VLTI Tutorial

The VLTI conceptual design

VLTI Concept...The birth

From a 16m telescope (1980)



...nice dream, but no interferometry ...



...to a linear array of four 8m telescopes... (1988)

...to a mature VLT Interferometer layout (1990)



SECOND WORKSHOP ON

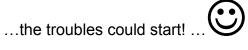
ESO's Very Large Telescope

Winton, 29 September – 2 October 1986

PROCEEDINGS

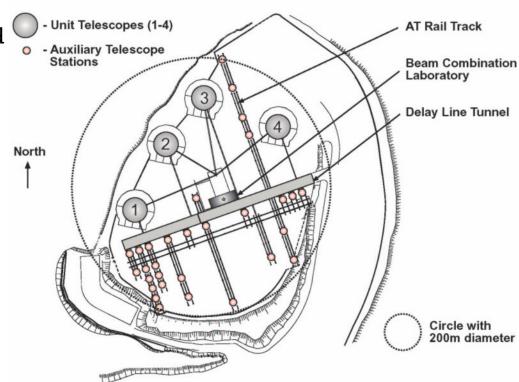
Edited by S. D'Odorros and J.-P. Swirgs

...the baby was born! ...



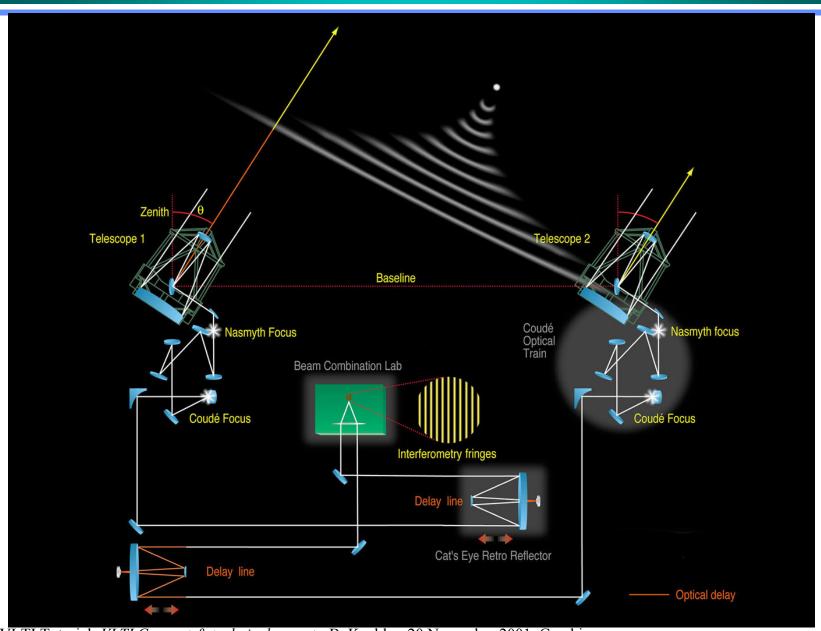
The Final VLTI Array Layout

- 4 UT's as 'trapezoidal' as possible (wind shadow, ground quality)
 - Baselines 47 130m $\Rightarrow 1.5$ milli arcsec
- 30 Stations for AT's
 - Baselines 8 200m⇒ 1 milli arcsec
- Delay Line Tunnel (160 x 8m) positioned to minimize path differences. Can house 8 DL's



- Central combining Lab (20 x 7m) with specific VLTI building / control room
- All elements are located on an 8m grid
- Light travelling underground for high thermal stability (vacuum alternative not selected for cost reasons)

The VLTI Optical Layout



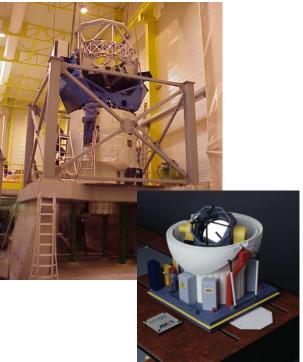
The telescope family

- The 'Appetizers' (2 Siderostats)
 - ♦ Installed early 2001
 - Relocatable in day(s)
 - Primary: 0.4 m
 - Autoguiding only
 - Airy disk (in K): 1.1"

- The 'Workhorses' (3 Auxiliary Tel.)
 - Relocatable in 3h
 - ♦ Primary: 1.8m
 - ♦ Fast Tip-Tilt
 - Limited Chopping
 - ◆ Airy (in K): 0.25"

- The 'Kings' (4 Unit Tel.)
 - Fixed position!
 - ♦ Primary: 8 m
 - Adaptive Optics
 - Airy disk (in K): 0.06"

