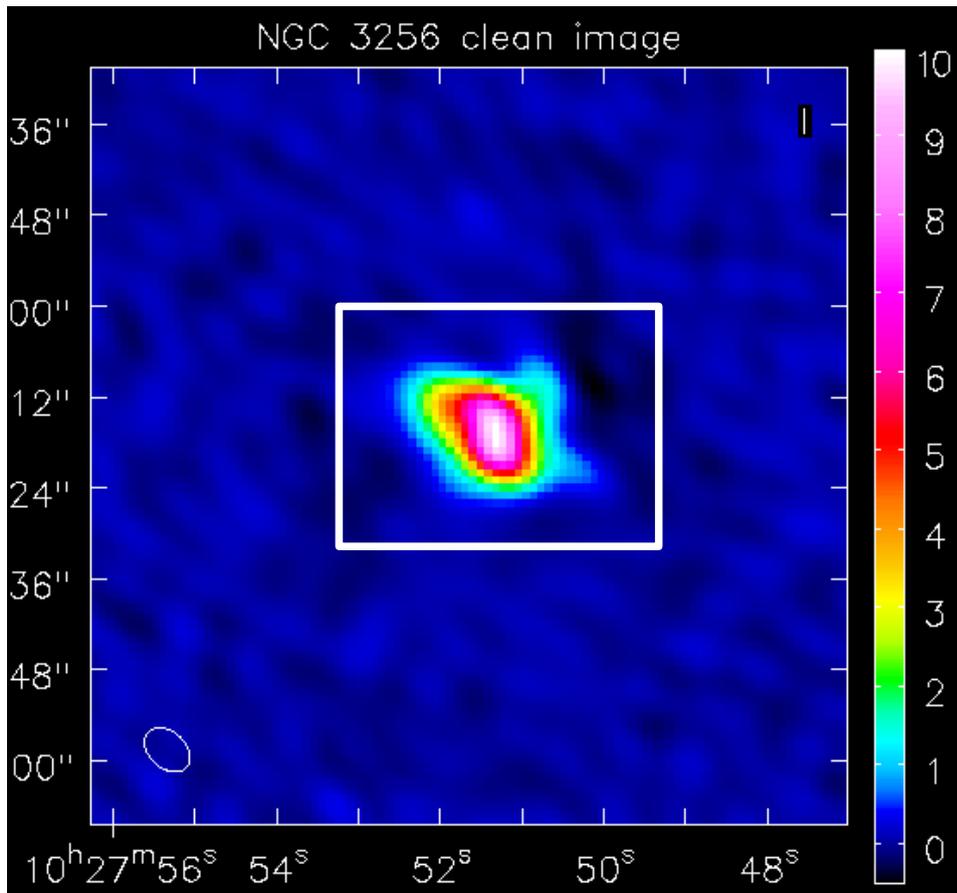


- Residual is just noise
 - Note different flux scale

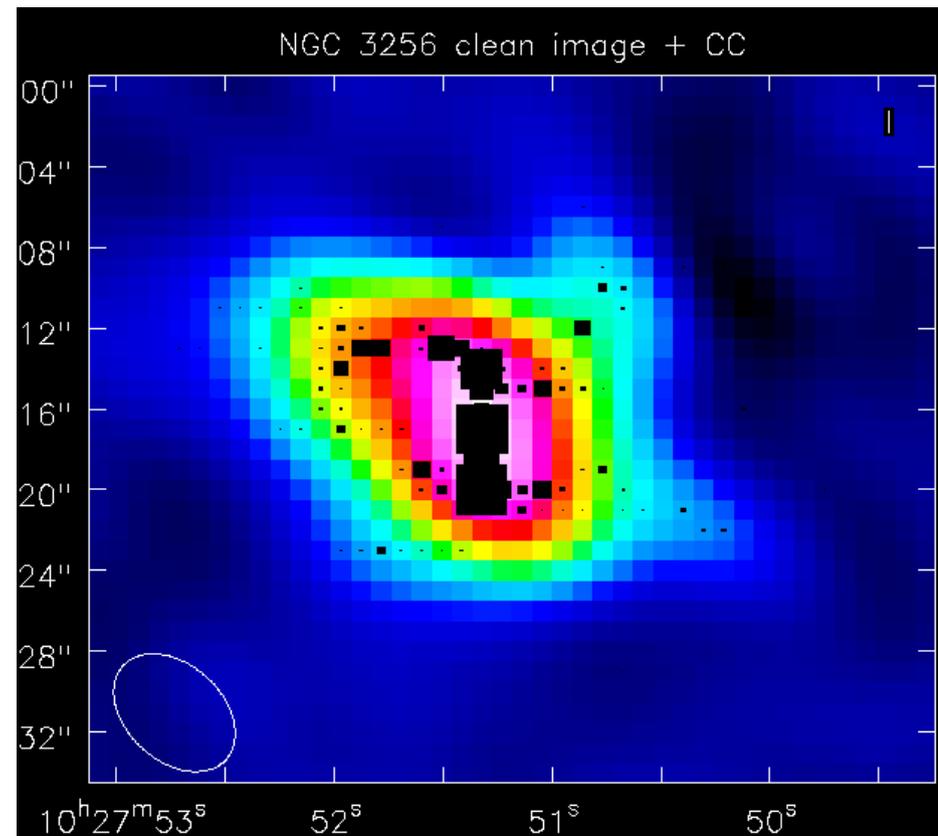


CLEANed image

- Note improved signal-to-noise in image

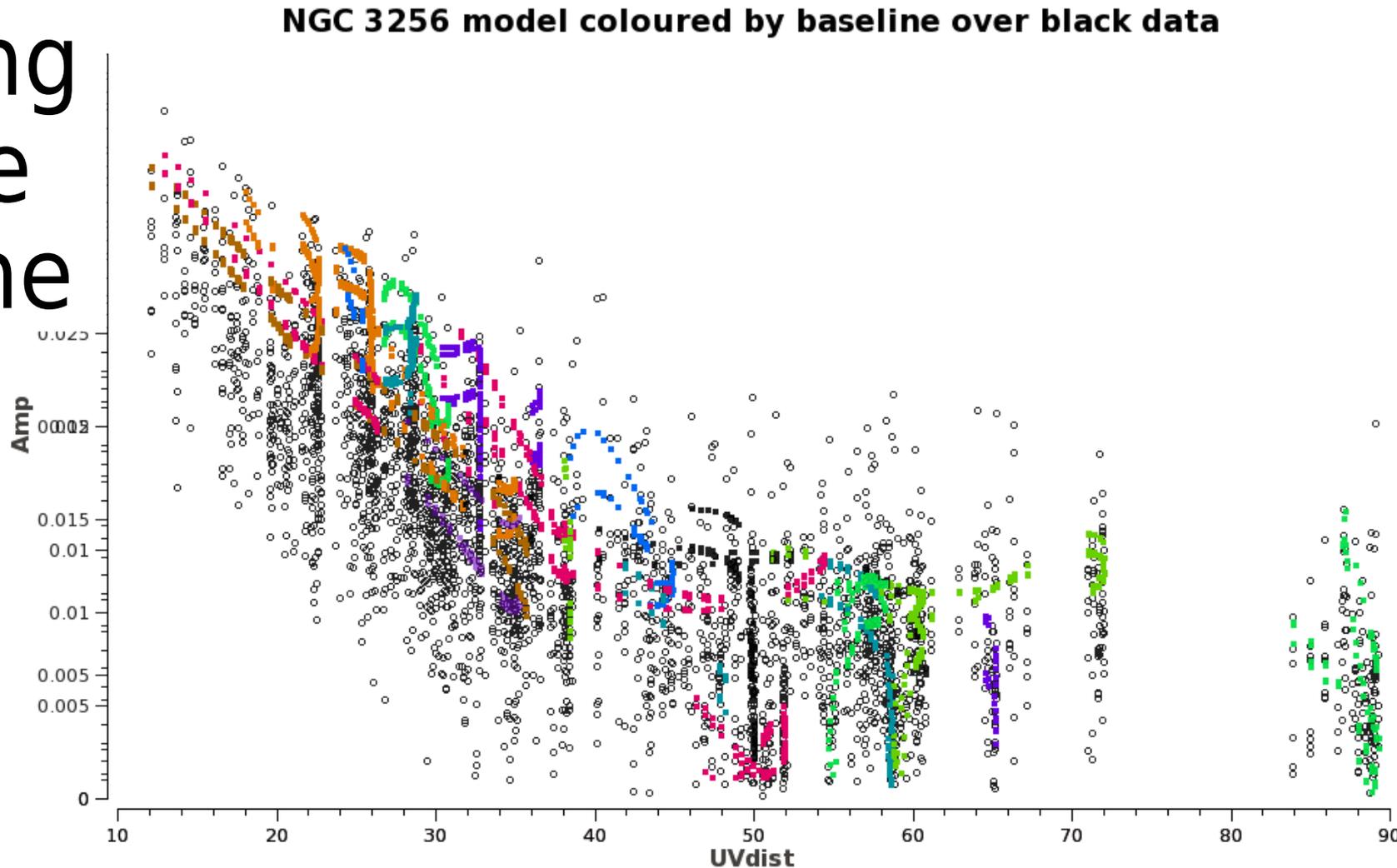


- Final image is combination of residual and Clean Components convolved with restoring beam



- NB if snapshot, extended array, narrow channels....
 - Sparse *uv* coverage can limit dynamic range

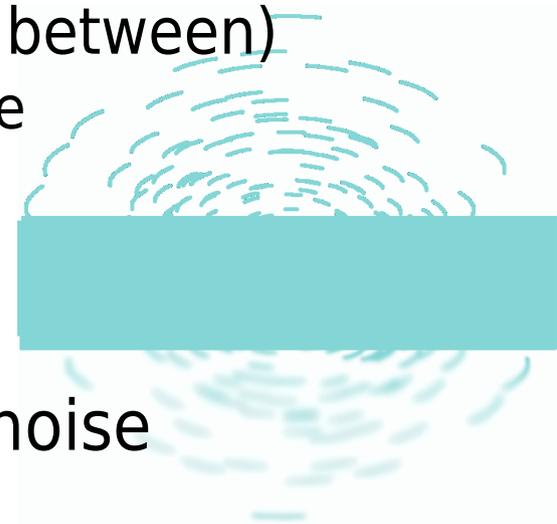
Cleaning and the *uv* plane



- *uv* model (colour) is FT of Clean Components
 - 'Major Cycles' subtract model from *uv* data and re-make dirty residual image
- Compare model with data to assess quality
 - Use for further rounds of self-calibration

