### Calibration of interferometric data VINCI overview

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# From coherence factors to object visibilities

- Calibrator 1:  $\mu^2_{cal1} = V_1^2 = \mu^2_{cal1} / V_{cal1}^2$
- Science target:  $\mu^2_* \implies V^2_* = \mu^2_* / T^2$
- Calibrator 2:  $\mu^2_{cal2} \implies T^2_2 = \mu^2_{cal2} / V^2_{cal2}$

 $=>\sigma({\rm V}^{2}_{*})/{\rm V}^{2}_{*}=\sigma\,(\mu^{2}_{*})/\mu^{2}_{*}+\sigma({\rm T}^{2})/{\rm T}^{2}$ 

Total error on V<sup>2</sup><sub>\*</sub> thus includes: - System errors on V<sup>2</sup><sub>cal</sub> - Transfer function errors on T<sup>2</sup>

- Statistical errors on  $\mu^2$  (detector noise, shot noise, seeing noise)

A good calibrator is...

A source for which V<sup>2</sup> can be predicted (at the baseline considered) with good accuracy and little bias

- Well modelled
  - Point source (O free parameter)
  - Uniform disk (1 free parameter)
  - Limb darkened disk (2 or more free parameters)
- Well known
- Stable in time
- Observable with the same setup  $(\Delta m, \lambda_{eff}...)$
- At a reasonable angular distance from the science target
- With a sufficient correlated flux (V<sup>2</sup>.  $N_{phot}$ )

#### Example: uniform disk calibrator

- Pick up a single star, non variable
- Derive diameter from surface brightness (via  $T_{eff}$  and  $F_{bol}$ )
- Convert LD diameter to UD diameter
- Compute visibility from UD diameter (Airy function)

Expected accuracy on  $\phi_{UD}$  (not V!) :

- 5% in common cases
- 1% for photometric standards (*cf. Cohen & al., A&A 117*)



# Calibrators choice strategies

- Selection of stars from a fixed set of rules on an « open » catalog (interferometric observations preparation tools)
  - PTI / GetCal (http://msc.caltech.edu/software/getCal/index.html)
  - JMMC / ASPRO (http://mariotti.ujf-grenoble.fr/~aspro/)
- Catalog of interferometric calibrators
  - Photometry-derived diameter on chosen sources (Bordé et al. 2003, A&A 393)
  - Catalog of interferometric measurements (Richichi & Percheron 2002, A&A 386)

#### Good calibrators may be hard to find!

### Estimating the transfer function



Constant T<sup>2</sup> (VLTI/VINCI, E0-G0, 2002-05-29)

The model used for describing the transfer function depends on:

- Sampling intervals
- Characteristic time evolution
- Amplitude of fluctuations



Linear interpolation (FLUOR/IOTA, 2000-02-27)



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### Transfer function and turbulence

$$T^2 = T^2_{instrument} \cdot T^2_{atmosphere}$$

- Atmospheric term caused by wavefront corrugation at each pupil
- Solutions:
  - Clean up the wavefront with adaptive optics
    - MACAO for UTs
  - Trade turbulent image for steady beam with intensity fluctuations in single-mode waveguides
    - Spatial filtering unit implemented in VINCI, AMBER, MIDI+

#### VINCI: concept

- Two inputs:
  - Beam A and Beam B
- Single-mode fibers for:
  - « cleaning » of turbulent beams
  - Polarization control
  - beam combination (X-coupler)
- Coaxial beam combination
- Temporal OPD modulation
  - $OPD = v_{scan} \cdot t$ With 200 <  $v_{scan}$  < 2000 $\mu$ m/s
- Four outputs:
  - I<sub>1</sub>, I<sub>2</sub>, P<sub>A</sub> and P<sub>B</sub>
- Piston *not* filtered



# VINCI: implementation





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between the two beams

 $(I - P_A - P_B) / 2(P_A P_B)^{0.5}$ 

## Data sample (joint space/wavenumber domain)

- Energy redistributed in space/wavenumber domain by wavelet transform
- Coherence factor (µ<sup>2</sup>) proportional to volume under fringe peak
- $\mu^2$  measurement affected by
  - Detection noise
  - Piston noise (non-regular fringe motion)







#### Weak piston



#### Strong piston

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# Performance on $\mu^2$ measurements

 $e(\mu^2)/\mu^2$  normalized for 100 scans (survey of 296 observations) VINCI with 35cm siderostats



- Statistical error depends on correlated flux
- Detector noise dominating for faint sources
- Atmospheric piston limiting for strong sources
  - => Good fringe tracking is critical (FINITO, PRIMA FSU)

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