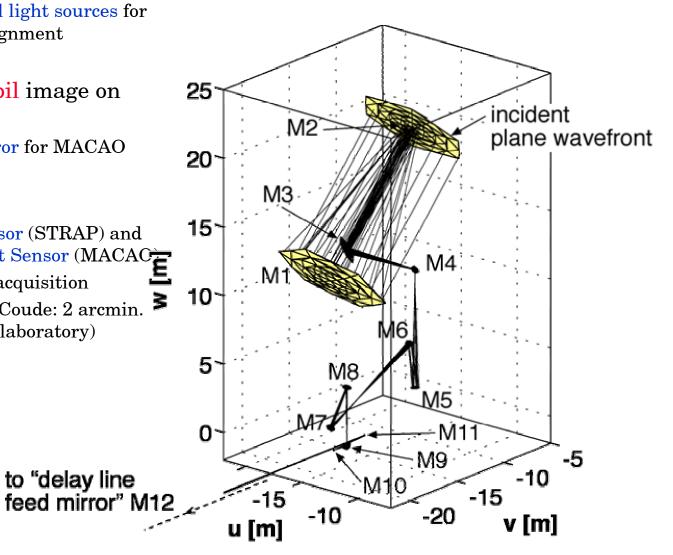




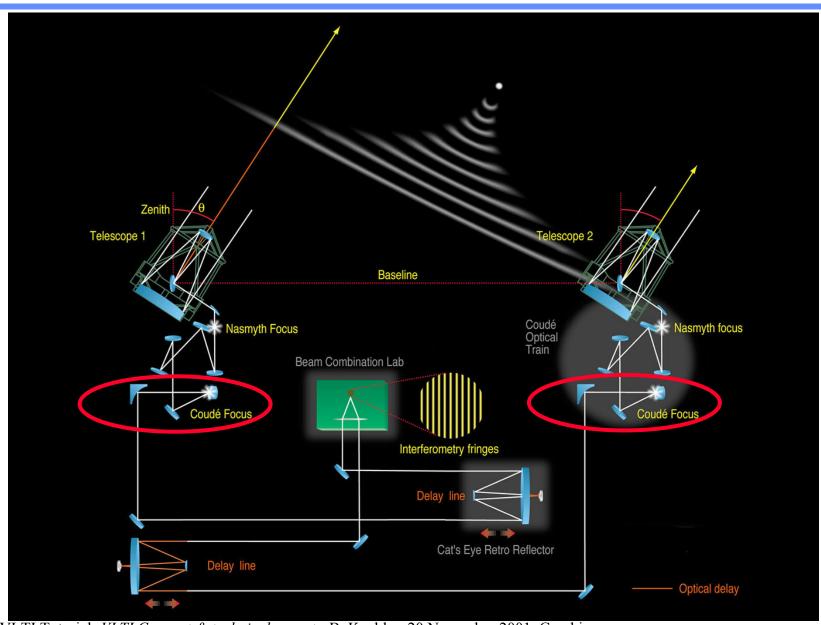


Telescope Optical Design

- Intermediate Focus below M4:
 - Various artificial light sources for calibration & alignment
- Intermediate pupil image on M8:
 - Deformable mirror for MACAO
- Coude Focus:
 - ◆ Fast Tip-tilt sensor (STRAP) and later Wave Front Sensor (MACAC
 - TCCD for Field acquisition
 - Field of View at Coude: 2 arcmin. (FoV 2 arcsec in laboratory)