Weighting

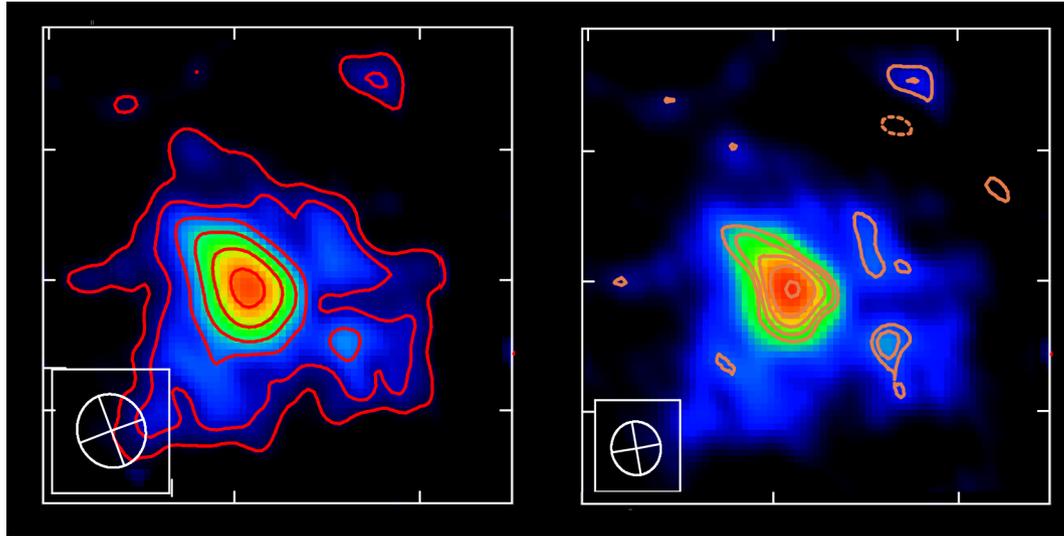
- Each visibility has a weight:
 - Intrinsic, for same t_{int} , T_{sys} etc.:
 - ACA baseline has noise $12^2/7^2 \times 12\text{-m}$ baseline
 - Single 12-m TP dish has noise $\sqrt{2} \times 12\text{-m}$ baseline
 - Different N_{samples} per averaged integration/channel
 - Variance of calibration solutions
- Weights can be adjusted further during imaging
 - Grid samples in uv plane
 - Natural: Original samples per cell (empty between)
 - Maximum sensitivity to extended structure
 - Uniform: Extrapolate uniformly
 - Finest resolution, worse noise
 - Intermediate (robust parameter)
 - Change resolution $\lesssim 2x$ at cost of higher noise



Weighting

- **Natural:**

- 110-mas resolution,
 3σ 51 $\mu\text{Jy/bm}$



- **Uniform:**

- 80-mas resolution,
 3σ 63 $\mu\text{Jy/bm}$

HL Tau *Greaves+'07*

- Weights can be adjusted further during imaging

- Grid samples in uv plane

- Natural: Original samples per cell (empty between)

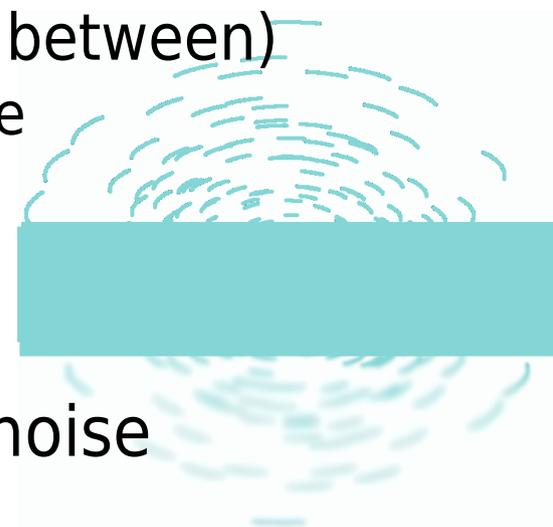
- Maximum sensitivity to extended structure

- Uniform: Extrapolate uniformly

- Finest resolution, worse noise

- Intermediate (robust parameter)

- Change resolution $\lesssim 2x$ at cost of higher noise

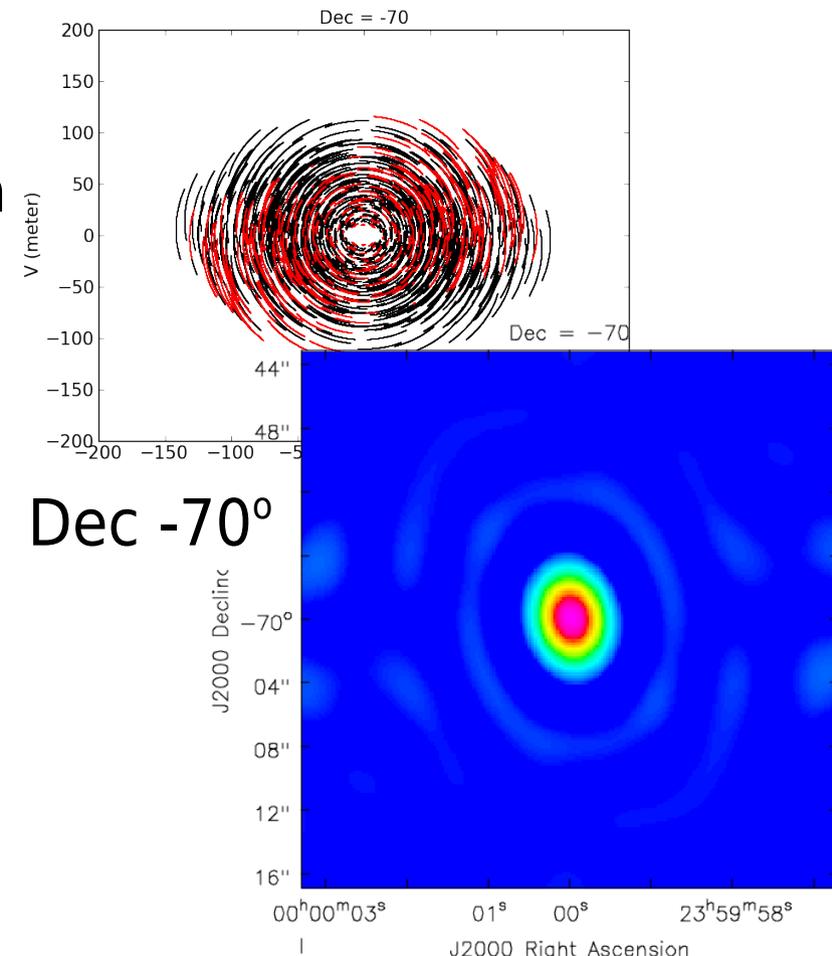
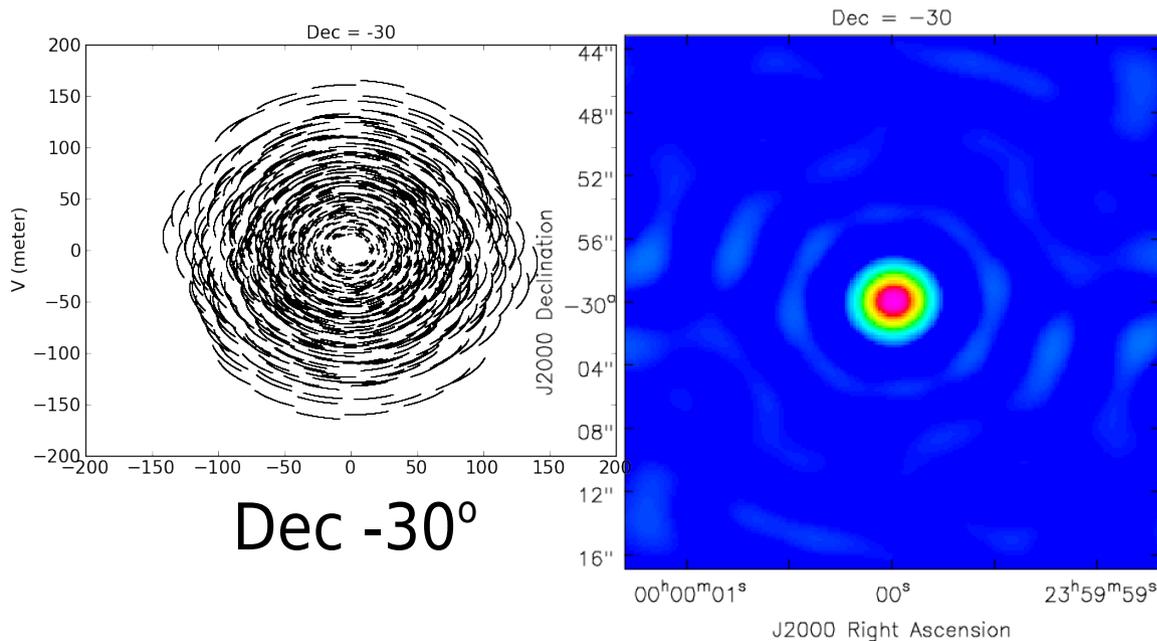


Simulating interferometry data

- CASA tasks
 - `simobserve`, `simanalyse`
 - Any array if antenna configs provided
 - Detailed parameters
 - `simalma`
 - Tailored for ALMA
- Observing Support Tool
 - Based on CASA library, results should be same
 - Web interface, limited inputs
 - Less flexible but easier to use
- Why simulate?
 - Effects of interferometer sampling large structures
 - Dynamic range limitations
 - Mosaicing
 - **But** check predicted noise with sensitivity calculator

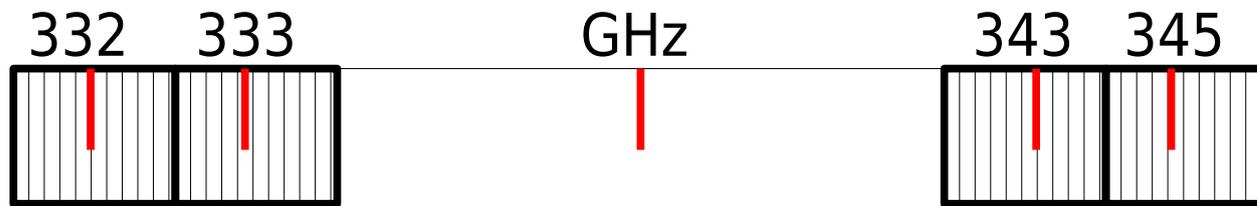
Input for simulations

- See <http://almaost.jb.man.ac.uk/help/>
 - FITS image
 - Required keywords (script available to check):
 - BUNIT, CDELTA_n, CROTA_n, CD_{n_n}, CTYPEN, NAXIS, NAXIS_n
 - Declination
 - Very high/low Dec:
 - Elongated synthesised beam
 - **Shadowing**



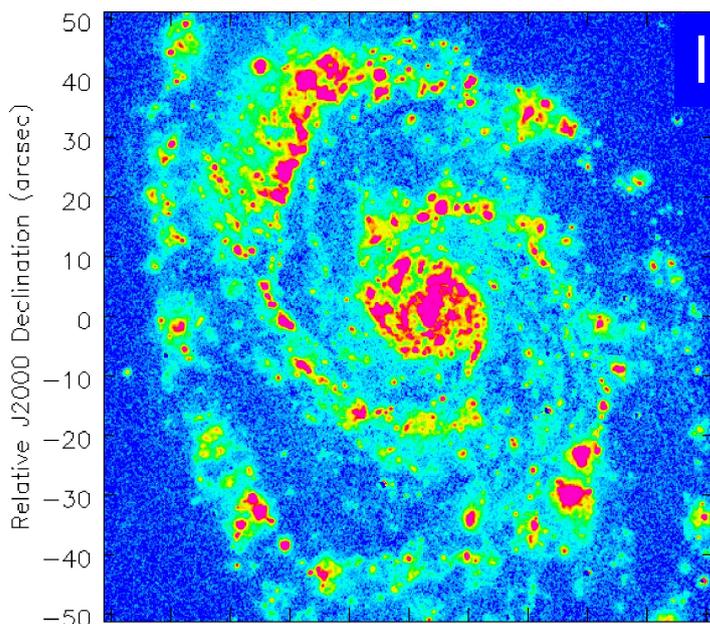
Input for simulations

- Bandwidth, frequency etc.
 - Line: OST handles a single channel only
 - Continuum: OST can adopt optimum place in band
 - NB bands 3,4,6,7,8 full b/w *gap between sidebands*

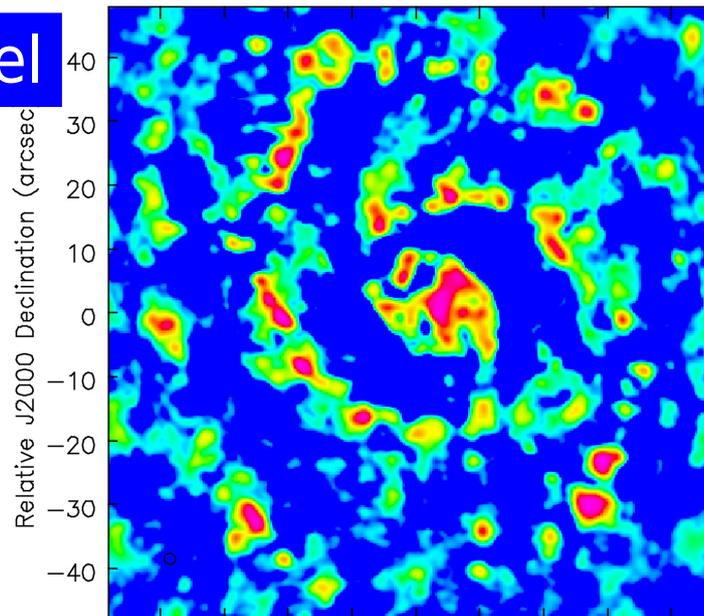


- Automatically mosaics if required by input size
 - Crop large input if you only need a single pointing!
- Resolution: Cycle 2, select array(s) directly
- Peak $\mu\text{m}/\text{Jy}/\text{pixel}$ (to rescale input)
- Time needed to reach sensitivity
- Add noise
 - OST does not simulate phase/amp correction!

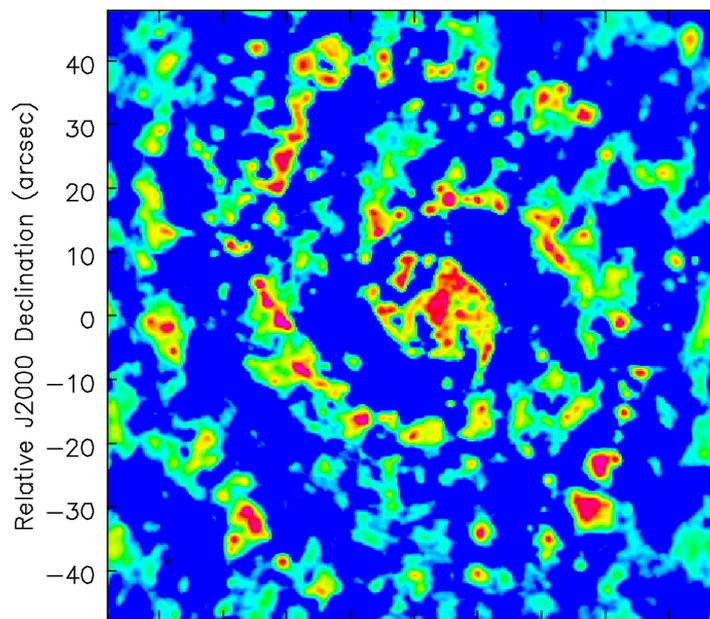
Cycle 2 resolution (scales @100 GHz)



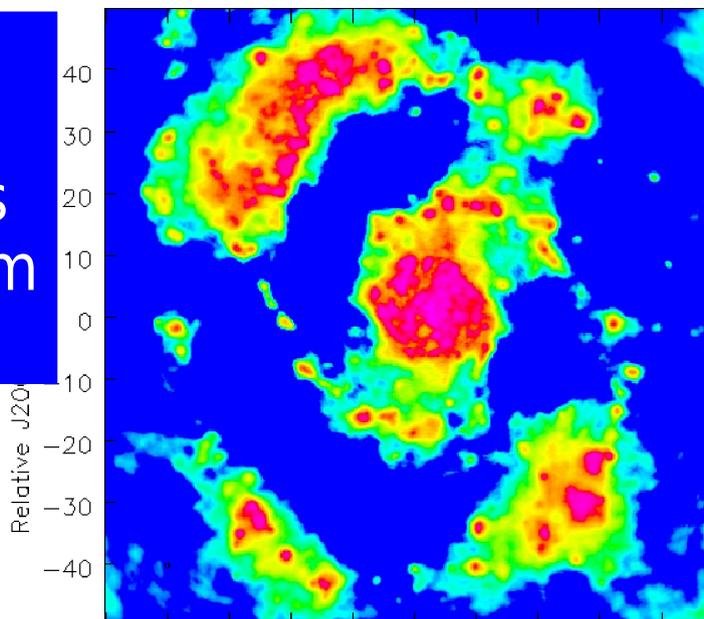
Input model



C34-3
Baselines
21 - 443 m
(1.4-18")



C34-3 +
C34-7
Baselines
21-1508m
(0.5-18")



ACA +
C34-3 +
C34-7
Baselines
9-1508m
(0.5-42")

Add TP for
larger
scales

Relative J2000 Right Ascension (arcsec)