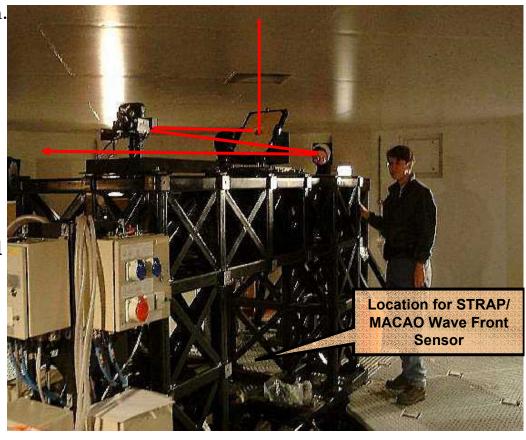
Relay Optics



Relay Optics

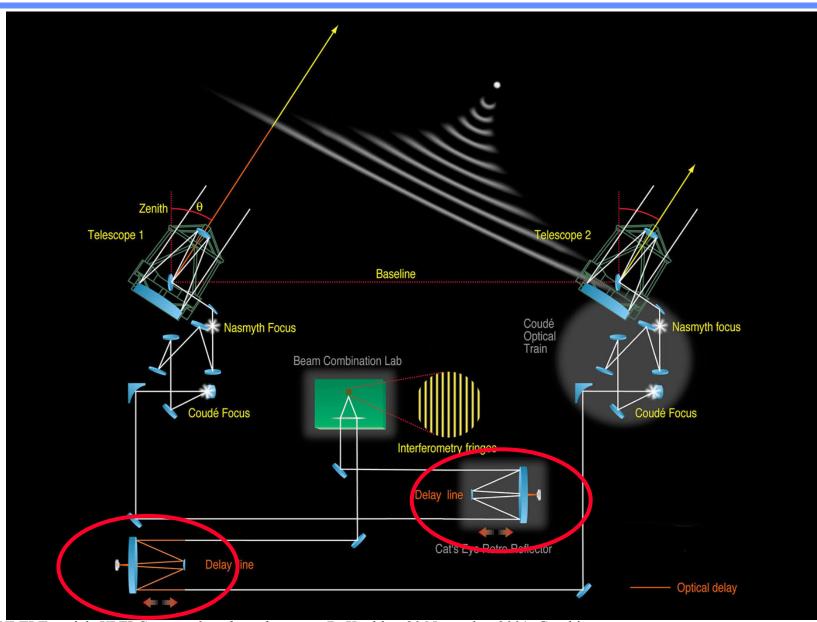
• 'Grasping' the UT-photons

- M9: large dichroic.
 - » Reflects IR to VLTI
 - » transmits Visible to STRAP and later MACAO Curvature sensor.
 - » Optimized for polarization.
- ♦ M10: convex spherical.
 - Re-image telescope pupil(M2) in Tunnel center.
 - » Articulated mount to adjust lateral pupil position in Lab.
- ♦ M11: off-axis parabola.
 - Collimates beam and send it into light duct towards M12 in DL Tunnel



The Relay Optics (M9, M10, M11) inside UT Coude room)

The Delay Lines



The Delay Lines

• The 'Paranal-Express'

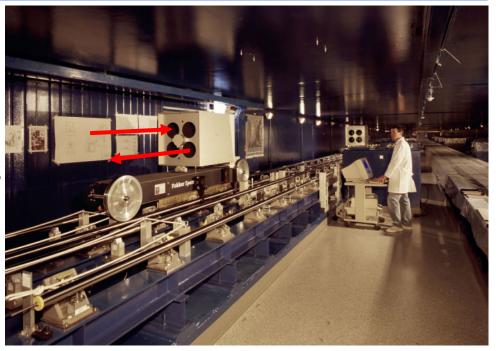
• Stroke: 60 m (120m in OPL)

♦ Resolution: <5nm

♦ Max. velocity: 0.5 m/s

♦ Stability (jitter): <14nm rms

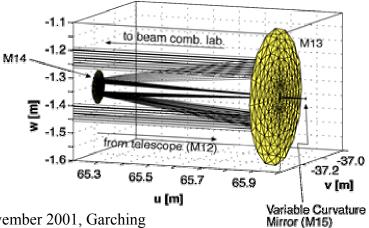
Power dissipation: <15W



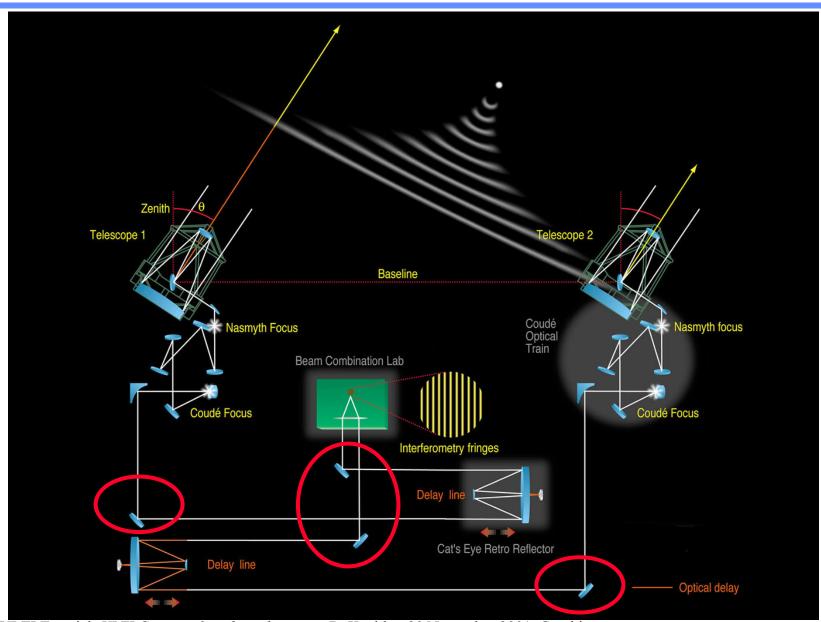
Variable Curvature Mirror (VCM)

- re-image pupil inside the Laboratory
- mounted on piezo translator for fast OPD correction

The first two Delay Lines (#I & II) inside the tunnel



Transfer Optics



Transfer Optics

- The beam bending 'gadgets'
 - ♦ Very high optical quality flats (λ/60 surf.)
 - ◆ Coating optimized for transmission and polarization (45° incidence)
 - Very stiff mounts and tables for immunity to μ-seismic noise
 - ◆ M12 eventually on robotic arm for automatic array reconfiguration
 - ◆ M16 on translation stages for beam switching inside lab.
 - Support future dual-feed (PRIMA)