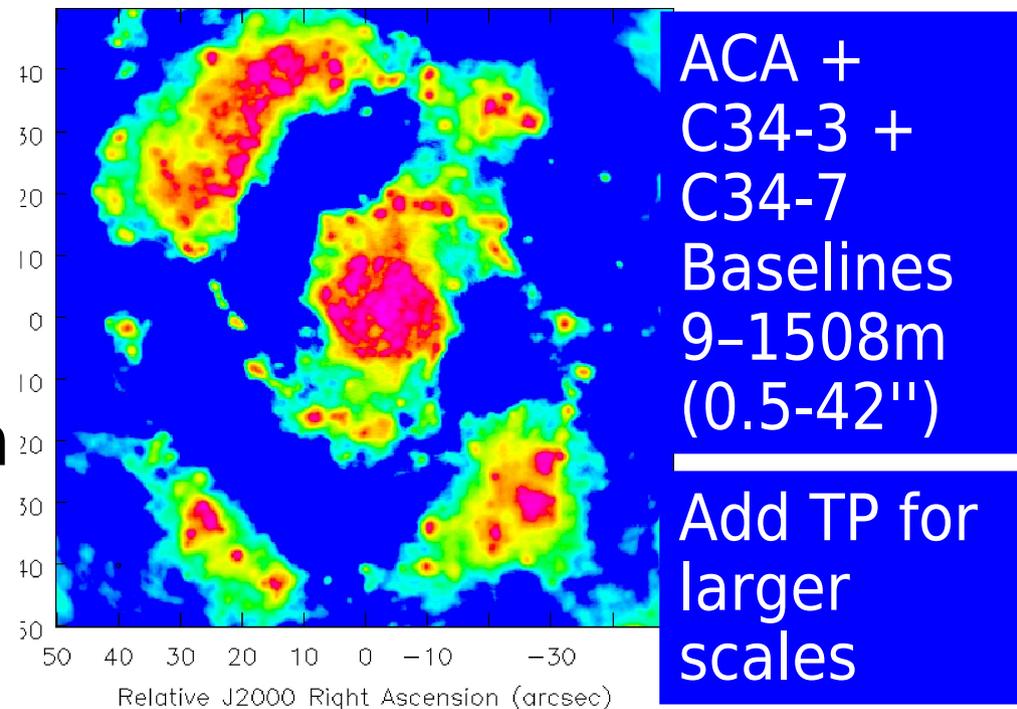
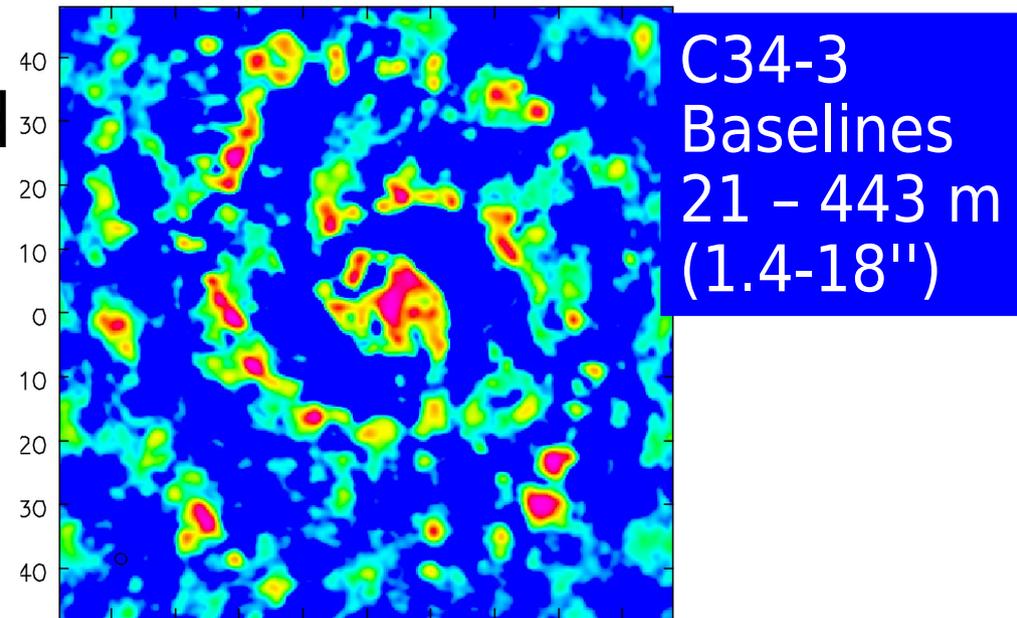
40 30 20 10 0 -10 -30

Relative J2000 Right Ascension (arcsec)

50 40 30 20 10 0 -10 -30

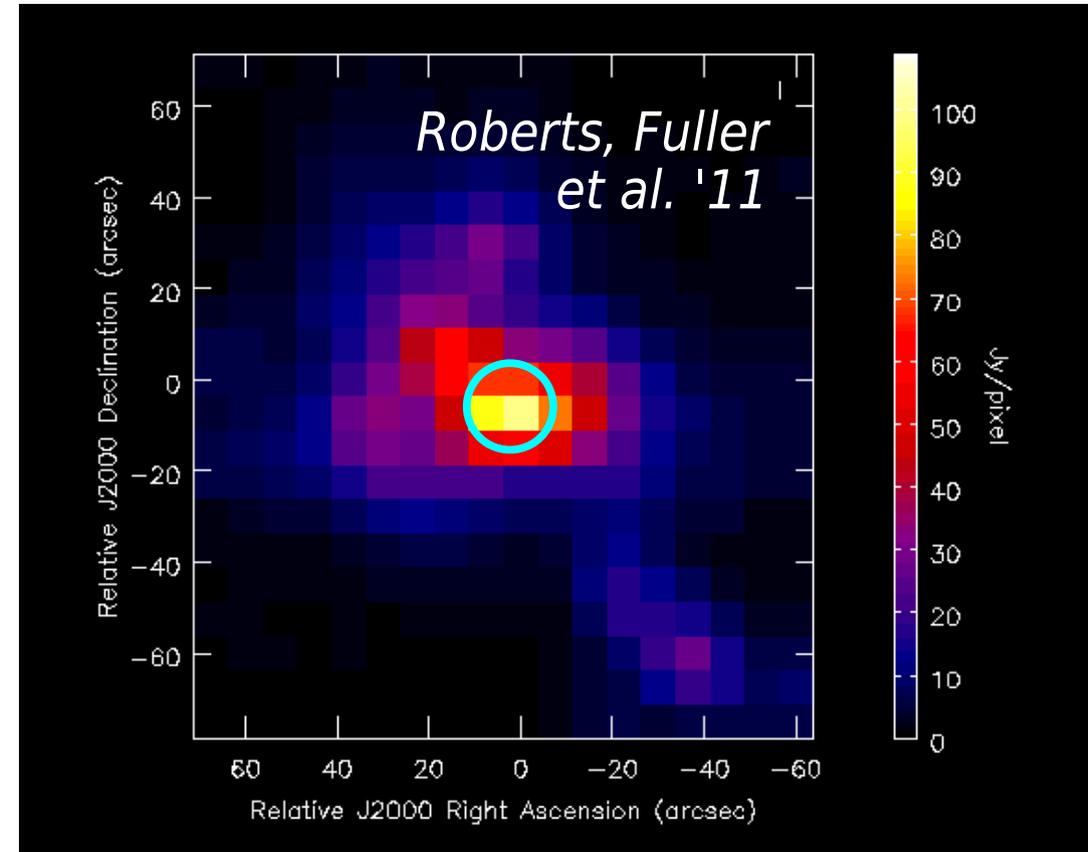
Cycle 2 examples (scales @100 GHz)

- Data for each array supplied separately by OST
 - Adjust weights when combining arrays
 - Further modify resolution by choosing degree of uniform/natural weighting in imaging
- No unique map
 - Vary combinations to emphasize regions of interest
 - Higher resolution can mean higher noise as well as resolving-out extended structure



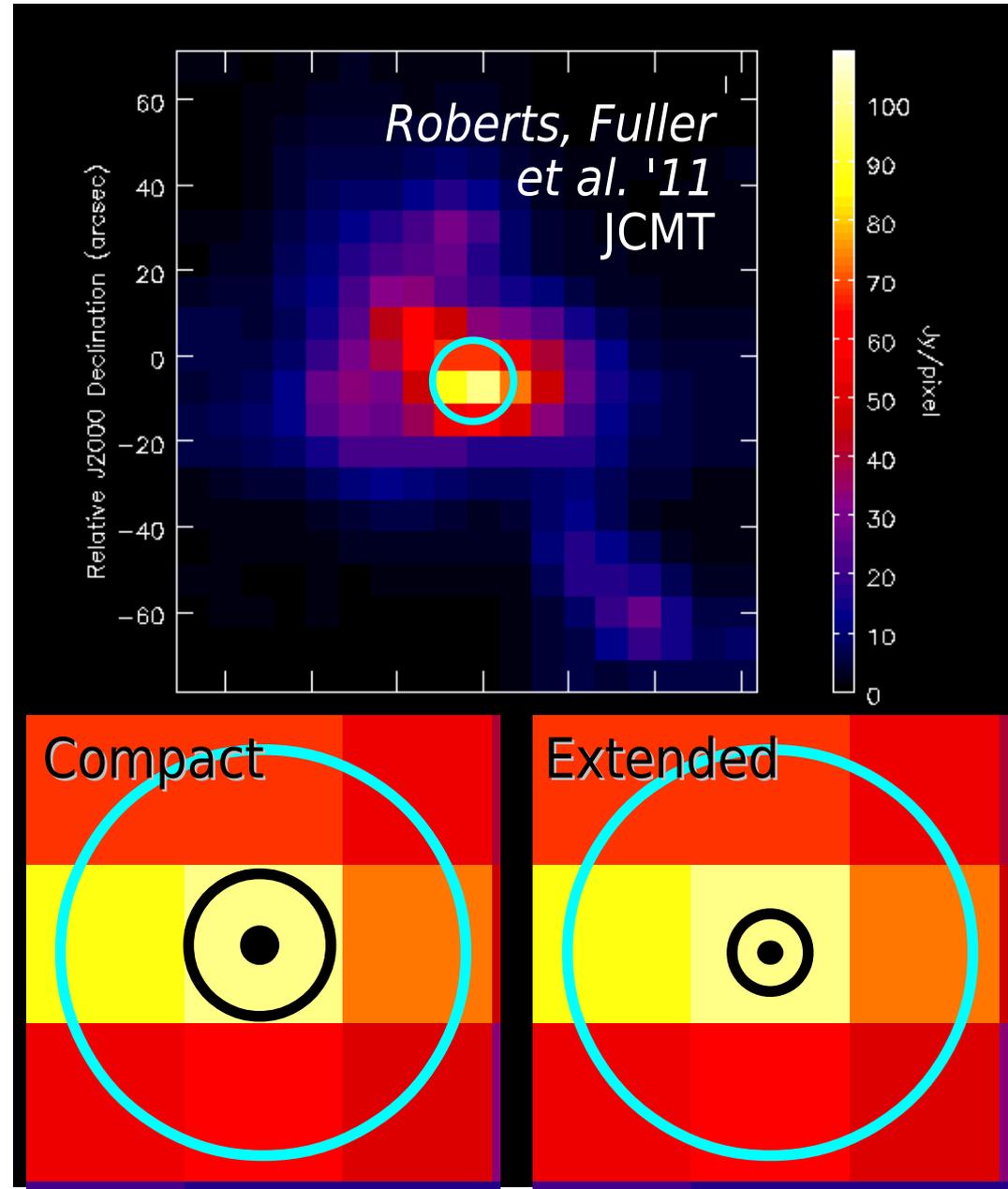
Structure scales

- JCMT single-dish mosaic of source at 11 kpc
 - 7".5 pixels
 - Field of view 150"
 - Peak 100 Jy/ 7".5 pixel
 - 354 GHz = λ 0.85 mm