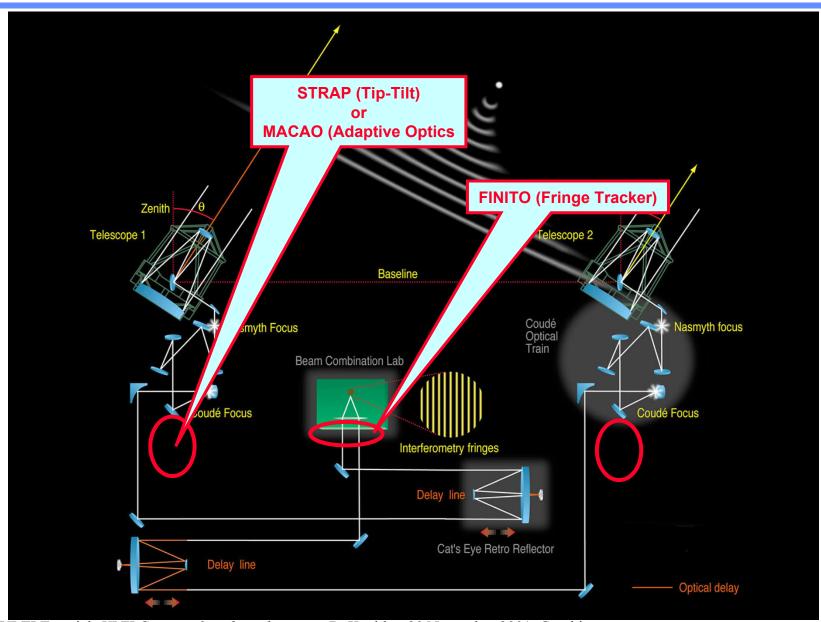


The M12 flat folding mirror



The M16 flat folding mirror

Beam Make-up



STRAP (Tip-Tilt)

Quad-cell detector with APD at telescope Coude focus

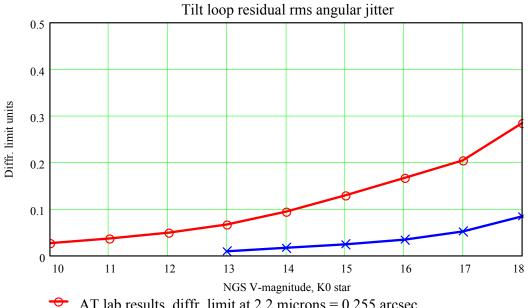
• Pure tip-tilt correction is optimal when $D/r_0<4$, i.e. $UT/10\mu m$ (MIDI)

or AT/2 μm (VINCI,AMBER, MIDI)

Gain on Strehl up to 5.

Will be used on UT till MACAO is available

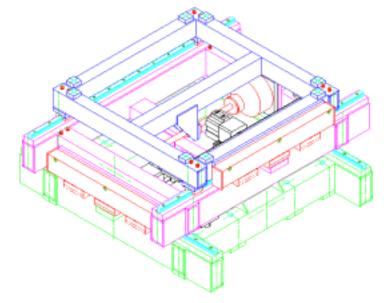
Will be resident on AT

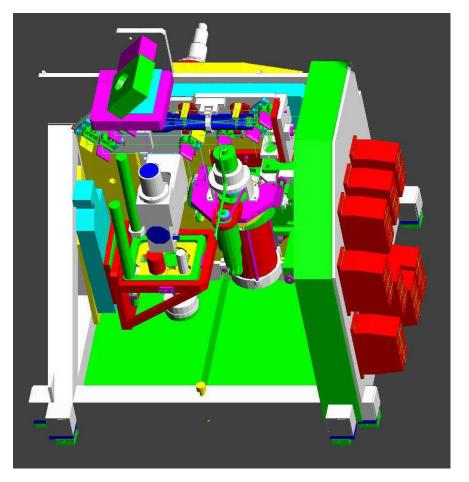


AT lab results, diffr. limit at 2.2 microns = 0.255 arcsec
UT lab results, diffr. limit at 10 microns=0.26 arcsec

MACAO (Adaptive Optics)

- A must for UT in K-band (AMBER). Gain in coherent flux ≈ 100
- 60 elements Curvature System at telescope Coude
 - WaveFrontSensor using APD coupled with optical fibers
 - Bimorph Deformable Mirror on Tip-Tilt mount
 - vibrating membrane,
 - radial geometry micro-lenses,
- X-Y Table allows reference source different from target