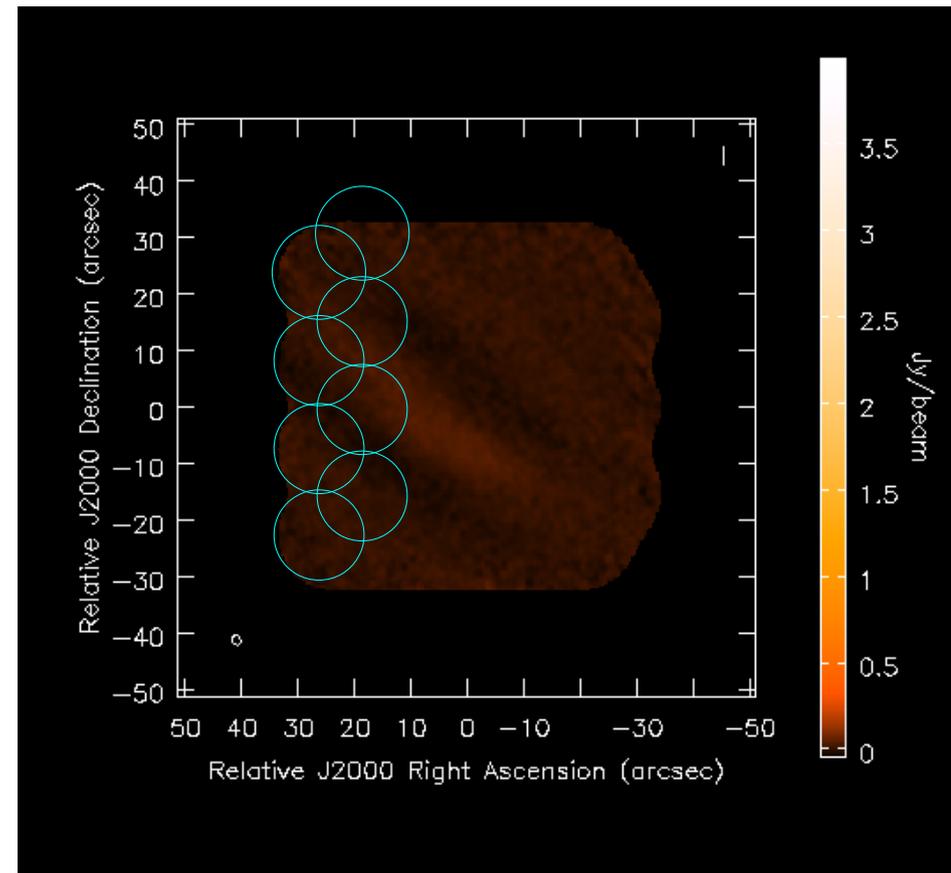
Structure scales

- JCMT source at 11 kpc
 - Peak 100 Jy/ 7".5 pixel
 - 354 GHz = λ 0.85 mm
- **ALMA field of view**
 - $1.2 \times \lambda / 12 \approx 18''$
 - 12-m dish primary beam
- ALMA synthesized beam
 - $\lambda /$ longest baseline
 - Compact array: 1"
 - Intermediate: 0".45
- Largest spatial scale \odot
 - $\lambda /$ shortest baseline
 - Compact array $\lambda/14 \approx 7.6''$
 - Intermediate $\lambda/21 \approx 5.2''$



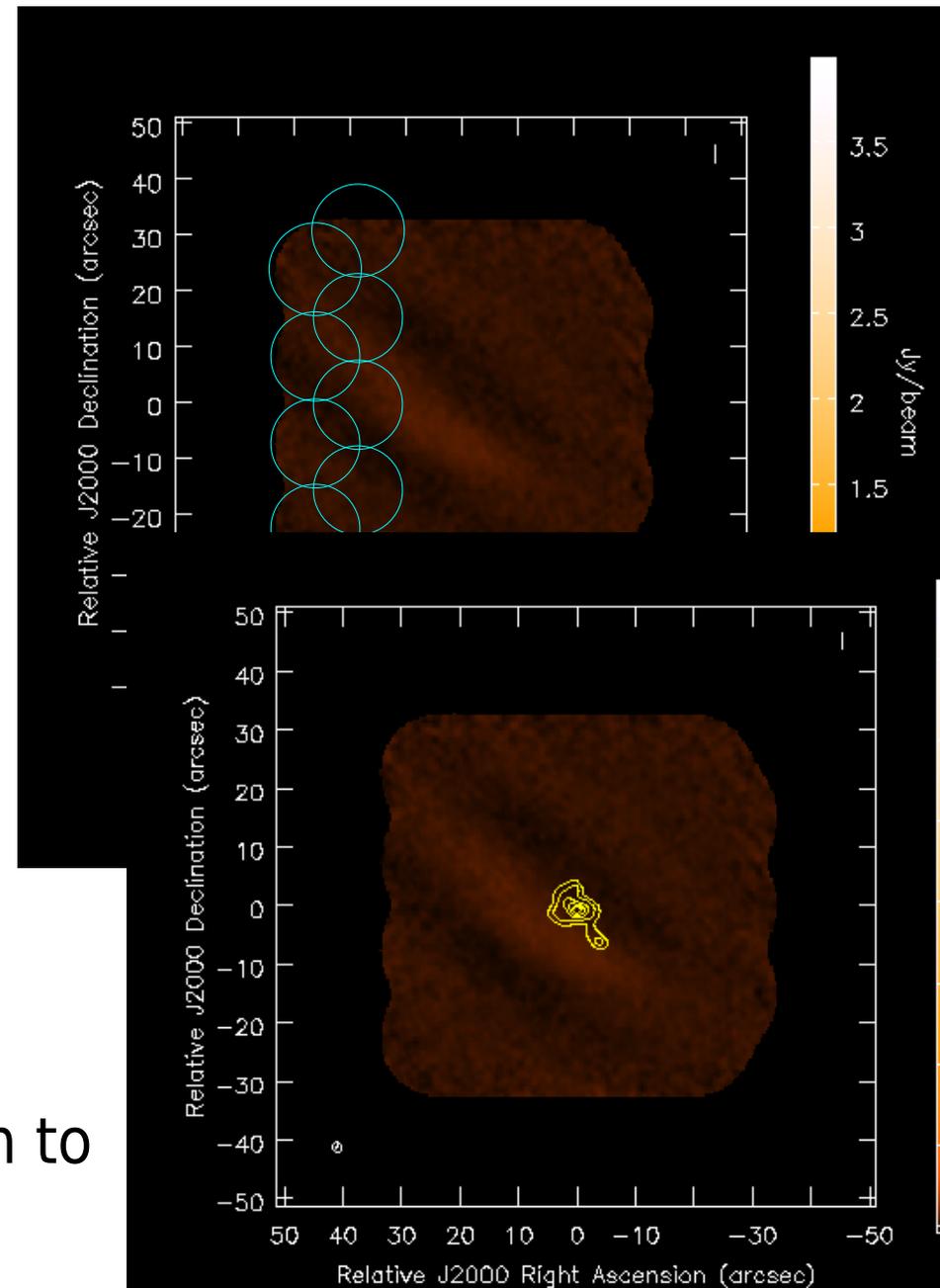
ALMA observations at 11 kpc

- Source original size 150"
 - ALMA **mosaic**
- Peak S_{JCMT} 100 Jy/pixel
- ALMA compact config
 - Synthesised beam θ_{bc} 1"
 - Expect peak $100 (1/7.5)^2 = 1.8$ Jy/beam?
 - Largest angular scale 7.6"
 - ~Input pixel!
- Flux which is *smooth* on JCMT scales is ~invisible!
 - Standard ALMA simulation fails



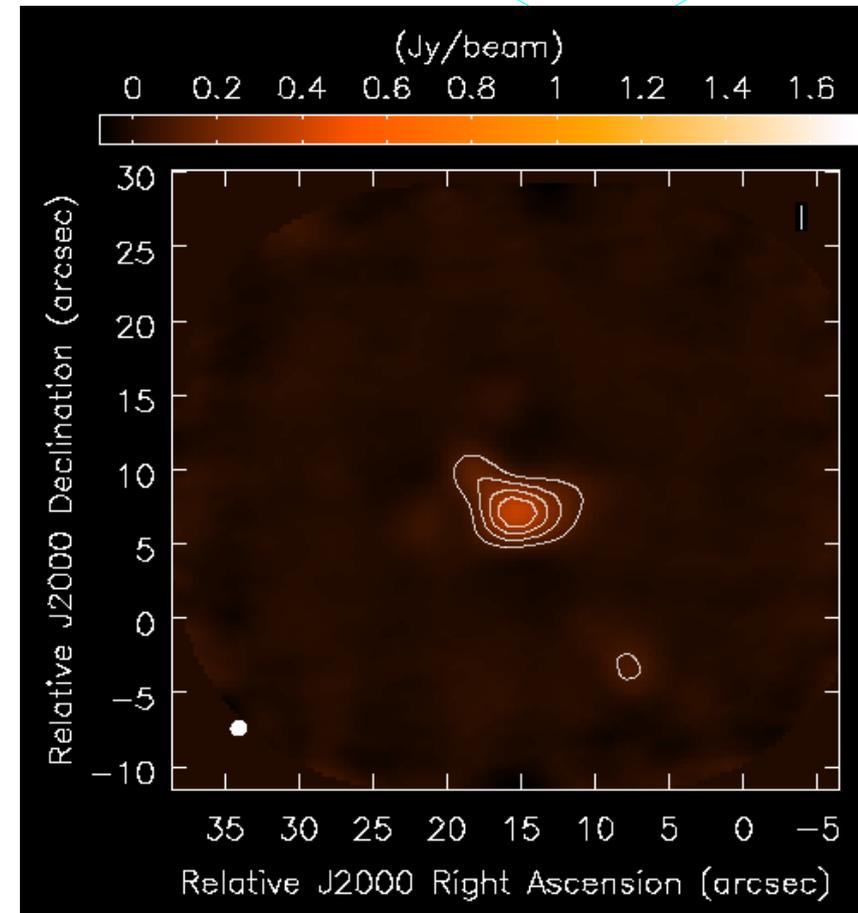
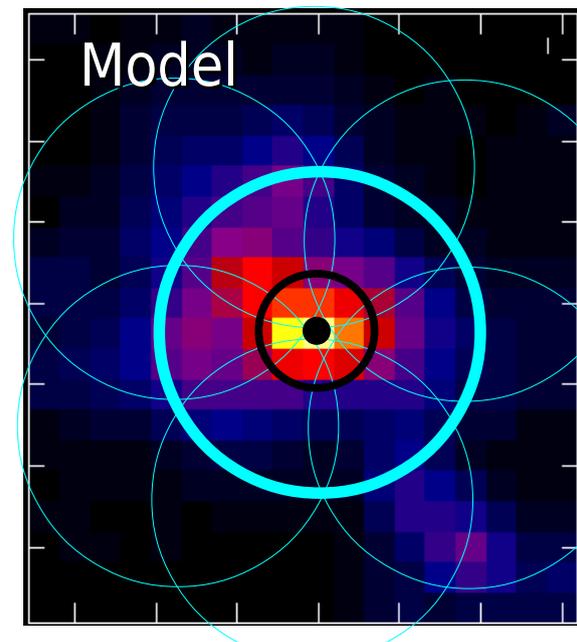
ALMA observations at 11 kpc

- Source original size 150"
 - ALMA **mosaic**
- Source original peak 100 Jy
ALMA compact config
 - Synthesised beam $\theta_{bc} 1''$
 - Expect peak $100 (1/7.5)^2 = 1.7$ Jy/beam?
 - Largest angular scale 7.6"
 - ~Input pixel!
- Flux which is *smooth* on JCMT scales is ~invisible!
- **Small-scale details may appear**
 - But only if you have added them to the model!



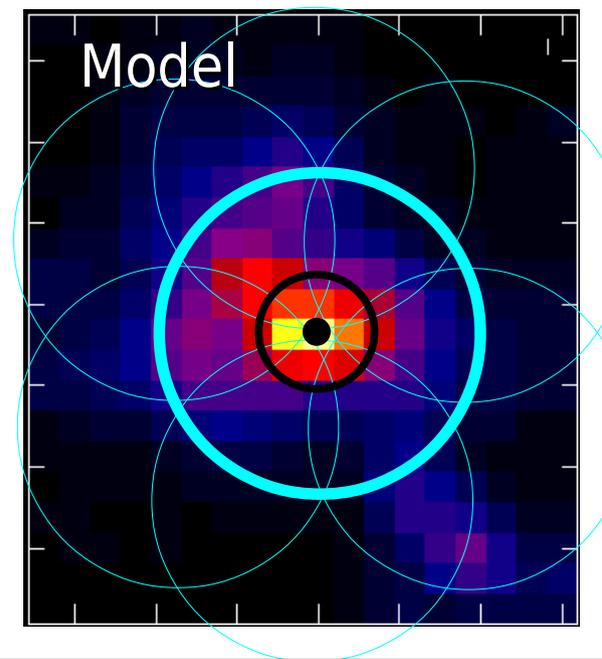
$d=55$ kpc

- JCMT field $30''$, distance $d = 55$ kpc
 - Pixel $p = 7''.5 \times 11/d = 1''.5$
 - $S_{\text{JCMT}} 100 \times (11/d)^2 = 4$ Jy/pix
- ALMA compact $\theta_{\text{bc}} = 1''$
 - 7 mosaic pointings
 - $S_{\text{ALMA}} = S_{\text{JCMT}} \times (\theta_{\text{bc}} / p)^2 \sim 1.8$ Jy/bm?
 - Actual peak ~ 0.4 Jy/beam
 - Large scale flux still missing



$d=55$ kpc

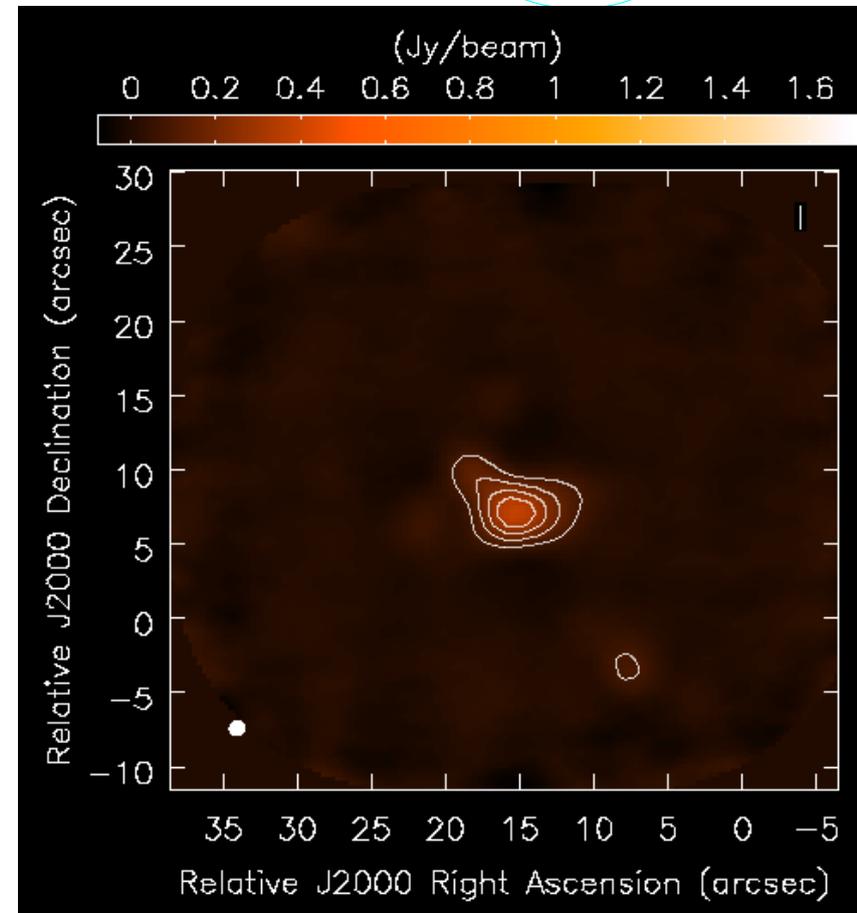
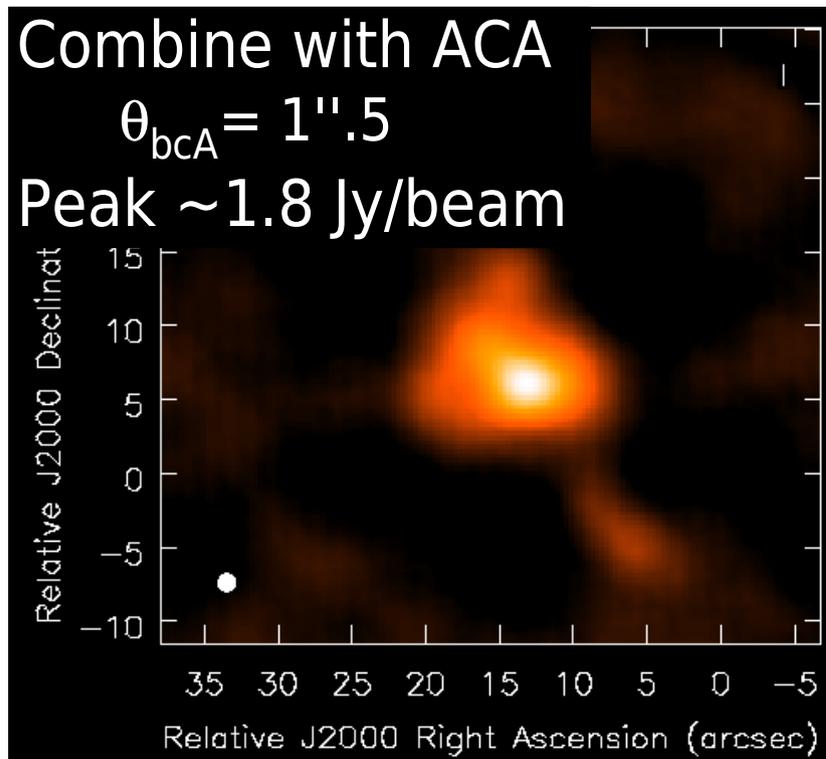
- JCMT field $30''$, distance $d = 55$ kpc
 - Pixel $p = 7''.5 \times 11/d = 1''.5$
 - $S_{\text{JCMT}} 100 \times (11/d)^2 = 4$ Jy/pix
- ALMA compact $\theta_{\text{bc}} = 1''$
 - 7 mosaic pointings
 - $S_{\text{ALMA}} = S_{\text{JCMT}} \times (\theta_{\text{bc}} / p)^2 \sim 1.8$ Jy/bm?