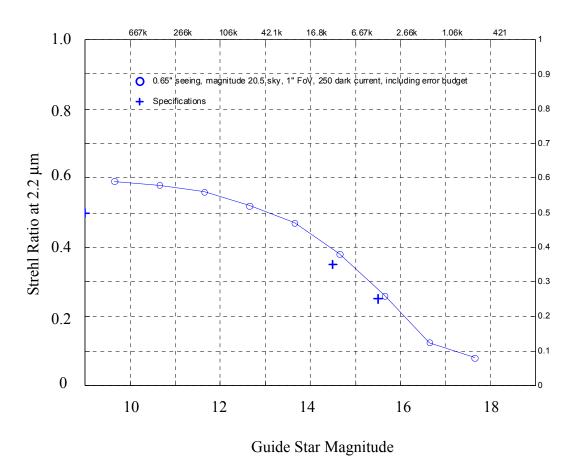




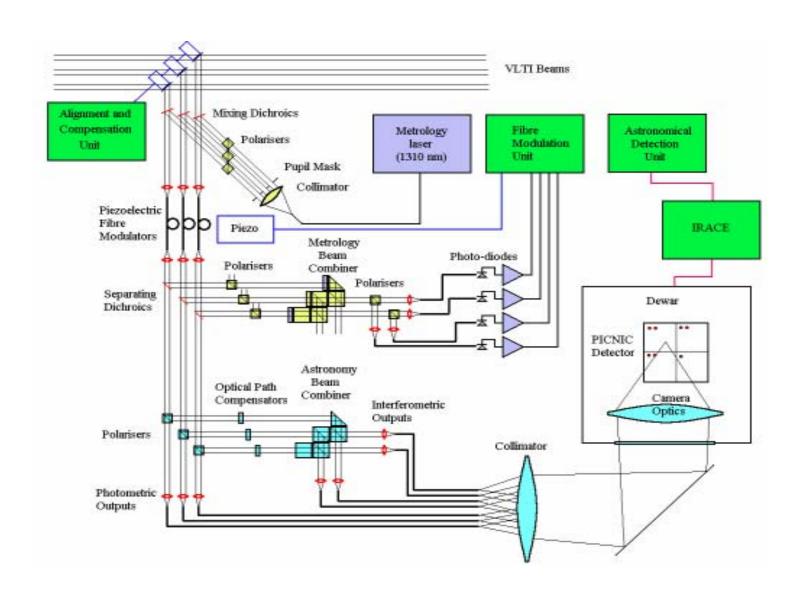
MACAO performance

Count/subaperture/second

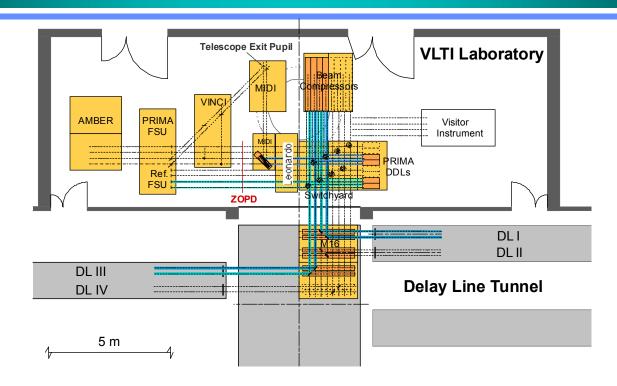
0.65" @ 500 nm, $\tau_o{\sim}4ms,$ V=20.5 sky background



FINITO (Fringe Tracker)



The VLTI Laboratory



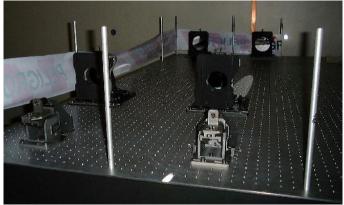
- High thermal stability; limited access, low power dissipation
- Telescope Exit Pupil re-imaged into instruments
- Optical design for up to 8 beams (4 UTs with dual feed)

Inside the Laboratory

- The Beam Switchyard
- The Beam Compressors
 - ◆ 3-mirror design (compress 80 → 18 mm)
 - High optical quality off-axis parabolas (surface error 7 rms)
- LEONARDO Reference sources
 - Laser and white-light sources
 - Light can be sent to any instrument or backwards to telescope
 - Provide reference axis for each beam and reference OPD between beams
 - Enable instrument to obtain fringes in 'autotest'
- VINCI Test Instrument
 - Used for VLTI commissioning & later as reference for performance tracking.
- Fringe Tracker FINITO
 - ◆ Co-phases (3 beams) to allow long exposures
 - ♦ mH<12 (UT)
 </p>