– Combine with ACA

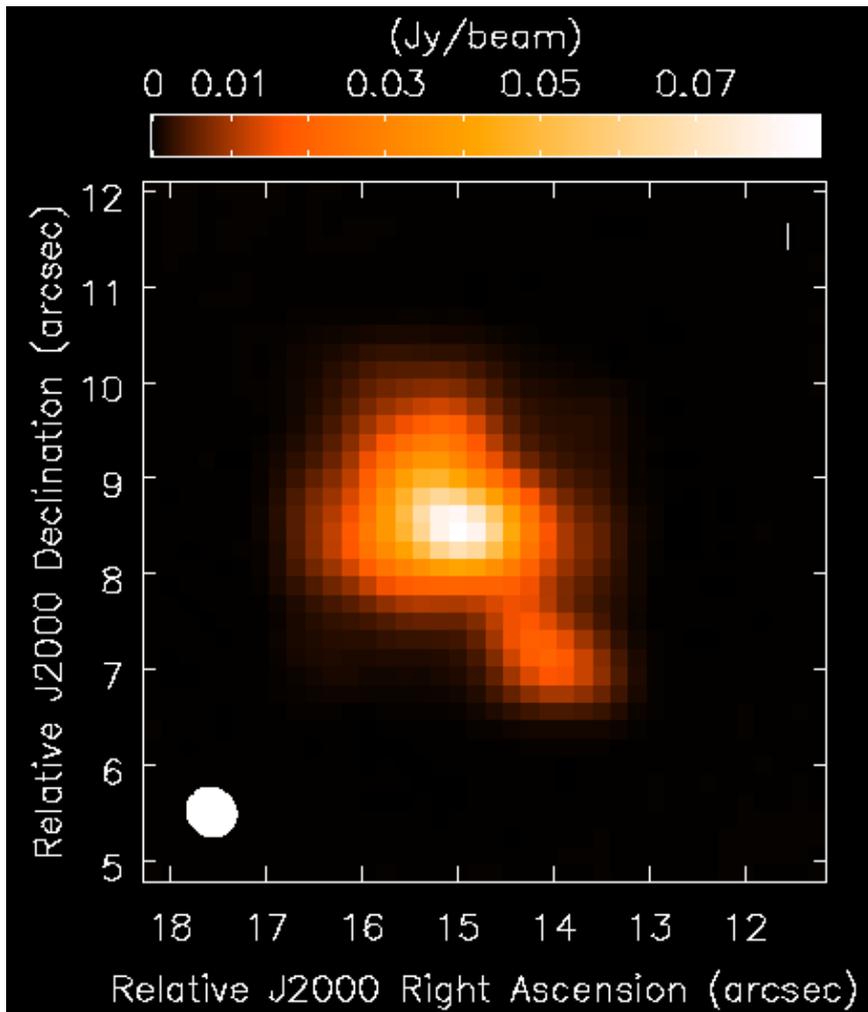
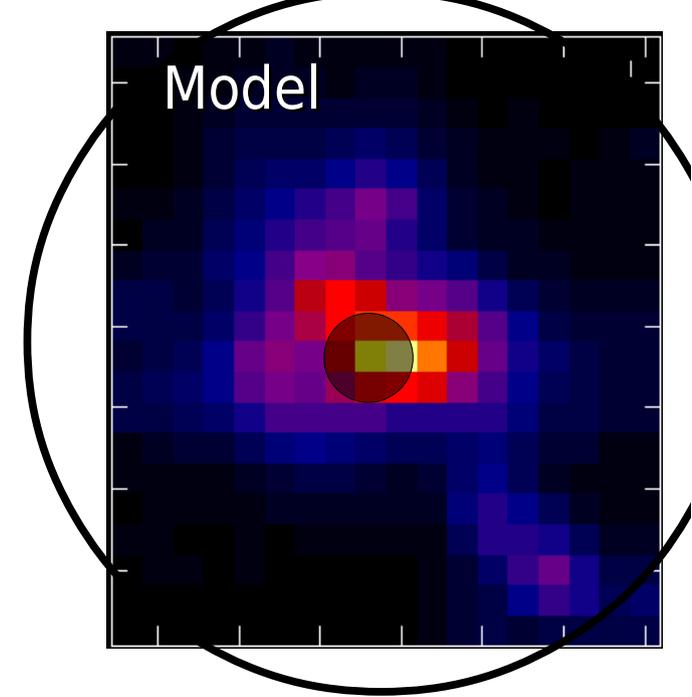
$$\theta_{\text{bcA}} = 1''.5$$

– Peak ~ 1.8 Jy/beam



$d=440$ kpc

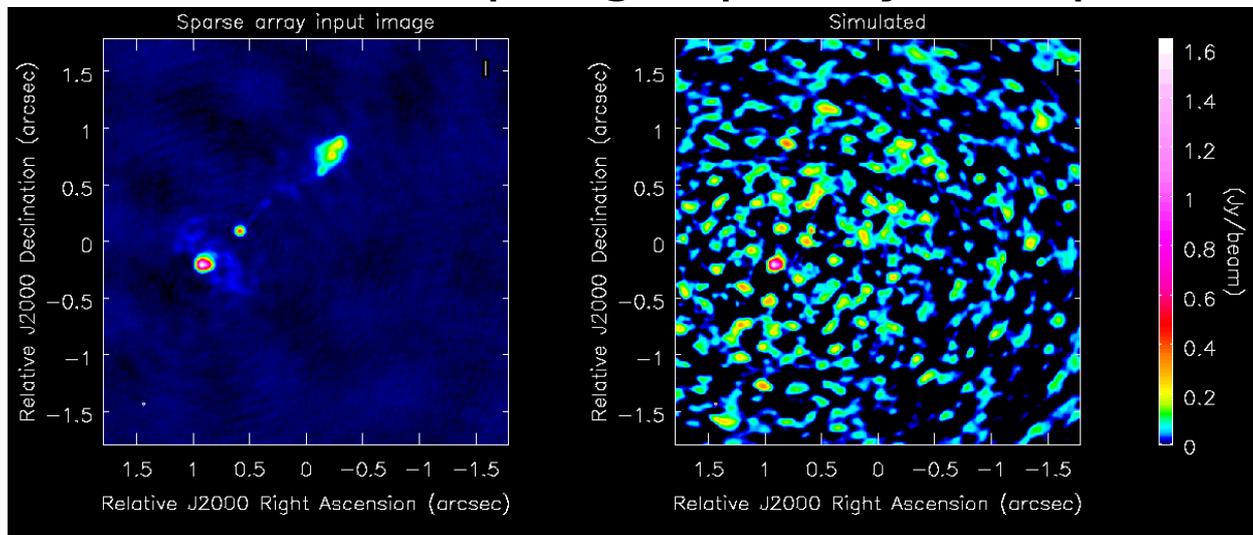
- JCMT field $30''$, distance $d = 440$ kpc
 - Pixel $p = 7''.5 \times 11/d = 0''.1875$
 - $Stot_{\text{JCMT}} \sim 2.2$ Jy



- ALMA intermediate $\theta_{\text{bi}} = 0.45''$
 - Total model \sim largest angular size $5''.2$
 - Well within field of view
- ALMA recovers all 2.2 Jy
- e.g. use Galactic single dish YSO model, for SFR in nearby galaxy seen with ALMA

Noise

- Input is noiseless model?
 - Select PWV appropriate for observing band
- Input has smooth noise σ_{in} ?
 - e.g. well-calibrated single-dish/optical etc. image
 - Estimate likely ALMA noise σ_A (sensitivity calculator)
 - Reduce added noise so that $\sigma_{\text{added}}^2 + \sigma_{\text{in}}^2 \sim \sigma_A^2$
- Input is interferometry image?
 - Beware re-sampling a poorly-sampled image!



In conclusion...

- Decide what you want to observe – science goal!
 - What frequency (and channel width, for lines)?
 - What angular resolution?
 - Largest smooth angular scale within source
 - OT will advise if you need to combine arrays
 - Field of view – will you need a mosaic?
 - What flux density per ALMA synthesised beam?
 - Detection experiments $\geq 5\sigma_{\text{rms}}$ noise
 - Sensitivity calculator/OT – roughly reasonable time?
- Find an input FITS model
 - Image at another wavelength, theoretical model...
 - Rescale size, brightness as required
 - Details on similar scales as you hope ALMA will see
 - Read the OST Help and simulate!

What ALMA data do you get?

Always:

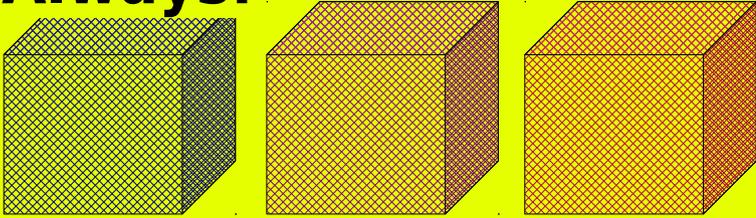


Image cubes for principal science target channels



Information and processing summary

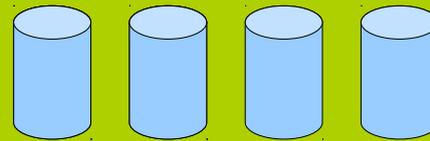


Data processing scripts

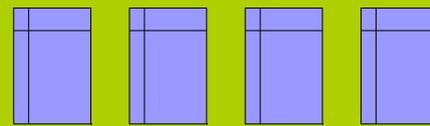
Science products + info always delivered to PI

+ Visibility data sufficient to re-do processing in CASA subject to what was available when observations were taken.

All ASDM & FITS images available from Archive



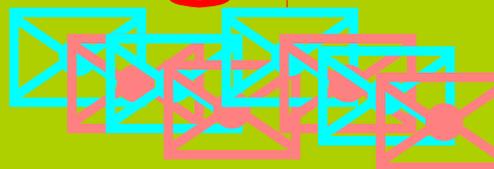
+ any or all of:
ASDM (one per EB)