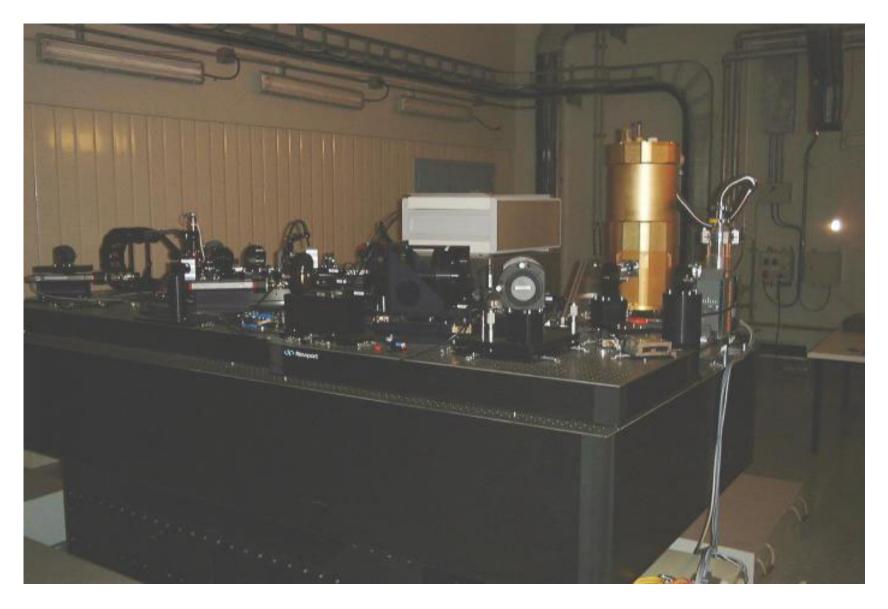


The Switchyard & Leonardo reference source



The Beam Compressors (3 mirrors each)

VINCI

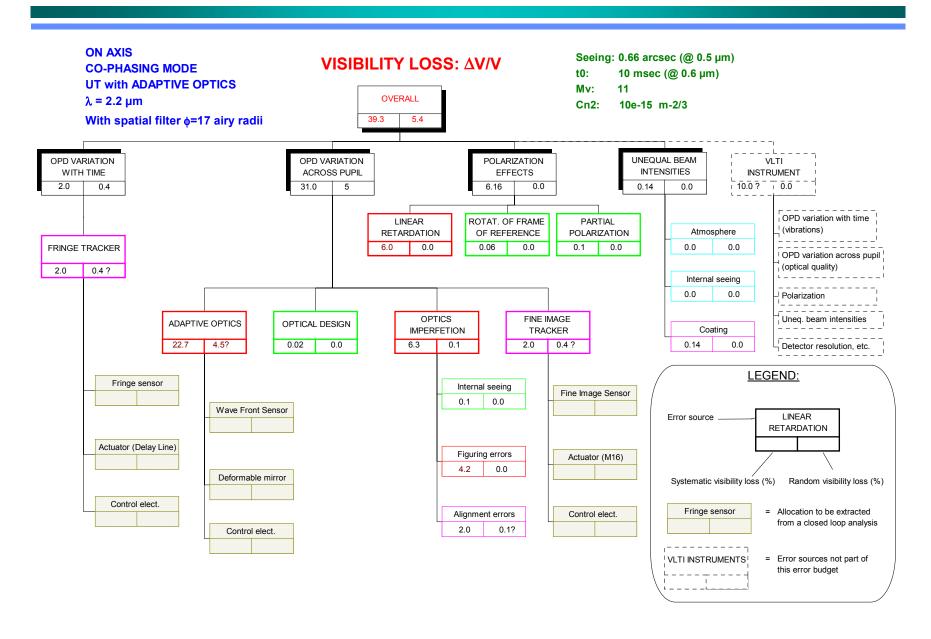


VLTI Tutorial: VLTI Concept & technical aspects, B. Koehler, 20 November 2001, Garching

VLTI Tutorial

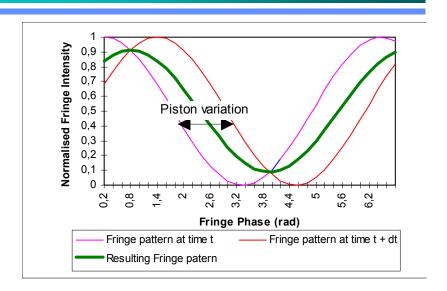
The VLTI selected critical technical aspects

VLTI Error Budget



OPD variation with time (Piston errors)

- Error sources:
 - Atmosphere
 - ◆ Internal seeing
 - Vibration (wind, natural & man-made seismics, acoustics, pumps, etc.)
- Compensated (Partially) by fringe tracking.



Top Level requirement:

Instrumental errors (internal seeing & vibrations) < atmosphere

Wavelength	0.6 µm	2.2 µm
Exposure time	10 msec	48 msec
OPL requirement (each arm) in [nm]	21	75
Telescope (UT or AT, each)	14	50
Delay Line (each)	14	50
Beam Combiner	6	21
Transfer Optics	3	10
Internal Seeing	3	10

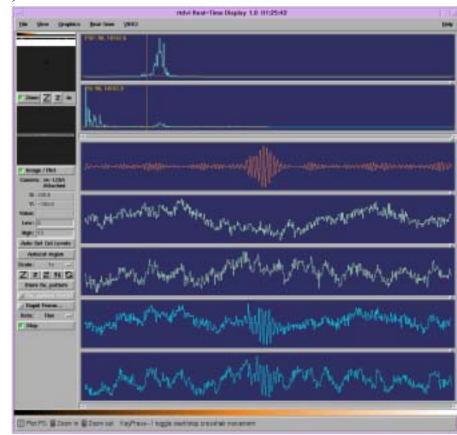
Unequal beam intensity

• Visibility loss due to intensity mismatch:

$$\frac{\Delta V}{V} = 1 - 2. \frac{\sqrt{I_1 \cdot \sqrt{I_2}}}{I_1 + I_2}$$

- Error sources:
 - Atmospheric scintillation (negligible)
 - Coatings (small)
 - For fiber-fed instrument (large):
 - » Tip-tilt errors
 - » Instantaneous Strehl fluctuation

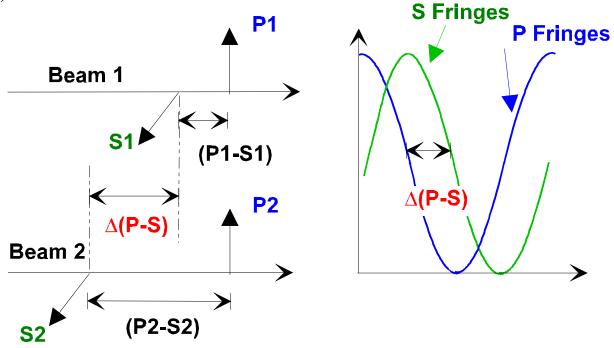
VINCI measure I1 & I2
(photometry channels) to
correct for this effect.



Polarization Effects

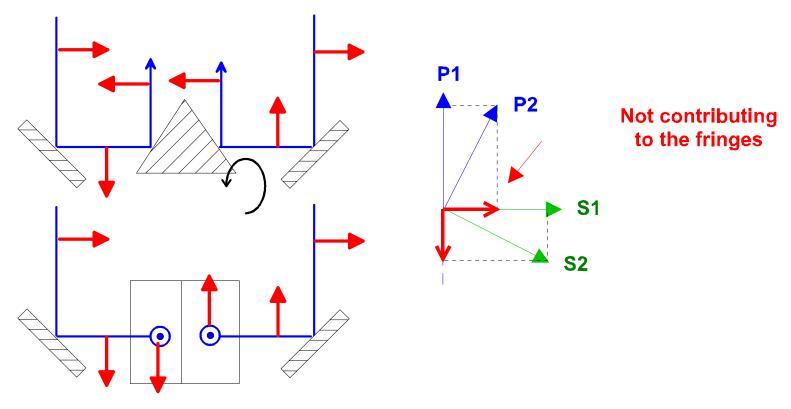
Linear Retardation

- Error sources: Coatings
 - » Different coatings in the two arms
 - » Differential incidence angles (between arms)
 - » Differential coating characteristics (e.g. thickness of the protecting layer)
- ◆ Can be very critical in Near IR/Visible and for multi-dielectric coatings (M9).



Polarization Effects

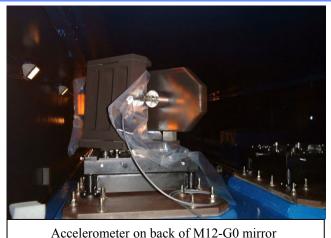
- Rotation of polarization frame
 - Error sources:
 - » Differential frame-of-reference/pupil rotation due to optical design and/or misalignment
 - ◆ Can be avoided by proper optical design and alignment.



VLTI Tutorial

Some results from on-going VLTI commissioning

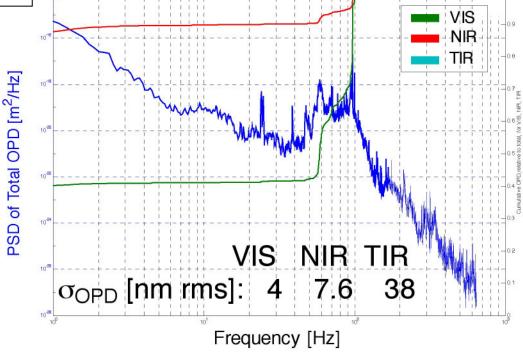
Measured micro-seismic vibration



• OPD as measured with accelerometers at the back of Transfer Optics mirrors (M12, M16, Switchyard, Beam Compressor)

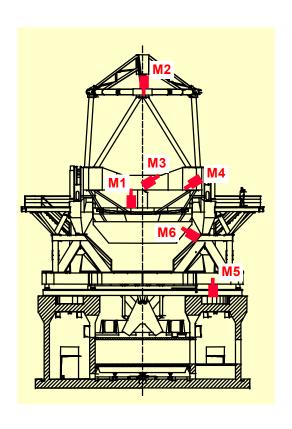
Error budget:

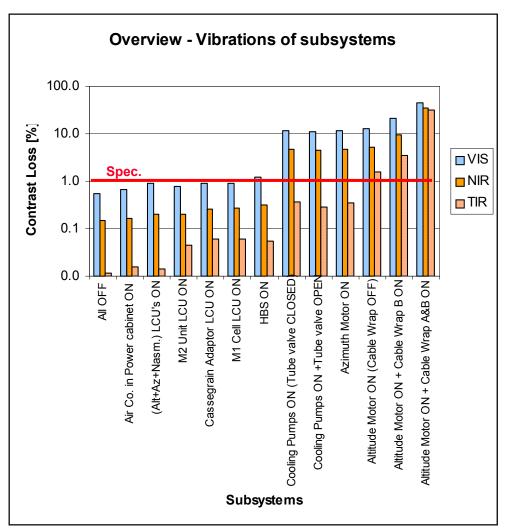
Wavelength	VIS	NIR	TIR
Transfer	3	10	45
Optics			