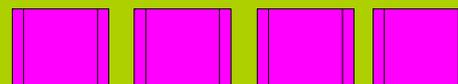
Part-calibrated MS



Flag tables



Calibration tables

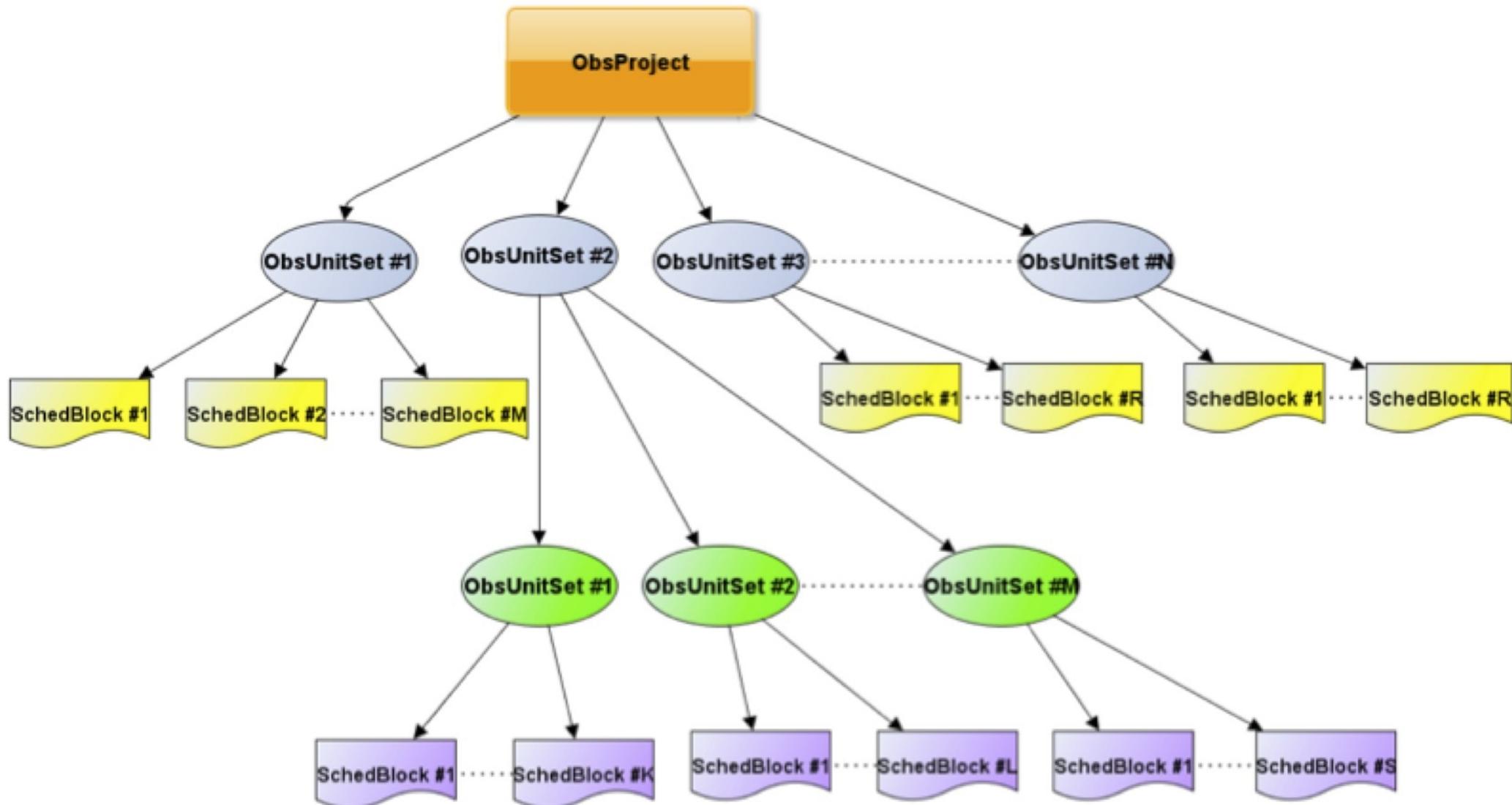


Calibrated MS

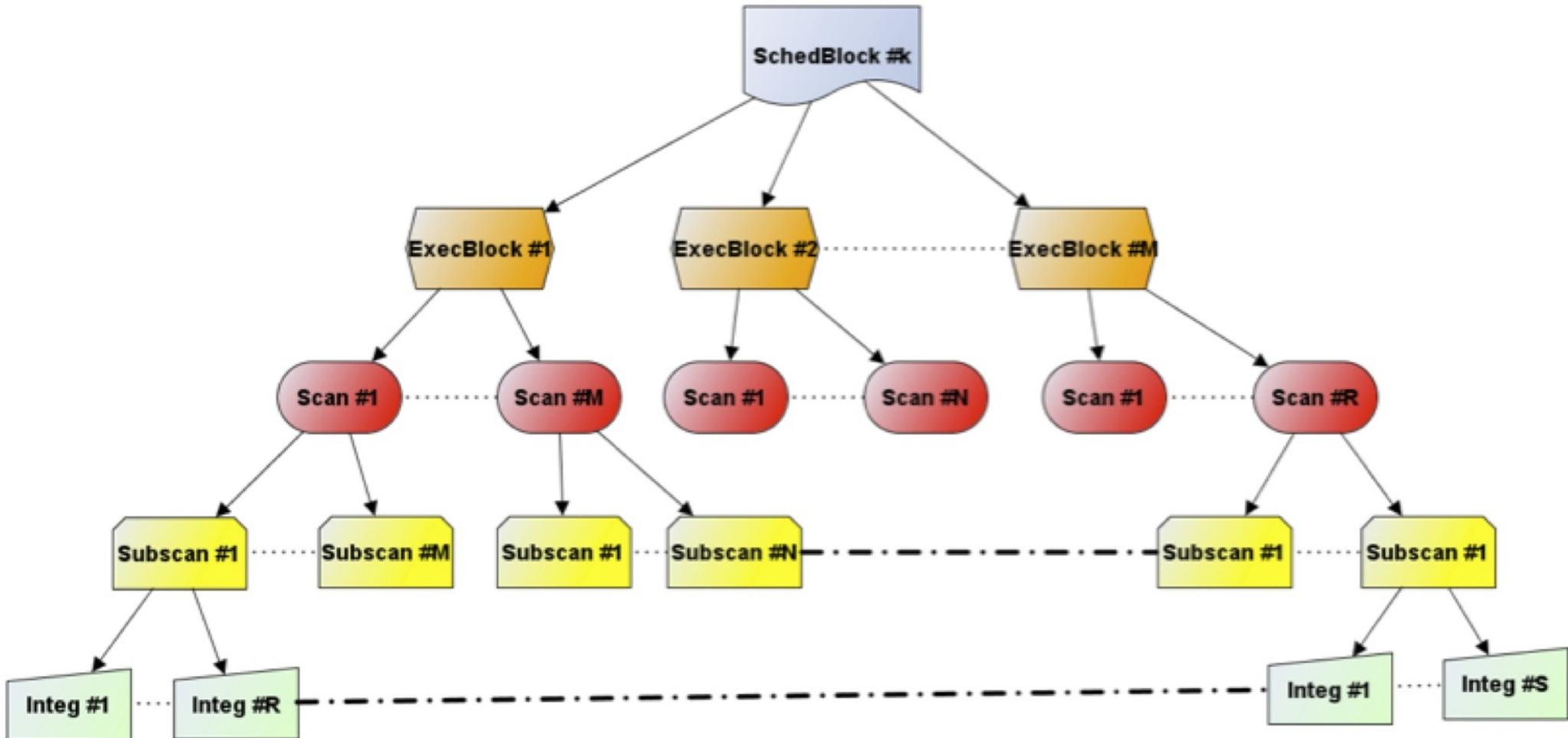
ALMA data conventions

- Scheduling Block: self-contained observation series
 - Short pointing, flux scale, bandpass, (pol.) cal scans
 - ~20-30 mins alternating between target(s)/ph ref(s)
 - Including multiple mosaic pointings
 - Repeat Execution until desired sensitivity is reached
 - All in same spectral and array configuration
 - Each EB produces one ASDM (ALMA Science Data Model) with binary data and lots of metadata
- Initial data processing (calibration, editing) per-EB
 - Convert ASDM to Measurement Set
- Combine EBs for final target imaging
- May also combine different SBs e.g. ACA+main

Data organisation for a project

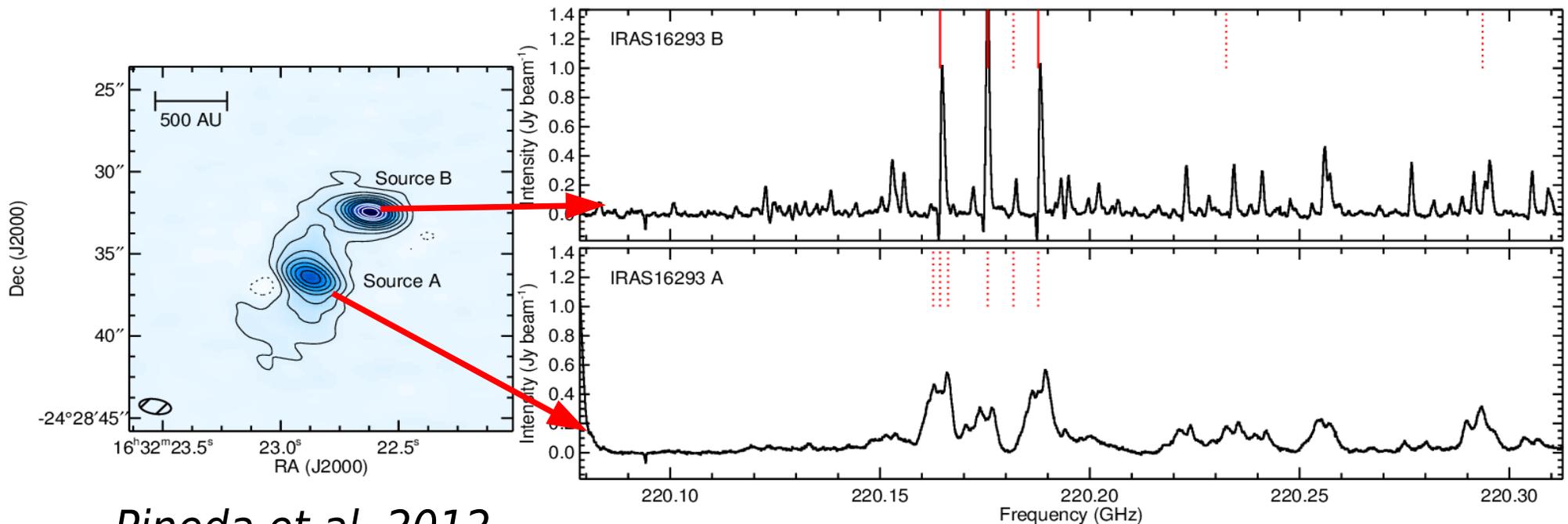


Individual scheduling block



Data reduction summary

- Initial steps common to most data sets
 - Standard procedures usually reliable
- Likely to want to self-calibrate
 - Re-make images at different resolutions etc.



Pineda et al. 2012