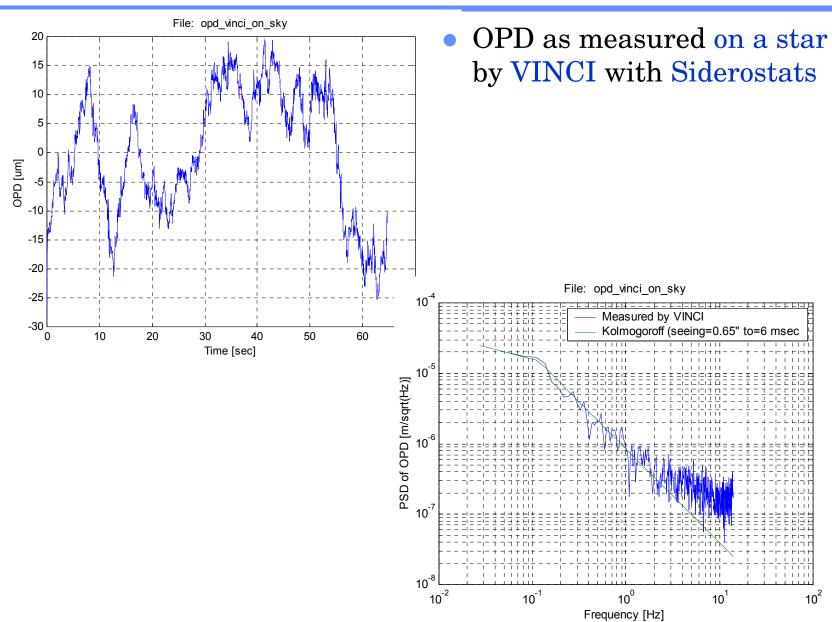
OPD stability inside UT

- Measured with high sensitive accelerometers on UT#1&3
- Few improvements on sub-system identified and on-going
- Overall stability excellent

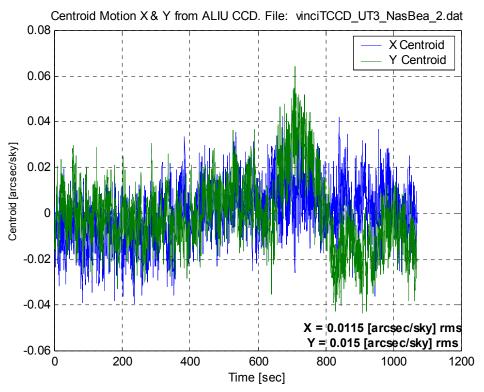




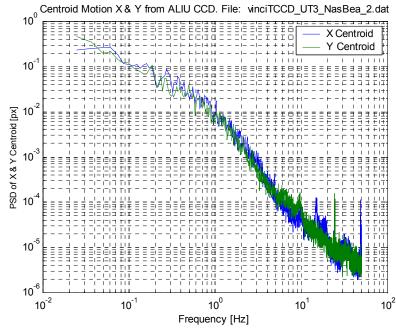
Measured OPD spectrum



Measured Internal seeing (tip-tilt)

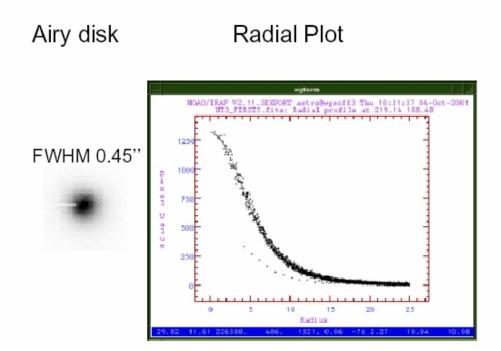


 Nasmyth laser beacon (UT3) imaged on VINCI CCD (after 25 mirrors and 200m distance)



Measured Image Quality

First UT Light in VINCI



(Note: the light reaches VINCI after 25 reflections and 200m travel)

• Image Quality from UT Nasmyth laser beacon to VINCI CCD:

FWHM < 0.040" (limited by pixel size)

Conclusion

- Specific and stringent error contributions need to be taken into account for an Interferometer:
 - ♦ OPD stability (vibrations from equipment, wind buffeting, micro-seismic noise, residual atmospheric piston,...)
 - Polarisation (optical layout, coatings)
 - ◆ Image Quality (mirror figuring, alignment, internal seeing,...)
- The two major technical risks have been:
 - ◆ OPD stability within the UT
 - ◆ The internal seeing
- Both proved to be according (or very close) to the required performance
- Ready for the next step: PRIMA + ...